



FERMILAB
Technical
Division

**Pressure Vessel Engineering Note
For the 1.3-GHz Helium Vessel,
Cavity AES-4**

**Vessel No. IND-138
Rev. No. --
Date: 19 November 2009**

**Pressure Vessel Engineering Note
For the 1.3-GHz Helium Vessel,
Cavity AES-4**

Authors: B. Wands , M. Wong

Date: 19 November 2009

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PRESSURE VESSEL ENGINEERING NOTE

PER CHAPTER 5031

Prepared by: B. Wands, M. Wong

Preparation date: 17 November 2009

1. Description and Identification

Fill in the label information below:

This vessel conforms to Fermilab ES&H Manual
Chapter 5031

Vessel Title 1.3GHz Helium Vessel, Cavity AES4

Vessel Number IND-138

Vessel Drawing Number D00000000872825

Maximum Allowable Working Pressures (MAWP):

Warm Internal Pressure 2.0-bar (29.0-psia)

Cold Internal Pressure 4.0-bar (58.0-psia)

External Pressure 1.0-bar (14.5-psia)

Working Temperature Range -457 °F - 100 °F

Contents Superfluid helium

Designer/Manufacturer FNAL / Hi-Tech, AES,
Sciaky, Fermilab

Test Pressure (if tested at Fermi) Acceptance
Date: _____

(2.3-bar)

19.0 PSIG, Hydraulic _____ Pneumatic X

Accepted as conforming to standard by

Apollonios George

of Division/Section TD Date: 11/18/09

←Document per Chapter 5034
of the Fermilab ES&H Manual

←Actual signature required

NOTE: Any subsequent changes in contents,
pressures, temperatures, valving, etc., which
affect the safety of this vessel shall require
another review.

Reviewed by: [Signature]

Date: 11/17/09

Director's signature (or designee) if the vessel is for manned areas but
doesn't conform to the requirements of the chapter.

S.D. Holmes

Date: 11/19/09

[Signature] for V. Grossman
ES&H Director Concurrence

Date: 11/19/09

Date:

Lab Property Number(s): _____
 Lab Location Code: Tested @ Meson Detector Building (FIMS #408)
 Purpose of Vessel(s): Liquid helium containment for nine-cell 1.3-GHz
Superconducting Radio Frequency (SRF) cavity
 Vessel Capacity/Size: 16.95 liters Diameter: _____ Length: _____
 Normal Operating Pressure (OP) 0.02-bar (0.25-psia)
 MAWP-OP = 28.75 PSID

List the numbers of all pertinent drawings and the location of the originals.

<u>Drawing #</u>	<u>Online Location of Original</u>
<u>D000000000872825</u>	<u>ILC EDMS (Engineering Data Management System), Team Center Enterprise - Hosted by DESY in Hamburg, Germany</u>
<u>4906.320-ME-440302</u>	<u>Fermi TDM</u>
<u>5520.000-ME-440517</u>	<u>Fermi TDM</u>

2. Design Verification

Is this vessel designed and built to meet the Code or "In-House Built" requirements?
Yes _____ No X_____.

If "No" state the standard that was used The ASME BPVC (the Code),
Section VIII, Division 1, reference to published mechanical data
for niobium and niobium-titanium materials (where Code data is not
available)

Demonstrate that design calculations of that standard have been made and that other requirements of that standard have been satisfied.
Skip to part 3 "system venting verification."

Does the vessel(s) have a U stamp? Yes _____ No X. If "Yes", complete section 2A; if "No", complete section 2B.

A. Staple photo of U stamp plate below.
Copy "U" label details to the side

Copy data here:

--	--

Provide ASME design calculations in an appendix. On the sketch below, circle all applicable sections of the ASME code per Section VIII, Division I. (Only for non-coded vessels)

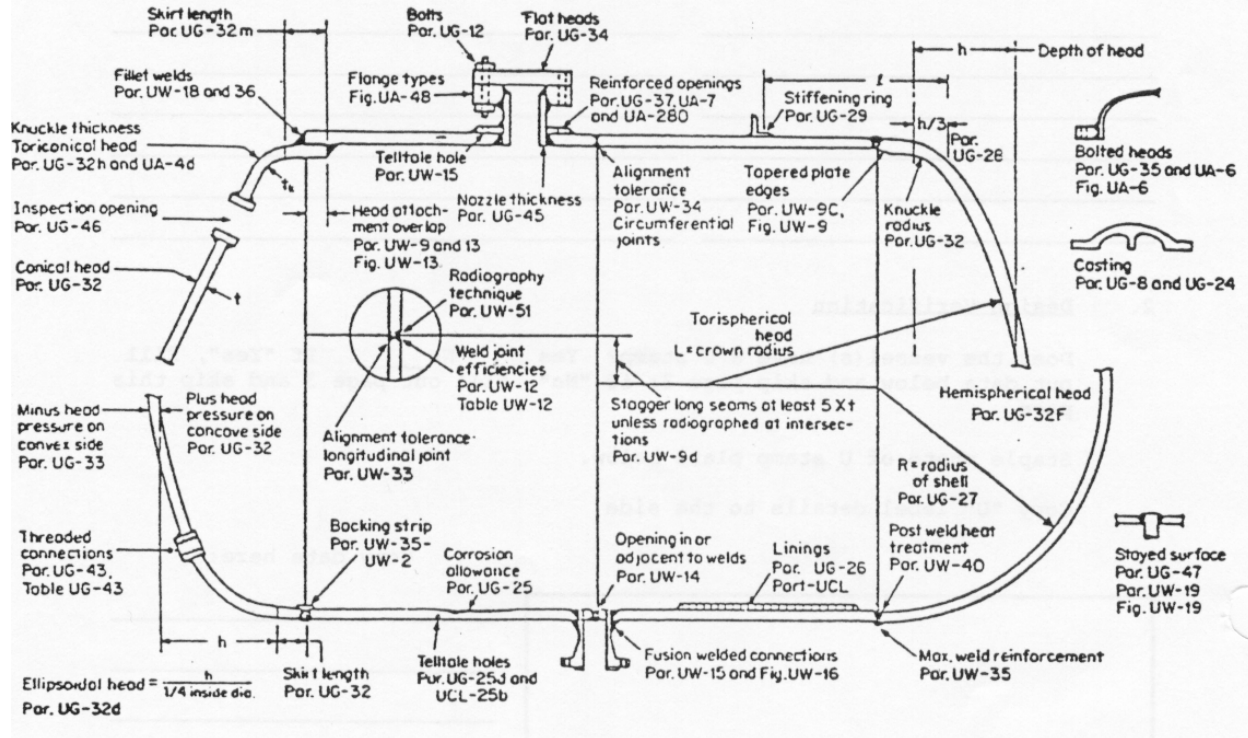


Figure 1. ASME Code: Applicable Sections

2B.

Summary of ASME Code

Item	Reference ASME Code Section	CALCULATION RESULT (Required thickness or stress level vs. actual thickness calculated stress level)
		VS
		VS
		VS
		VS
		VS

3. System Venting Verification Provide the vent system schematic.

Does the venting system follow the Code UG-125 through UG-137?

Yes__ No X

Does the venting system also follow the Compressed Gas Association Standards S-1.1 and S-1.3?

Yes ____ No X

Note that the burst disk is not a Code-stamped device due to the low set pressure (below 15-psig). However, all system venting calculations follow the standard codes listed (ASME BPVC and CGA).

A "no" response to both of the two proceeding questions requires a justification and statement regarding what standards were applied to verify system venting is adequate.

List of reliefs and settings:

For the Horizontal Test Cryostat:

<u>Manufacturer</u>	<u>Model #</u>	<u>Set Pressure</u>	<u>Flow Rate</u>	<u>Size</u>
<u>BS&B</u>	<u>LPS</u>	<u>12-psig</u>	<u>2188-SCFM air</u>	<u>3-inch</u>
<u>Hylok 700</u>	<u>CV5-F12N-25</u>	<u>5-psig *</u>	<u>Cv=5.2</u>	<u>3/4-inch</u>

*The valve was reset to 5-psig from 25-psig by the PPD Mechanical Vacuum and Instrumentation Group. The model number reflects the original set pressure of 25-psig.

4. Operating Procedure

Is an operating procedure necessary for the safe operation of this vessel?

Yes ____ No X (If "Yes", it must be appended)

5. Welding Information

Has the vessel been fabricated in a non-code shop? Yes X No ____

If "Yes", append a copy of the welding shop statement of welder qualification (Procedure Qualification Record, PQR) which references the Welding Procedure Specification (WPS) used to weld this vessel.

6. Existing, Used and Unmanned Area Vessels

Is this vessel or any part thereof in the above categories?

Yes ____ No X

If "Yes", follow the requirements for an Extended Engineering Note for Existing, Used and Unmanned Area Vessels.

7. Exceptional Vessels

Is this vessel or any part thereof in the above category?

Yes X No ____

If "Yes", follow the requirements for an Extended Engineering Note for Exceptional Vessels.

Appendix A

Extended Engineering Note for Exceptional Vessel

Introduction

The 1.3-GHz “dressed cavity” is a niobium superconducting radio frequency (SRF) cavity surrounded by a titanium vessel. The vessel contains liquid helium which surrounds the SRF cavity. During operation of the dressed cavity, the liquid helium is at a temperature as low as 1.8°K.

The design of the Generation 3 (G3) Helium Vessel RF Cavity Assembly has been modified from the TESLA TTF design for more efficient fabrication. The design is the result of a collaboration between FNAL and INFN.

AES-4 will be fully tested in the Horizontal Test System (HTS) at the Meson Detector Building. At the time of writing the original version of this engineering note, the final location of AES-4 after it has been tested in HTS has not been determined.

This pressure vessel engineering note describes the design and fabrication of the AES-4 1.3-GHz dressed cavity. This document also summarizes how the AES-4 vessel follows the requirements of the FESHM Chapter 5031 for Pressure Vessels ⁽¹⁾. Note that the original version of the note will contain venting calculations for the dressed cavity when it is installed in HTS. An amendment will be added to the note once the final operating location of AES-4 is determined. This document and supporting documents for the AES-4 helium vessel engineering note may be found online at:

<http://ilc-dms.fnal.gov/Workgroups/CryomoduleDocumentation/AES004/>

Exceptional Vessel Discussion

Reasons for Exception

Pressure vessels, as defined in FESHM Chapter 5031, are designed and fabricated following the ASME Boiler and Pressure Vessel Code (the Code) ⁽²⁾. The 1.3-GHz dressed cavity as a helium pressure vessel has materials and complex geometry that are not conducive to complete design and fabrication following the Code. However, we show that the vessel is safe in accordance with FESHM 5031. Since the vessel design and fabrication methods cannot exactly follow the guidelines given by the Code, the vessel requires a Director’s Exception. Table 1 lists the specific areas of exception to the Code.

Analysis and use of the ASME Code

The extended engineering note presents the results of the analysis that was performed on the entire vessel.

Analytical Tools

Analysis was done using ANSYS Workbench 11 and Mathcad version 14.

Table 1 – Areas of Exception to the Code

Item or Procedure	Reference	Explanation for Exception	How the Vessel is Safe
Niobium material	Pg. 21, 32	Used for its superconducting properties; Not an established material listed by the Code	There has been extensive testing done on the niobium used in the cavity. The Code procedure for determining Div.1 allowable stresses (see Section II, Part D, Mandatory Appendix 1) are conservatively applied to the measured yield and ultimate stresses to establish allowable stresses which are consistent with Code philosophy.
Niobium-Titanium material	Pg. 21, 32	Used for as a transition material between niobium and titanium materials for welding purposes; Not an established material listed by the Code	Material properties were provided by the vendor of the material.
Some category B (circumferential) welds in the titanium sub-assembly are Type 3 butt welds (welded from one side with no backing strip).	Pg. 21, 26	Category B joints in titanium must be either Type 1 butt welds (welded from both sides) or Type 2 butt welds (welded from one side with backing strip) only (see the Code, Div. 1, UNF-19(a)).	The evaluation of these welds is based on a de-rating of the allowable stress by a factor of 0.6, the factor given in Div. 1, Table UW-12 for a Type 3 weld when not radiographed.
No liquid penetrant testing was performed on the titanium sub-assembly.	Pg. 21, 26	All joints in titanium vessels must be examined by the liquid penetrant method (see the Code, Div. 1, UNF-58(b)).	The evaluation of all welds is based on a de-rating of the allowable stress by a factor given in Div. 1, Table UW-12 for welds not radiographed. For the corner joints, the joint efficiency has to be less than 1.00.
No electron beam welds were ultrasonically examined in their entire length	Pg. 21, 26	All electron beam welds in any material are required to be ultrasonically examined along their entire length (see the Code, UW-11(e)).	The evaluation of all welds is based on a de-rating of the allowable stress by a factor given in Div. 1, Table UW-12 for welds not radiographed.
Use of enhanced material properties at cryogenic temperatures in stress analysis	Pg 21, 32	Titanium is not a material with established material properties at temperatures less than 38°C by the Code (see the Code, ULT-5(b))	Published material properties for titanium (outside the Code) at cryogenic temperatures were used.
Fabrication procedure for the niobium cavity assembly does not include WPS, PQR, or WPQ	Pg. 73, 75	The fabrication procedure for the niobium cavity is propriety. Detailed information on the procedure is not available.	The RF performance of the niobium cavity is acceptable, showing indirectly that all welds in the cavity are full penetration

Item or Procedure	Reference	Explanation for Exception	How the Vessel is Safe
Weld at the 2-phase helium pipe stub attachment to the vessel	Pg. 73, 77	- Not a Code-approved design (Fig. UW-16.1) - X-ray report shows that there is not complete fusion.	Video examination of the weld shows that it is greater in size than the minimum required thickness.
System venting verification	Pgs. 6, 60-72	The Code does not recognize relief valves set for pressures below 15 psig	The cavity will be operated installed in the Horizontal Test System at MDB. The venting system for the HTS has been analyzed for all worst case venting conditions for a single 1.3GHz dressed cavity and has been shown to be safe.

Fabrication

For all welds, the available Weld Procedure Specifications (WPS), Procedure Qualification Record (PQR), and Welder Performance Qualification (WPQ) are stored online at:

<http://ilc-dms.fnal.gov/Workgroups/CryomoduleDocumentation/AES004/weld-docs/>

Other fabrication documents such as electronic copies of material certifications and leak check results are located online at:

<http://ilc-dms.fnal.gov/Workgroups/CryomoduleDocumentation/AES004/other-fab-docs/>

Hazard Analysis

When tested in the HTS, the 1.3-GHz helium vessel is completely contained with a multilayered structure that protects personnel. The 5°K copper thermal shield completely surrounds the helium vessel. The 80°K copper thermal shield, in turn, completely surrounds the 5°K. The outer vacuum vessel of the HTS encases the 80°K thermal shield. From a personnel safety standpoint, the helium vessel is well contained within the both the test cryostat and the cryomodule. For the HTS, vacuum safety reliefs vent any helium spill. The vacuum vessel relief analysis for the HTS is documented in its vacuum vessel engineering note ^[3].

Pressure Test

The helium vessel [will be] pressure tested to 2.3-bar, which is 1.15 times the warm MAWP of 2.0-bar.

Description and Identification

AES-4 is a G3 Helium Vessel RF Cavity Assembly. It is pressure vessel number IND-132. The top assembly drawing of the assembly, drawing 872825, is shown in Figures 2 and 3. The G3 Helium Vessel RF Cavity Assembly consists essentially of two sub-assemblies: the niobium SRF cavity and the titanium helium vessel.

The niobium SRF cavity is an elliptical nine-cell assembly. A drawing of the nine-cell cavity is shown in Figure 4 (drawing 4904.010-MD-440004). A single cell, or a dumbbell, consists of two half-cells that are welded together at the equator of the cell. Rings between the cells stiffen the assembly to a point. Some flexibility in the length of the nine-cell cavity is required to tune the cavity and optimize its resonance frequency. The end units each consist of a half cell, an end disk flange, and a transition flange. The transition flange is made of a titanium-niobium alloy. The iris' minimum inner diameter is 35-mm (1.4-in), and the maximum diameter of a dumbbell is 211.1-mm (8.3-in) (see drawing 4904.010-MD-439173). The length of the cavity, flange-to-flange, is 1247.4-mm (49.1-in.) (see drawing 4904.010-MD-440004). Refer to the section titled "Drawing Tree" for the location of the drawings not shown in this note.

The titanium helium vessel encases the niobium SRF cavity. Figure 5 shows the drawing of the titanium vessel assembly (drawing 812765). The vessel has a helium fill port at the bottom. Close to the top of the vessel is the two-phase helium return line. At the sides of the vessel are tabs which support the vessel within the HTS cryostat. The vessel is flexible in length due to a bellows at the middle of its length. This flexibility in the vessel allows for accommodating the change in the nine-cell cavity length due to thermal contraction at cryogenic temperature and to turning the cavity during operation. A slim blade tuner supports the vessel around the bellows. Two control systems act on the blade tuner to change the length of the vessel, and thus change the length of the cavity. A slow-control tuner system that consists of a stepper motor that changes the vessel length. The stepper motor extends the length of the cavity (and the helium vessel) by less than 2.0-mm (0.079-in.) to bring it to the desired resonance frequency to counteract the combined effects of thermal contraction and pressurization during cooldown. Once the cavity is at cryogenic temperature, the slow tuner system is shut-off. A fast-control tuner system consisting of two piezoelectric actuators prevents detuning of the cavity during operation due to Lorentz Forces and noise sources (microphonics)⁽⁴⁾. The piezos provide an increase in bellows length (bellows expansion) of 13- μ m during operation.⁽¹⁹⁾ The vessel is expected to have a lifetime of 10-years. The minimum inner diameter of the cylindrical part of the vessel (both the tubes and bellows) is 230-mm (9.1-in.). Refer to the tubes drawings 812995 and 813005 and bellows drawing 844575.

The design of the niobium nine-cell cavity is the same as the cavities used in the TESLA facility at DESY (Hamburg, Germany), which has been in operation for the past 10 years. The design of the helium vessel is a modification of the TESLA design. The location of the titanium bellows, along with the blade tuner and control systems, is a modification of the TESLA design that is the result of collaboration between Fermilab and INFN.

The dressed cavity will be performance tested in HTS. The results of the testing will be feedback in optimizing the design and fabrication process for future G3 dressed cavities which will be used in a cryomodule.

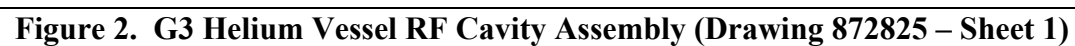
The dressed cavity has two internal maximum allowable working pressures (MAWP). At room temperature, the (warm) internal MAWP is 2.0-bar. The vessel will be pressure tested in room temperature. The internal MAWP for cold temperatures (2°K) is 4.0-bar. The external MAWP is 1.0-bar.

Drawing Tree

A drawing tree for the G3 Helium Vessel RF Cavity Assembly is shown in Table 2. All drawings are located online at

<http://ilc-dms.fnal.gov/Workgroups/CryomoduleDocumentation/AES004/drawings/>

There are three separate files that are located online: the top assembly drawing, 872825 – G3 Helium Vessel RF Cavity Assembly; the G3 Helium Vessel Assembly, drawing 812765, and its sub-assembly and component drawings; and the RF Cavity Assembly, drawing 440004, and its sub-assembly and component drawings.



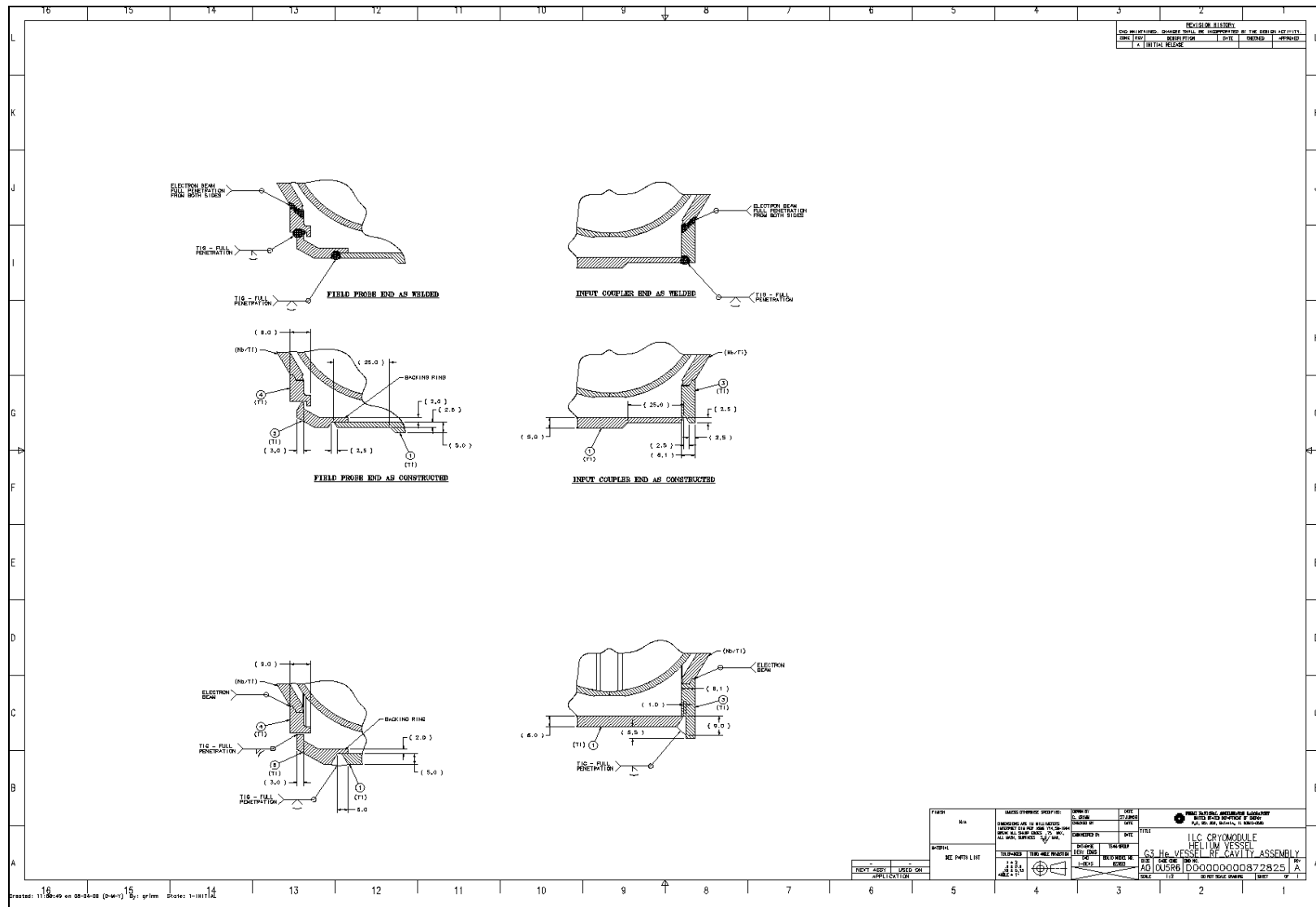


Figure 3. G3 Helium Vessel RF Cavity Assembly (Drawing 872825 – Sheet 2)

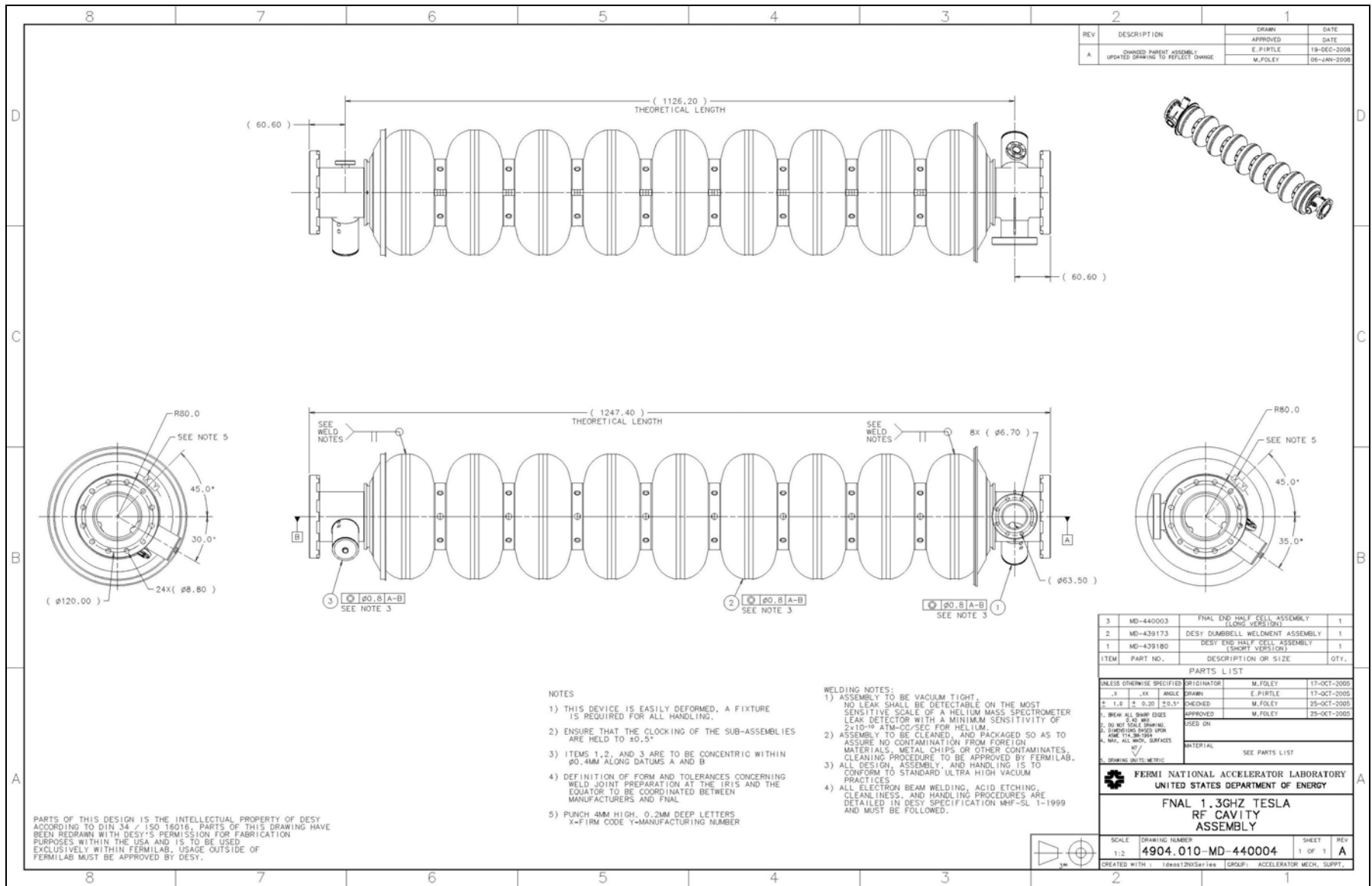


Figure 4. 1.3-GHz Nine Cell RF Cavity Assembly (4904.010-MD-440004)

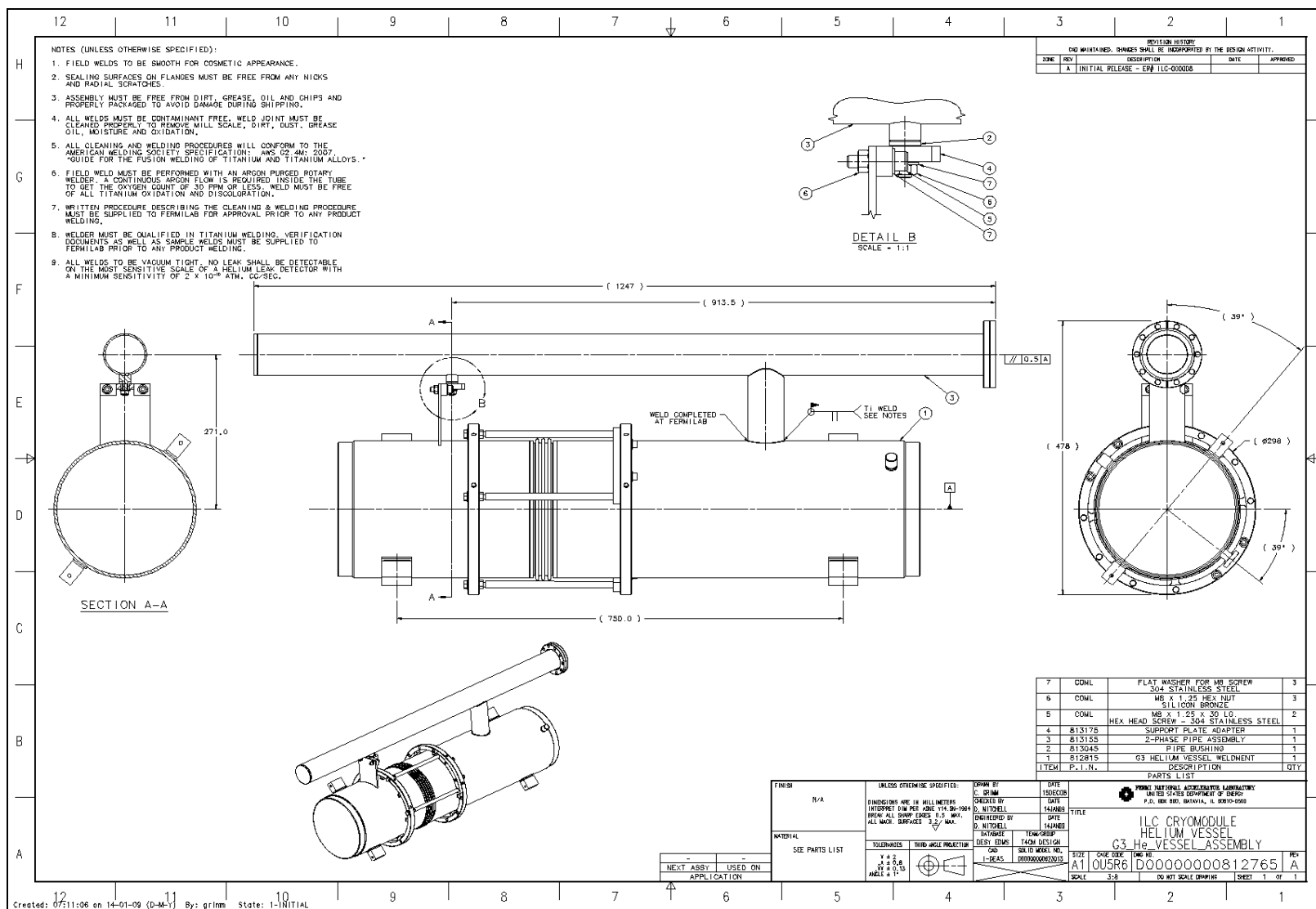


Table 2 – Drawing Tree for the G3 Helium Vessel RF Cavity Assembly

Drawing No.	Rev.	Title
872825	A	G3 He Vessel RF Cavity Assembly
812765	A	G3 He Vessel Assembly
812815	A	G3 Helium Vessel Weldment
844675	A	Tuner Ring Piezo End
844685	A	Tuner Ring Coupler End
812995	A	Tube Fld Probe End
813005	A	Tube MC End
844575	A	(COML) He Vessel Bellows Assmby G3
813065	A	Invar Rod Clamping Pin
813165	A	Roller Pad Wide
813205	A	CF Flange Custom Knife Edge
844695	A	Vessel Support Bracket
844705	A	Spanner Rod
813035	A	Pipe Support Plate
813045	A	Pipe Bushing
813155	A	2-Phase Pipe Assembly
813075	A	Pipe Cap
813085	A	2-Phase Pipe
813055	A	Sliding Pipe Pin
863685	A	2-Phase Helium Supply Pipe
791535	A	Flange CF Knife Edge Body
813175	A	Support Plate Adapter
440004	A	RF Cavity Assembly
449180	D	Short End Half Cell Assembly
439178	B	End Disk Weldment - Short Version
439164	A	End Tube Spool Piece
439152	B	End Cap Flange
439168	--	End Cap Disk (Short Version)
439163	--	RF Half Cell (Short Version)
439177	A	End Tube Weldment - Short Version
439175	--	Short Version HOM Assembly
439166	--	Short Version HOM Formteil Housing
439150	--	HOM Spool Piece
439162	--	Short Version Formteil
439161	B	Short Version End Tube
439171	--	Coupler Spool Piece
439169	--	Coupler Rib
439159	--	NW78 Beam Flange
439158	--	NW40 Coupler Flange
439157	--	NW12 HOM Flange
813185	A	Cavity Transition Ring MC End
439173	-	DESY Dumbbell Weldment
439172	--	Dumbbell
439156	--	Mid Half Cell
439151	A	Half Support Ring
440003	-	FNAL End Half Cell Assembly
439178	B	End Disk Weldment (Long Version)
439164	A	End Tube Spool Piece
439152	B	End Cap Flange
439167	--	End Cap Disk (Long Version)
439155	--	RF Half Cell (Long Version)
440002	B	FNAL End Tube Weldment (Long Version)
439174	--	DESY Long Version HOM Assembly
439165	--	HOM Long Version Formteil Housing
439150	--	HOM Spool Piece
439154	--	Long Version Formteil
440001	--	FNAL Long Version End Tube
439170	A	DESY Antenna Spool Piece
439159	--	DESY NW78 Beam Flange
439160	--	DESY NW8 Antenna Flange
439157	--	DESY NW12 HOM Flange
813195	A	Cavity Transition Ring Field Probe End
872775	A	Cavity-Vessel Adapter Ring Rough

Blade Tuner Description

While not an integral part of the pressure vessel design, the blade tuner's function is affected by the performance of the pressure vessel. Figure 2 (drawing 872825) shows the “slim” blade tuner around the titanium bellows on the helium vessel. The blade tuner maintains the tuning of the RF cavity after cooldown of the vessel and during operation of the RF cavity. The design that is used on AES-4 is version 3.9.4.⁽¹⁸⁾

Figure 6 shows the different parts of the blade tuner assembly. The tuner rings (part numbers 844675 and 844685) are welded to the titanium helium vessel.

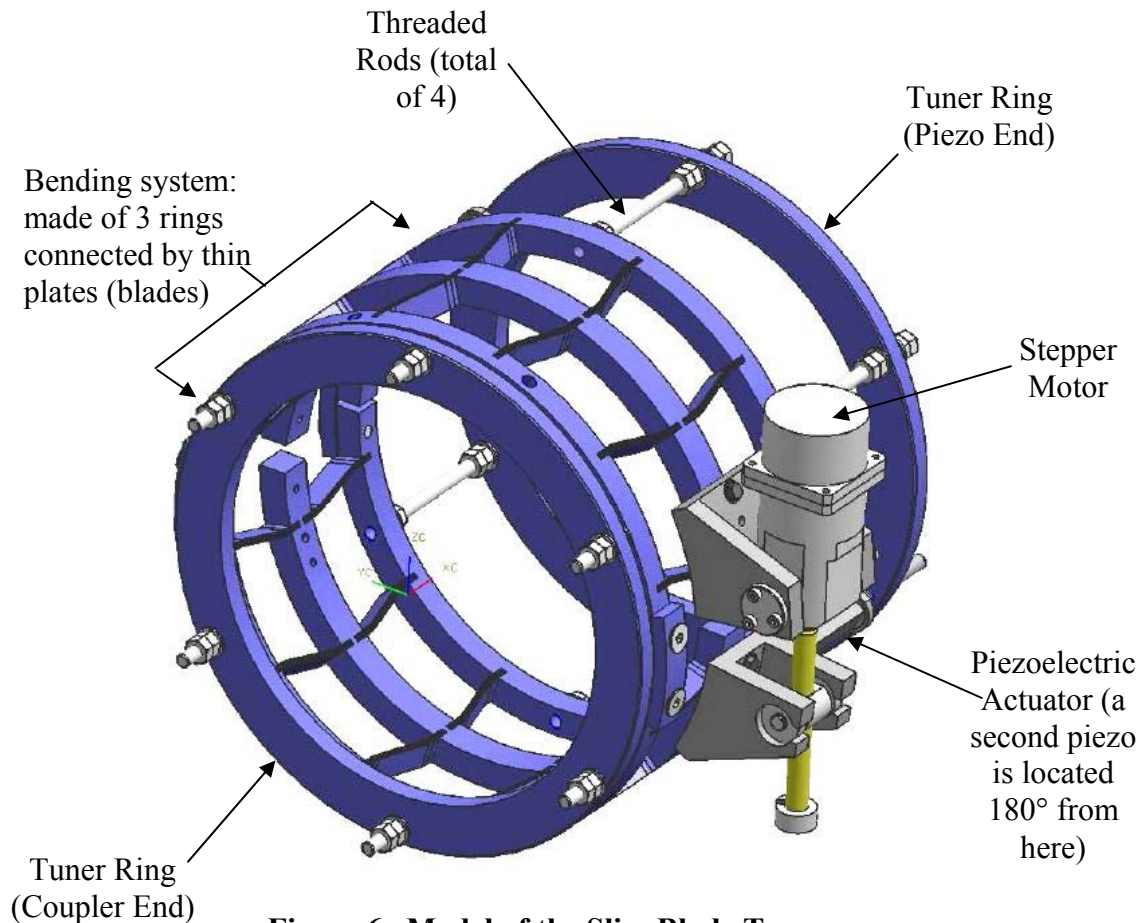


Figure 6. Model of the Slim Blade Tuner

The tuner assembly is composed of two parts that are defined by their tuning functions: slow tuner assembly and the fast tuner assembly. The slow tuner assembly consists of the stepper motor and the bending system. The bending system consists of three rings. One ring is rigidly attached to the helium vessel by way of the tuner ring (at the coupler end). The central “ring” is divided into two halves. The three rings are connected by thin plates, or blades.⁽¹⁹⁾ The stepper motor “is rigidly connected to the helium vessel and produces a rotation of the [central ring halves]. The movement of the [central ring halves] induces the rotation of the bending system that changes the cavity length.” The design of the bending system of the slow tune assembly “provides the amplification of the torque of the stepper motor, dramatically reducing the total movement and increasing the tuning sensitivity.”⁽¹⁸⁾

The fast tuner assembly consists of two piezoelectric actuators that are parallel to each other and clocked 180° from each other. One side of the fast tuner assembly is fixed to the helium vessel, and the other side is fixed to the bending system of the slow tuner assembly. Figures 6 and 7 show how the piezoelectric actuators are installed.

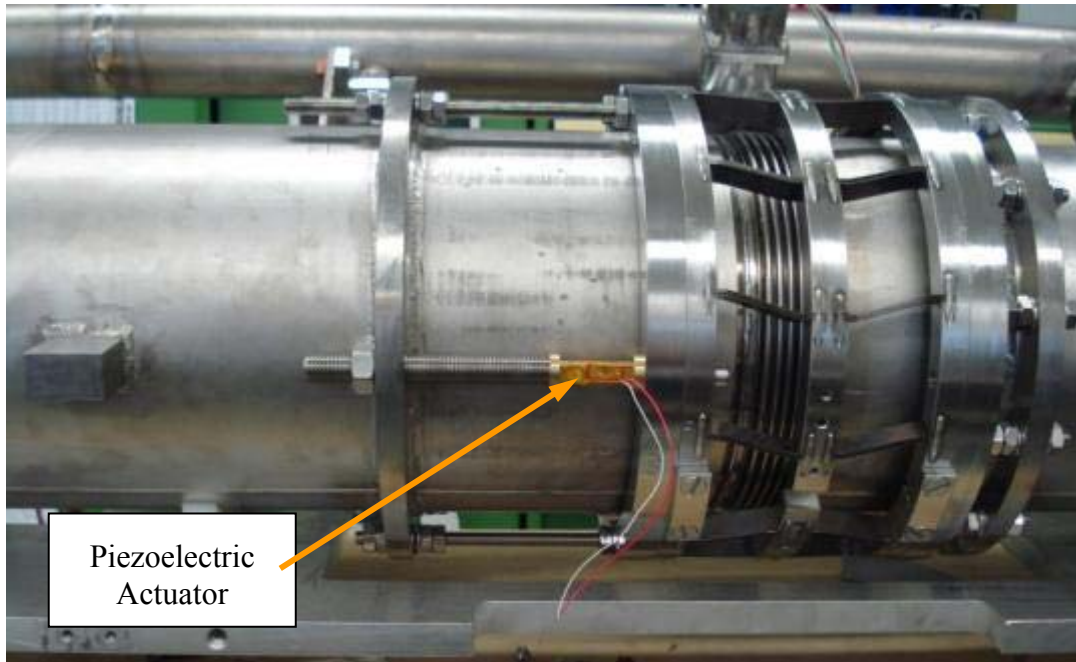


Figure 7. Slim Blade Tuner Installed on Helium Vessel. One of the two piezoelectric actuators is shown here. The other piezo is located 180° from the one shown here. ^[19]

The slow tuner system lengthens the vessel to maintain the RF cavity tuning after cooldown. The extension compensates for the combined effects of thermal contraction and pressurization, thus bringing the SRF cavity back to its desired resonance frequency. The stepper motor is actuated to increase the vessel length about 1.5-mm after cooldown. During operation of the RF cavity, the beam pulses create a tendency for the RF cavity to decrease in length. This phenomenon is called Lorentz Force Detuning. The piezoelectric actuators increase the vessel length about 13-μm during operation. ⁽¹⁹⁾

Displacement and Force Limits of the Slim Blade Tuner

The limits of displacement that cause the slim blade tuner to change the length of the vessel are defined by deformation of the tuner assembly. The maximum tuning range of the blade tuner assembly corresponds to 14 steps of the stepper motor (see Section 6.3.3.2 of the Panzeri paper). ⁽¹⁸⁾ For more than 12 steps of the stepper motor, the tuner assembly goes from yield deformation into plastic deformation. The 12 steps corresponds to a displacement of less than 1.8-mm (Figure 37 of the Panzeri paper).

The tuner ring and four threaded rods provide an additional limit on the movement of the tuner assembly. During assembly at room temperature, the outer bolts are installed so that there is a 0.2-mm gap between each bolt and the tuner ring. In the final assembly, the tuner ring is compressing the piezoelectric actuators. The threaded rods act as a safety device in the case of a piezoelectric actuator failure or overpressure of the helium vessel. The threaded rods limit free movement of the tuner assembly to less than 0.2-mm.

The maximum expected force of compression on the tuner assembly is 3116-N during operation. This would occur when the beam tube is evacuated, the helium vessel is internally pressurized at 1-bar, and the helium vessel is externally pressurized at 1-bar. The expected compressive force is less than the maximum allowed compressive force of 10900-N. Note that the maximum allowed force takes into account a design factor of 1.5.⁽¹⁸⁾

The maximum calculated tensile force on the tuner assembly is 9630-N. This would occur during an emergency scenario when the helium vessel is internally pressurized to its MAWP of 4-bar. The maximum allowed tensile force is 19000-N. So when the vessel is at its internal MAWP, the expected tensile force exerted on the tuner assembly is well within the tuner's allowed tensile force. Note that these calculations took into account material properties at room temperature. The assumption was made that the material properties would be better at cryogenic temperatures.⁽¹⁸⁾

Table 3 summarizes the limits of movement and forces and the required movement and forces of the slim blade tuner assembly.

Table 3 – Summary of the Movement and Forces on the Slim Blade Tuner Assembly

	Maximum Allowed	Required Value
Slow tuner movement range	0 – 1.8 mm	0 – 1.5 mm
Free movement range	0 – 0.2 mm	---
Compressive force	10,900 N	3116 N
Tensile force	19,00 N	9630 N

Design Verification

Introduction and Summary

This analysis is intended to demonstrate that the AES-4 1.3 GHz SRF cavity conforms to the ASME Boiler and Pressure Vessel Code (the “Code”), Section VIII, Div. 1, to the greatest extent possible.

Where Div. 1 formulas or procedures are prescribed, they are applied to this analysis. For those cases where no rules are available, the provisions of Div. 1, U-2(g) are invoked. This paragraph of the Code allows alternative analyses to be used in the absence of Code guidance.

This cavity contains several features which are not supported by the Code. These are related primarily to materials, weld types, and non-destructive examination, and are addressed in detail in the next section of this report, titled “Non-Code Elements.” These are accepted as unavoidable in the context of SRF cavities, and every effort is made to demonstrate thorough consideration of their implications in the analysis.

Advantage is taken of the increase in yield and ultimate strength which occurs in the Nb and Ti components at the operating temperature of 1.88 K.

The design pressures specified for this analysis are 30 psi (2.0-bar) at 293 K, and 60 psi (4.0-bar) at 1.88 K. This analysis confirms that the MAWPs of the vessel can be safely set at these pressures. Negligible margin for increase is available at 293 K, but the cold MAWP could be increased substantially above 60 psi (4.0-bar).

In addition to these fundamental operating limits, the cavity was also shown to be stable at external pressures on the Ti shell of 15 psid (1.0-bar), and internal pressures on the Nb cavity of 15 psid (1.0-bar); these loadings could occur under fault conditions, when the beam and insulating vacuums have been compromised, and the helium volume has been evacuated.

Non-Code Elements

With regards to the Design Verification, the AES-4 1.3 GHz cavity does not comply with Div. 1 of the Code in the following ways:

1. Pure niobium, and Ti-45Nb titanium alloy are not “Code” materials, i.e., they have not been approved for use in Div. 1 or Div. 2 vessels, and there are no mechanical properties available from Code sources.
2. Category A and B joints in titanium must be either Type 1 butt welds (welded from both sides) or Type 2 butt welds (welded from one side with backing strip) only (see Div. 1, UNF-19(a)). Some category B (circumferential) joints in the AES-4 are Type 3 butt welds (welded from one side with no backing strip.)
3. All joints in titanium vessels must be examined by the liquid penetrant method. (see Div. 1, UNF-58(b)). No liquid penetrant testing was performed on the vessel.
4. All electron beam welds in any material are required to be ultrasonically examined along their entire length. (see UW-11(e)). No ultrasonic examination was performed on the vessel.
5. The use of enhanced material properties at cryogenic temperatures for titanium is not allowed by the Code. For this design analysis, published material properties for titanium (outside the Code) at cryogenic temperatures are used.

Although material properties are not available for Nb or Ti-45Nb from Code sources, there has been extensive testing done on the Nb used in the cavity. The Code procedures for determining Div. 1 allowable stresses (see Section II, Part D, Mandatory Appendix 1) are conservatively applied to the measured yield and ultimate stresses to establish allowable stresses which are consistent with Code philosophy.

The evaluation of the Type 3 butt welds in the titanium is based on a de-rating of the allowable stress by a factor of 0.6, the factor given in Div. 1, Table UW-12 for such welds when not radiographed.

The exceptions listed above do not address Code requirements for material control, weld procedure certification, welder certification, etc. These requirements, and the extent to which the cavity production is in compliance with them, are addressed in the section titled “Weld Information.”

Geometry

General

This analysis is based on geometry obtained from Drwg # 872825 and associated details.

Figure 8 shows the dressed cavity, complete with shielding, piping and blade tuner.

For the analysis, only the Nb cavity, conical Ti-45Nb heads, and titanium shells and bellows are modeled, as well as the flanges to which the blade tuner attaches to the Ti cylindrical shell. These components are shown in Figure 9.

The geometric limits of the analysis are further clarified in Figure 10.

The individual cavity component names used in this report are shown in Figure 11.

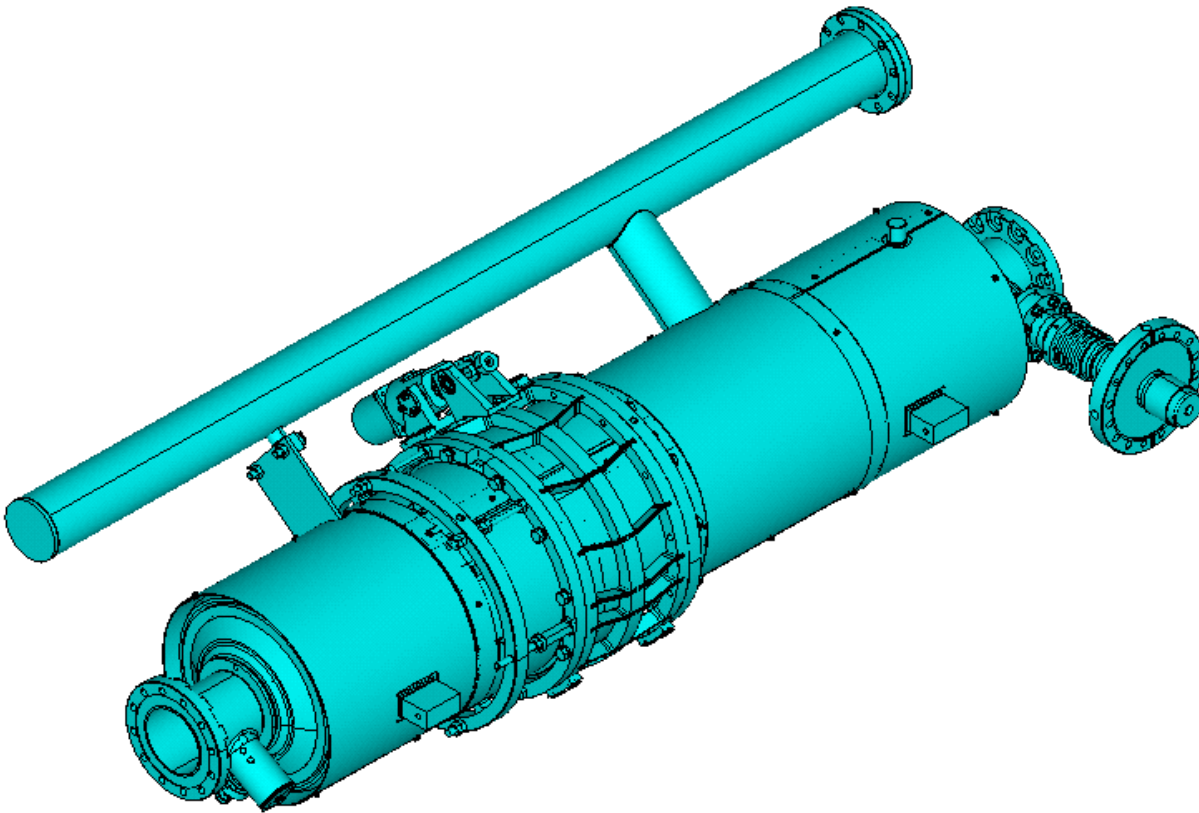


Figure 8. AES1 SRF cavity

cavity assembly as analyzed (Nb cavity not fully visible)

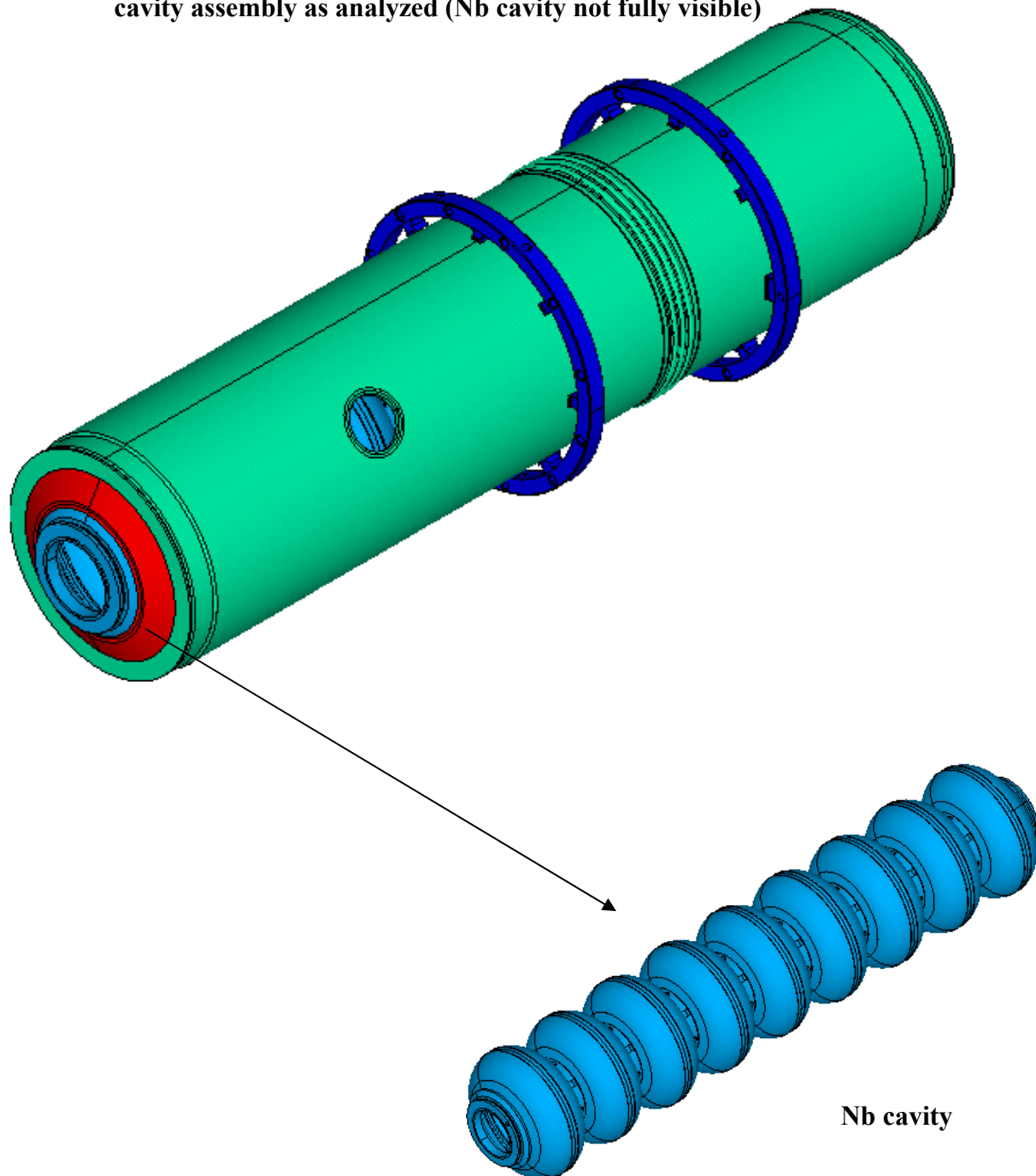


Figure 9. Cavity components considered in the analysis

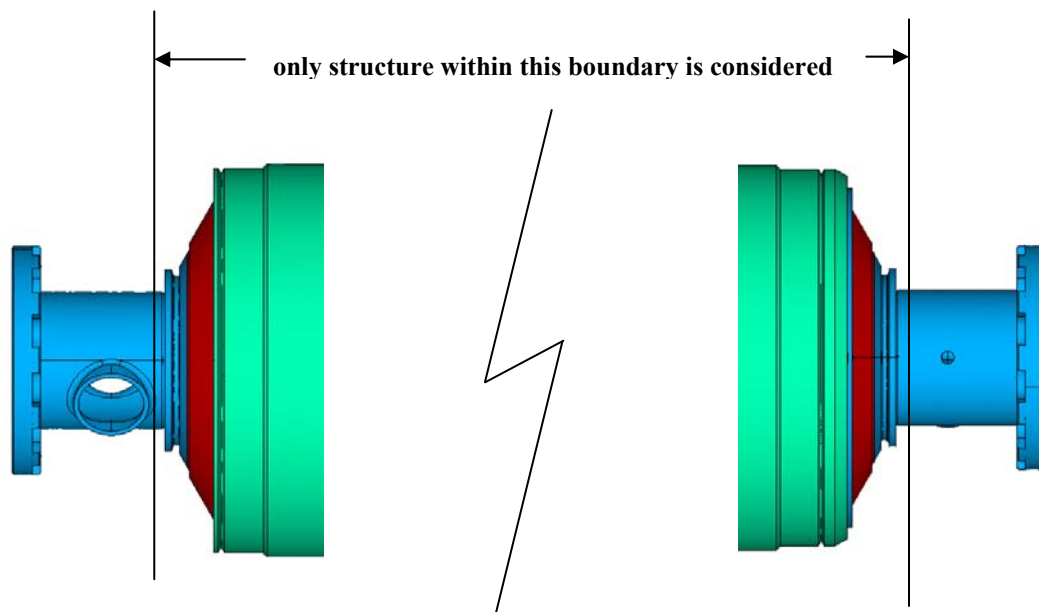


Figure 10. Geometric limits of analysis

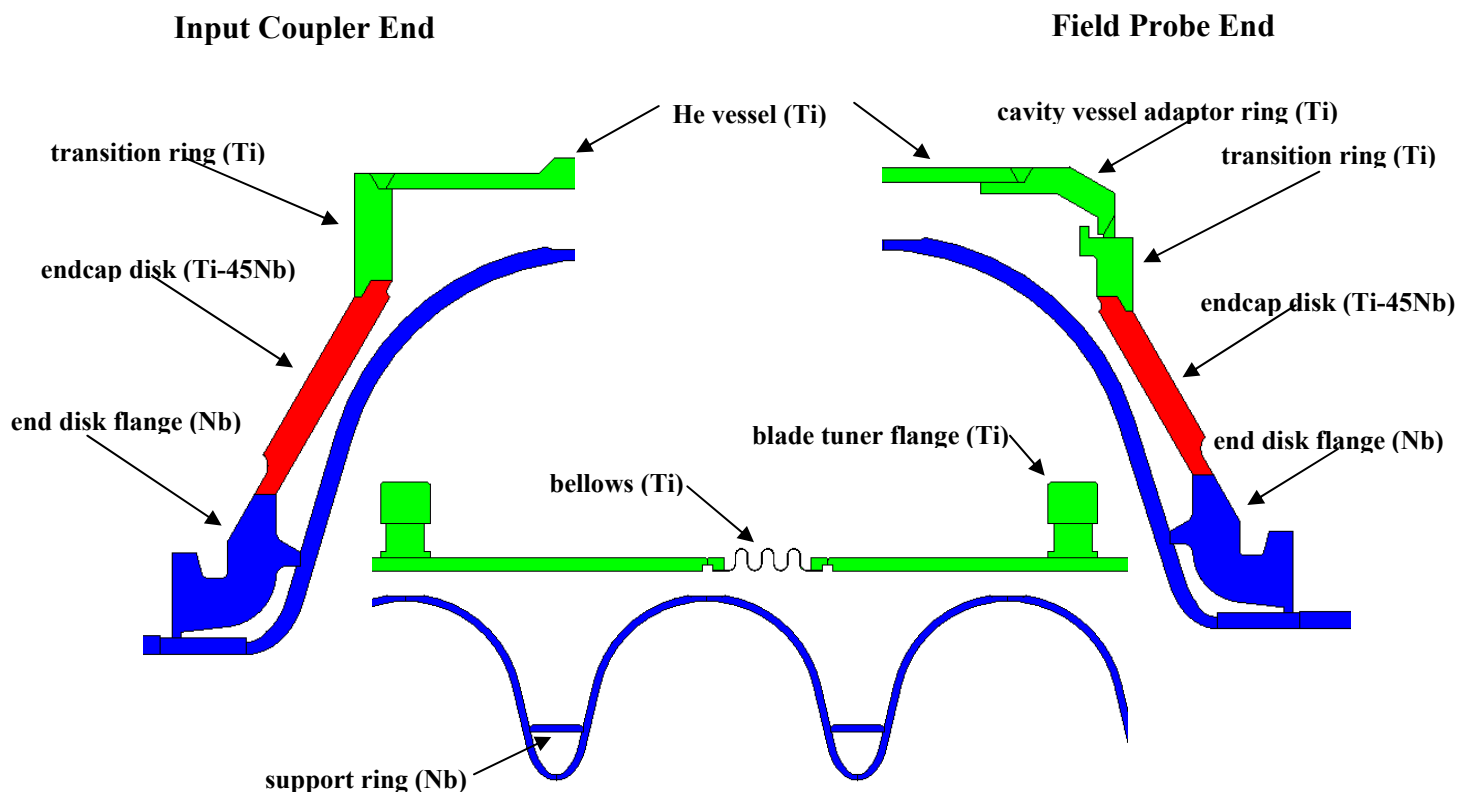


Figure 11. Parts and Materials

Welds

This section of the note describes the welds as a precursor to the weld stress evaluation. Details regarding the weld fabrication process are shown in a later section of this note titled “Welding Information.”

Welds are produced by the EB process (in the Nb, and Nb-to-Ti transitions), and the TIG (GTAW) process (Ti-Ti welds).

All welds on the dressed cavity are designed as full penetration butt welds. All welds are performed from one side, with the exception of the Ti-45Nb to Ti transition welds. Those welds are performed from two sides. No backing strips are used for any welds.

Table 3 summarizes the weld characteristics, including the Code classification of both joint category and weld type, and the corresponding efficiency.

The locations of the welds as numbered in Table 4 are shown in Figure 12. Detailed weld configurations and assumed zones of fusion are illustrated in Figs. 13-16.

Table 4 – Summary of Weld Characteristics

Weld	Weld Description	Drawing	Materials Joined	Weld Process	Joint Category	Code Weld Type	Joint Efficiency
1	End Tube Spool Piece to End Cap Flange	MD-439178	Nb-Nb	EB	B	3	0.6
2	End Tube Spool Piece to RF Half Cell	MD-439178	Nb-Nb	EB	B	1	0.7
3	End Cap Flange to RF Half Cell	MD-439178	Nb-Nb	EB	-	3	0.6
4	End Cap Flange to End Cap Disk	MD-439178	Nb-Ti45Nb	EB	B	3	0.6
5	End Cap Disk to Transition Ring	MD-439180 MD-440003	Ti45Nb-Ti	EB	B	1	0.7
6	1.3GHz 9 Cell RF Cavity (Transition Ring) to Cavity-Vessel Adapter Ring	872825	Ti-Ti	TIG	B	3	0.6
7 (FB End)	Cavity-Vessel Adapter Ring to G3 Helium Vessel Assembly	872825	Ti-Ti	TIG	C	7	0.7
7 (Coupler End)	G3 Helium Vessel Assembly to 1.3GHz 9 Cell RF Cavity	872825	Ti-Ti	TIG	C	7	0.7
8	Bellows Assembly to Tube	812815	Ti-Ti	TIG	B	3	0.6
9	Support Ring to Half Cell	MC-439172	Nb-Nb	EB	-	3	0.6
10	Dumbbell to Dumbbell	MD-439173	Nb-Nb	EB	B	3	0.6
11	Half Cell to Half Cell	MC-439172	Nb-Nb	EB	B	3	0.6
12	Bellows Convolutions to Weld Cuff	844575	Ti-Ti	TIG	B	3	0.6

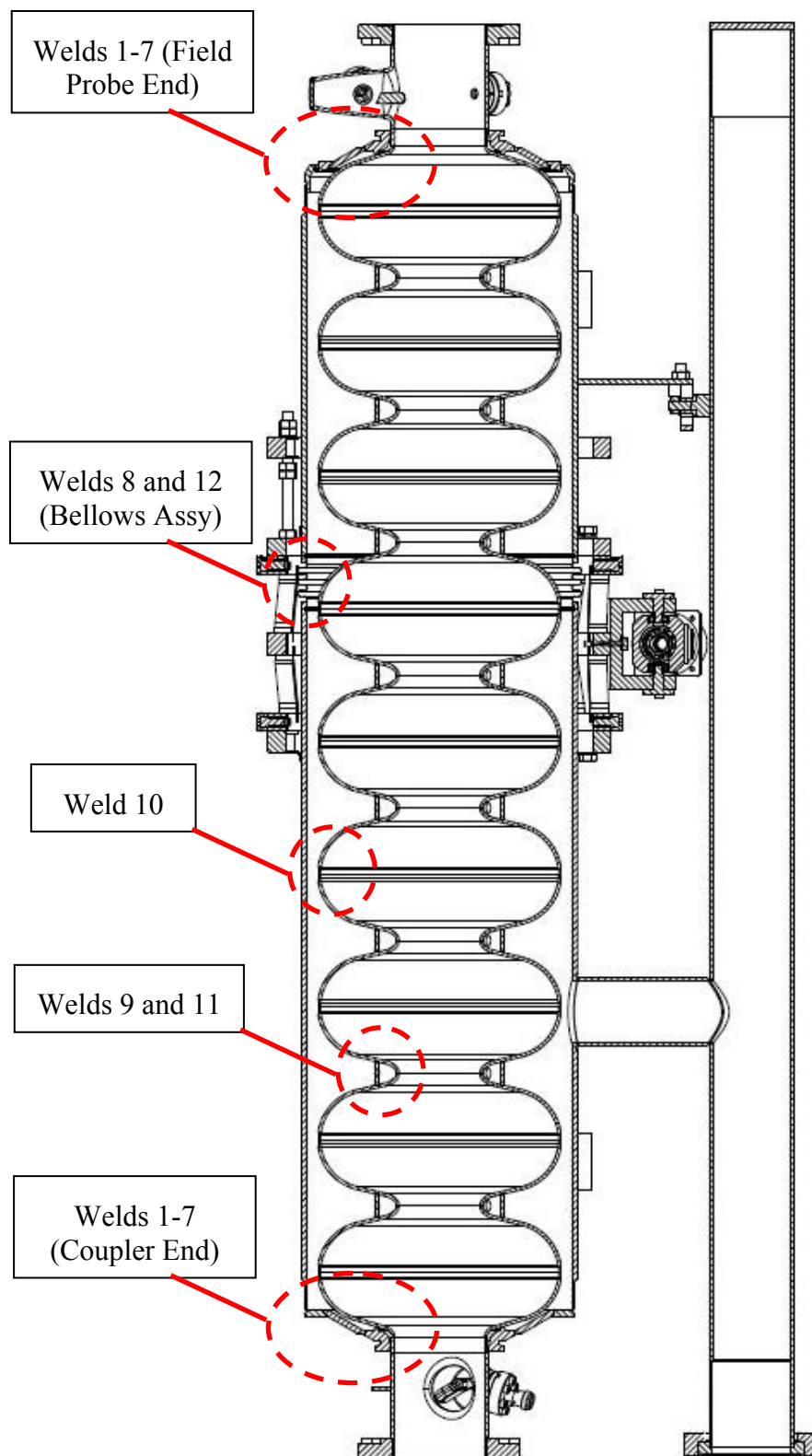


Figure 12. Welds Numbered as in Table 3

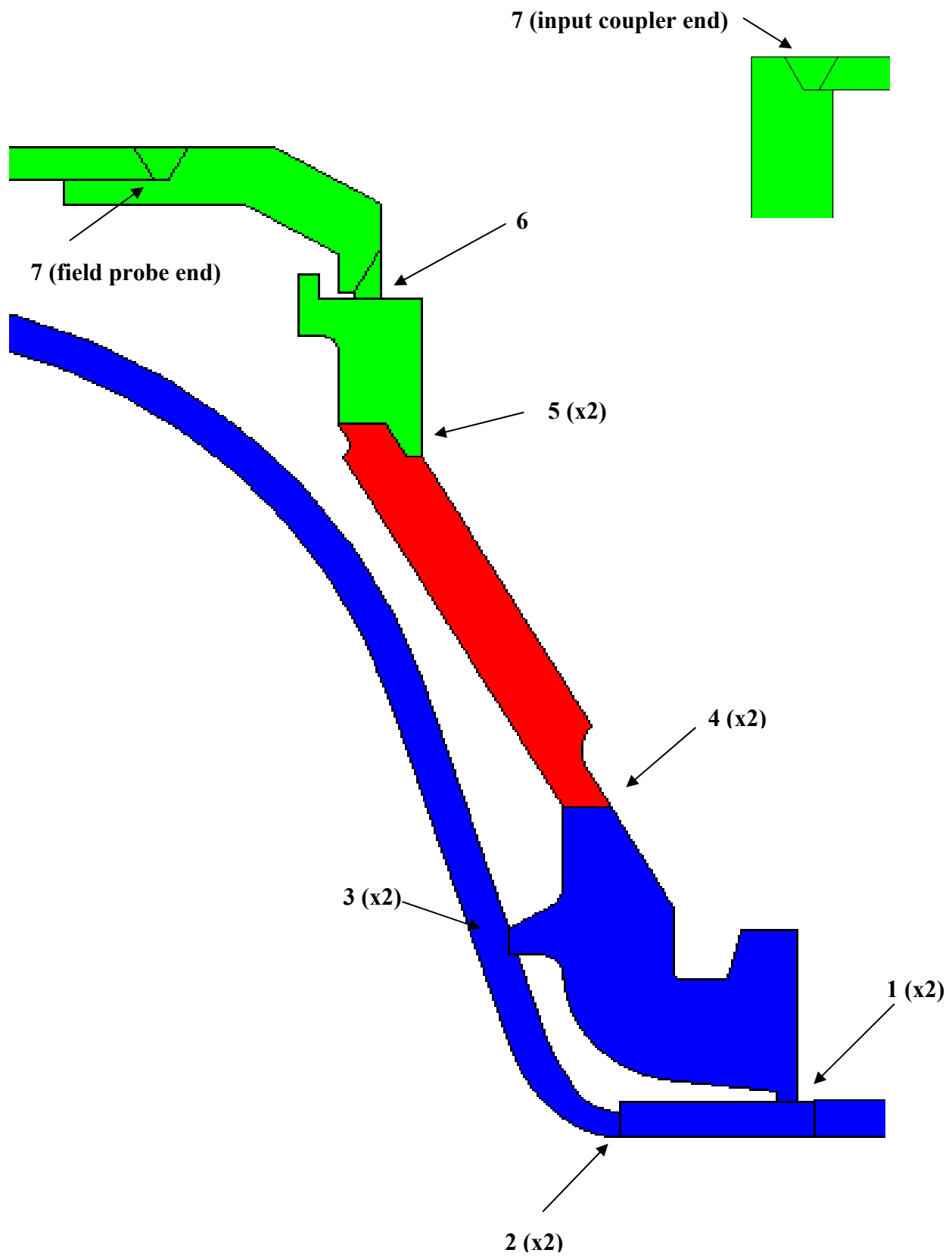


Figure 13. Weld Numbering

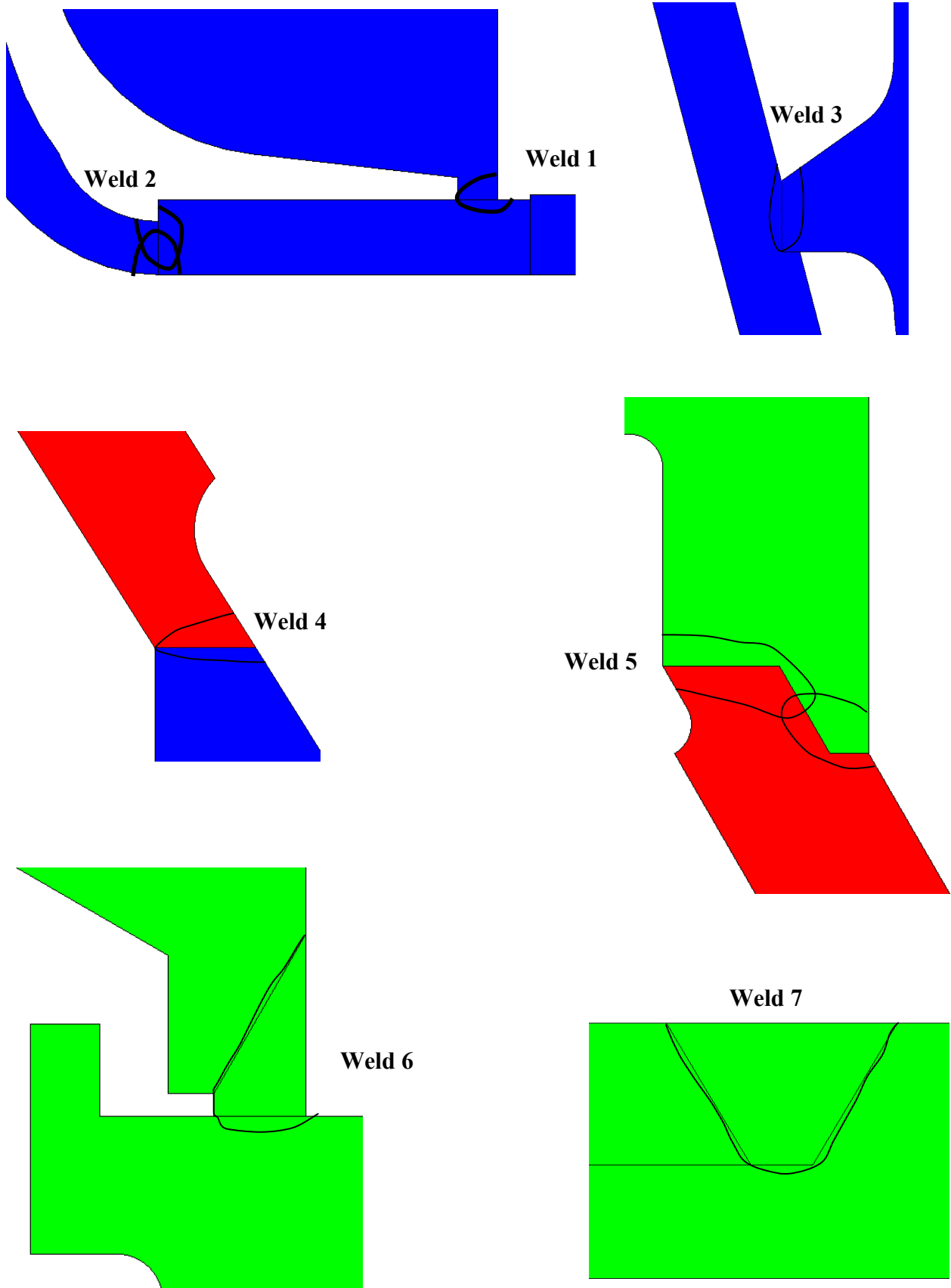


Figure 14. Assumed fusion zones welds 1-7

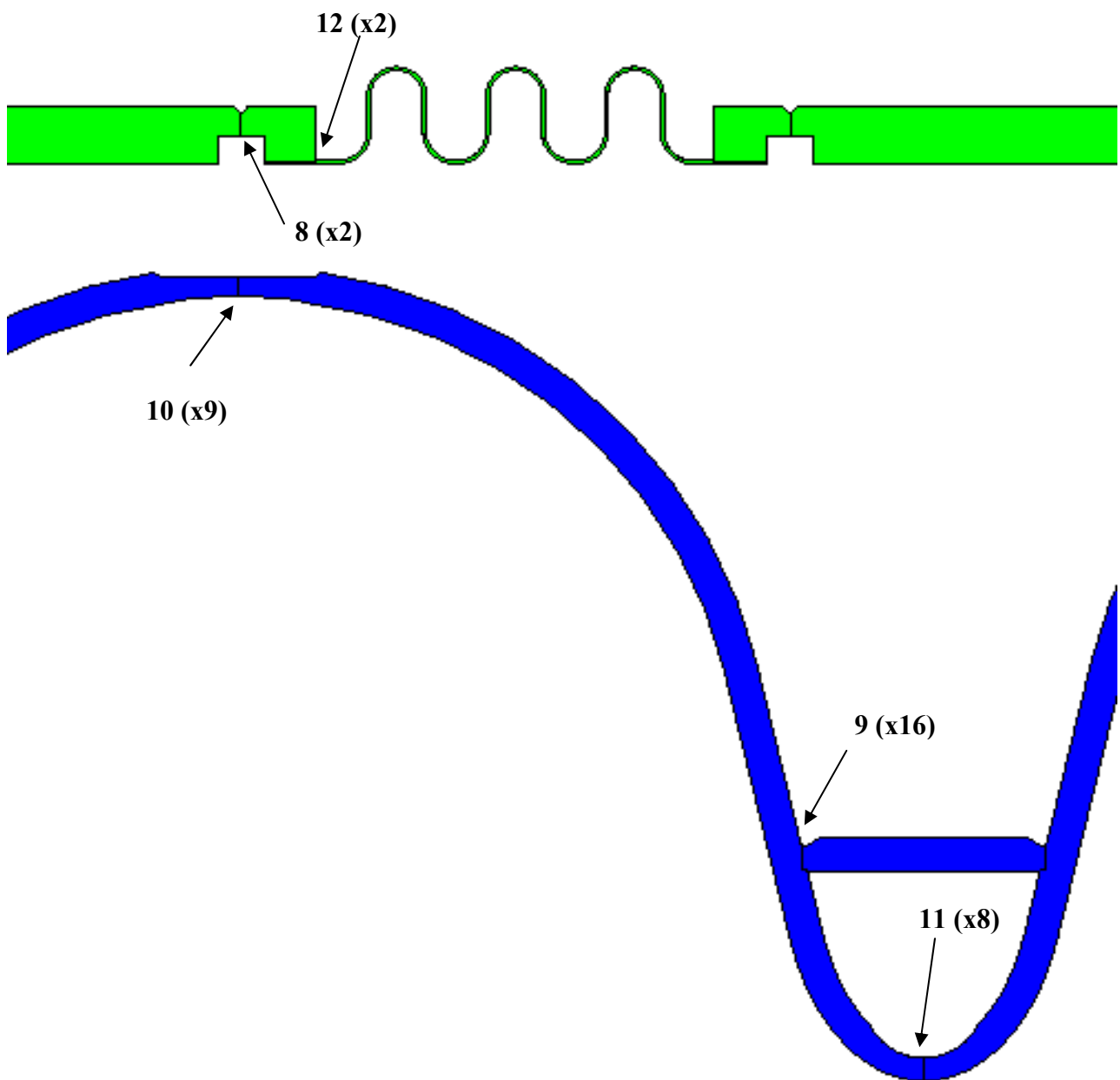


Figure 15. Location of welds 8 - 11

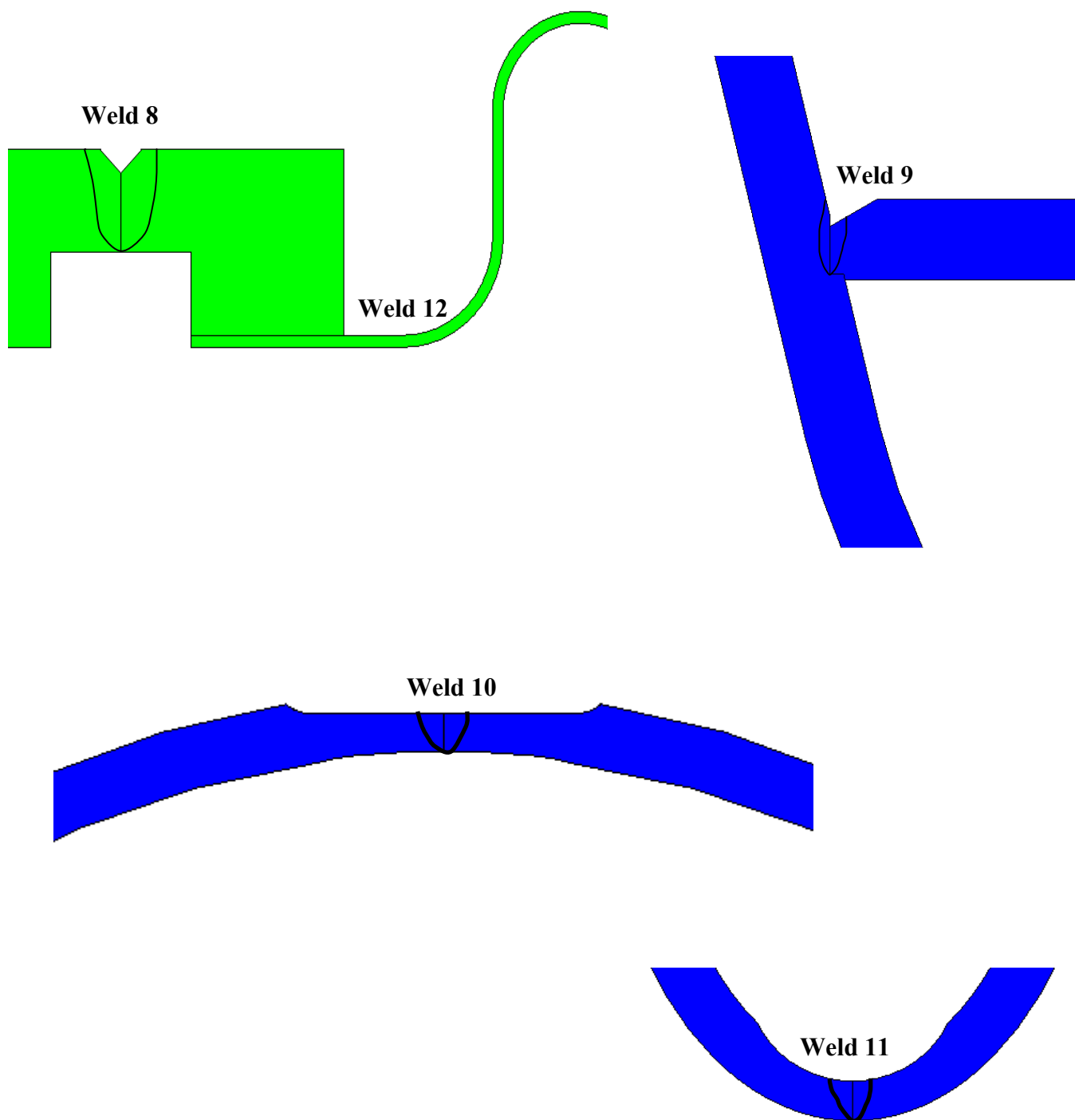


Figure 16. Assumed fusion zones – welds 8 - 11

Material Properties

General

The dressed cavity is constructed of three materials: Pure niobium, Ti-45Nb alloy, and Grade 2 titanium. Of these materials, only Grade 2 Ti is approved by Div. 1 of the Code, and hence has properties and allowable stresses available from Section II, Part D.

The room temperature material properties and allowable stresses for this analysis are identical to those established in the analysis of the 3.9 GHz elliptical cavity⁽⁵⁾. The determination of the allowable stresses was based on Code procedures, and employed a multiplier of 0.8 for additional conservatism.

For the cryogenic temperature load cases, advantage was taken of the increase in yield and ultimate stress for the Nb and Ti. As with the room temperature properties, the properties for these materials at cryogenic temperature were also established by previous work related to the 3.9 GHz cavity⁽⁶⁾.

Room temperature properties were used for the Ti-45Nb alloy for all temperatures, as no low temperature data on that alloy were available. However, it is highly likely that, like the elemental Nb and Ti, substantial increases in strength occur.

Material Properties

The elastic modulus, yield strength, ultimate strength, and integrated thermal contraction from 293 K to 1.88 K are given in Table 5 for each material used in the construction of the cavity.

Table 5 – Material Properties

Material	Property					
	Elastic Modulus (psi)	Yield Strength (psi)		Ultimate Strength (psi)		Integrated Thermal Contraction 293K to 1.88K (in/in)
		293K	1.88 K	293K	1.88 K	
Niobium	1.52E+07	5500	46000	16600	87000	0.0014
55Ti-45Nb	9.00E+06	69000	79000	N/A	N/A	0.0019
Titanium, Gr. 2	1.55E+07	40000	121000	50000	162000	0.0015

Allowable Stresses

The Code-allowable stresses for unwelded materials for the various categories of stress (see “Stress Analysis Approach” of this report) are given in Table 6. The allowed stresses for each stress category are defined in the Code, Division 2, Paragraphs 5.2.2.4(e) and 5.5.6.1(d).

The Code-allowable stresses for welded materials are calculated by multiplying the values of Table 6 by the joint efficiency given in Table 3.

Table 6 – Allowable Stresses for Each Stress Category (Units in PSI)

Material	Stress Category							
	P_m		P_l		$P_l + P_b$		$P_l + P_b + Q$	
	1.88K	293K	1.88K	293K	1.88K	293K	1.88K	293K
Nb	19800	2900	29700	4350	29700	4350	59400	8700
Ti-45Nb	15300	15300	22950	22950	22950	22950	45900	45900
Gr. 2Ti	24500	9680	14520	36750	14520	36750	73500	29040
Note: P_m = primary membrane stress P_l = primary local membrane stress P_b = primary bending stress Q = secondary stress								

The allowable stresses for each stress category in Table 6 are based on the value S, which is the allowable stress of the material at the design temperature. Table 7 shows the values of S for each material at 1.88K and 293K. Note that S includes the de-rating factor of 0.8 of the established allowable stress for a material for an experimental vessel. The de-rating follows the guidelines in FESHM Chapter 5031.

Table 7 – Allowable Stress “S” (Units in MPa [PSI])

Material	Allowable Stress (S)		Established Values	
	1.88°K	293°K	1.88°K	293°K
Nb	137 [19870]	20 [2900]	171 [24801]	25 [3626]
Ti-45Nb	106 [15374]	106 [15374]	133 [19290]	133 [19290]
Gr. 2Ti	169 [24511]	66.4 [9630]	213 [30893]	83 [12038]

Loadings

General

The AES-4 cavity is shown in cross section in Figure 17.

There are three volumes which may be pressurized or evacuated:

1. The LHe volume of the helium vessel
2. The volume outside the cavity typically evacuated for insulation
3. The volume through which the beam passes on the inside of the Nb cavity itself.

The pressures in these volumes are denoted as P_1 , P_2 , and P_3 , respectively.

With regards to pressure, typical operation involves insulating vacuum, beam vacuum, and a pressurized LHe volume. Atypical operation may occur if the insulating or beam vacuums are spoiled, and the LHe space simultaneously evacuated. This reverses the normal operational stress state of the device, producing an external pressure on the Ti shell, and an internal pressure on the Nb cavity; however, this pressure is limited to a maximum differential of 15 psid.

In addition to the pressure loads, the cavity also sees dead weight forces due to gravity which are reacted at the Ti blade tuner flanges, as well thermal contractions when cooled to the operating temperature of 1.88 K, and a strain-controlled extension by the blade tuner after cooldown.

All of these loadings are considered in this analysis. Specific load cases are defined in the next section.

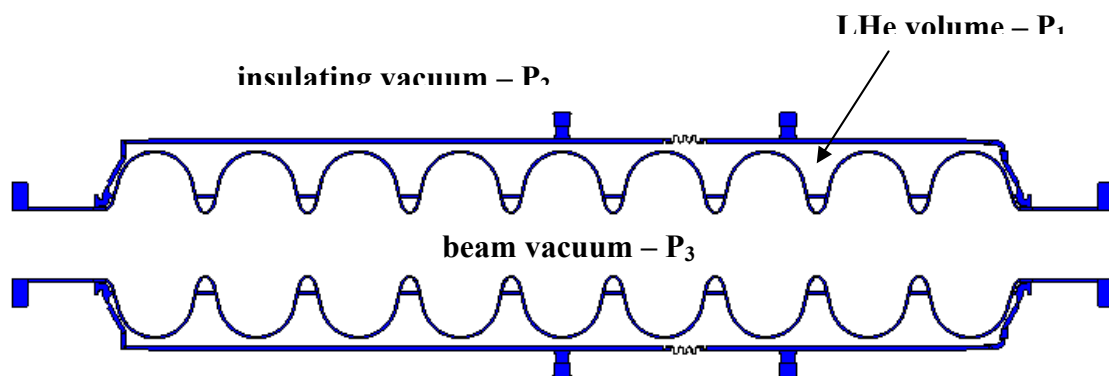


Figure 17. Volumes for Pressure/Vacuum

Load Cases

The cavity is subjected to five basic loads:

1. Gravity
2. LHe liquid head
3. Thermal contraction
4. Tuner extension
5. Pressure (internal and external)

Three of these loads – gravity, liquid head, and pressure – produce both primary and secondary stresses. The remaining loads – thermal contraction and tuner extension – are displacement-controlled loads which produce secondary stresses only. This results in five load cases. These load cases are shown in Table 8, along with the temperatures at which the resulting stresses were assessed, and the stress categories that were applied.

Table 8 – Load Cases

Load Case	Loads	Condition Simulated	Temperature for Stress Assessment	Applicable Stress Categories
1	1. Gravity 2. $P_1=30$ psi 3. $P_2=P_3=0$	Warm Pressurization	293 K	$P_m, P_1, P_1 + Q$
2	1. Gravity 2. LHe liquid head 3. $P_1=60$ psi 4. $P_2=P_3=0$	Cold operation, full, maximum pressure – no thermal contraction	1.88 K	$P_m, P_1, P_1 + Q$
3	1. Cool down to 1.88 K 2. Tuner extension of 0.083 in	Cool down and tuner extension, no primary loads	1.88 K	Q
4	1. Gravity 2. LHe liquid head 3. Cool down to 1.88 K 4. Tuner extension 5. $P_1=60$ psi 6. $P_2=P_3=0$	Cold operation, full LHe inventory, maximum pressure – primary and secondary loads	1.88 K	Q
5	1. Gravity 2. $P_1=0$ 3. $P_2=P_3=15$ psi	Insulating and beam vacuum upset, helium volume evacuated	293 K	$P_m, P_1, P_1 + Q$

Stress Analysis Approach

The goal of the analysis is to qualify the vessel to the greatest extent possible in accordance with the rules of the Code, Section VIII, Div. 1. This Division of the Code provides rules covering many cases; however, there are features of this cavity and its loadings for which the Division has no rules. This does not mean that the vessel cannot be qualified by Div. 1, since Div. 1 explicitly acknowledges the fact that it does not prevent formulaic procedures (“rules”) covering all design possibilities. From U-2(g)

“This Division of Section VIII does not contain rules to cover all details of design and construction. Where complete details are not given, it is intended that the Manufacturer, subject to the acceptance of the Inspector, shall provide details of design and construction which will be as safe as those provided by the rules of this Division.”

Applying Division I Rules to the Cavity

Division 1 rules relate to both geometries and loads. For either, there are few rules applicable to the features of the cavity.

The only components of the cavity which can be designed for internal and external pressure by the rules of Div. 1 are the Ti shells and the Ti bellows. In the Ti shell, there are two penetrations for connection of externals for which the required reinforcement can also be determined by Code rules.

The conical heads have half-apex angles exceeding 30 degrees, and no knuckles; Div. 1, Appendix 1, 1-5(g) states that their geometry falls under U-2(g).

The Nb cavity itself resembles an expansion joint, but does not conform to the geometries covered in Div. 1, Appendix 26. Therefore, U-2(g) is again applied.

UG-22(h) states that “temperature gradients and differential thermal contractions” are to be considered in vessel design, but provides no rules to cover the cavity. In this analysis, all thermal contraction effects are addressed under U-2(g).

The cavity is also subjected to a controlled displacement loading from blade tuner. There are no rules in Div. 1 covering such a loading, so U-2(g) is applied.

The applicable Code rules for each component are summarized in Table 9.

Table 9 - Applicable Code, Div. 1 Rules for 1.3 GHz Cavity

Component	Loading		
	Internal/External Pressure	Thermal Contraction	Tuner Extension
Nb cavity	U-2(g)	U-2(g)	U-2(g)
Conical heads	U-2(g)	U-2(g)	U-2(g)
Ti shells	UG-27/UG-28	U-2(g)	U-2(g)
Ti bellows	Appendix 26	U-2(g)	U-2(g)

Applying U-2(g)

U-2(g) is satisfied in this analysis by the application of the design-by-analysis rules of the Code, Section VIII, Div. 2, Part 5.

These rules provide protection against plastic collapse, local failure, buckling, fatigue, and ratcheting. The specific sections of Part 5 applied here are:

1. Plastic collapse – satisfied by an elastic stress analysis performed according to 5.2.2.
2. Ratcheting - satisfied by an elastic stress analysis performed according to 5.5.6.1
3. Local failure – satisfied by an elastic stress analysis performed according to 5.3.2
4. Buckling – satisfied by a linear buckling analysis performed according to 5.4.1.2(a).
5. Fatigue assessment – the need for a fatigue analysis is assessed according to 5.5.2.3

In general, an elastic stress analysis begins by establishing stress classification lines (SCLs) through critical sections in the structures according to the procedures of Part 5, Annex 5A. The stresses along these lines are then calculated (in this case, by an FEA), and “linearized” to produce statically equivalent membrane stress and bending stress components. The allowable stress for each component depends on the category of the stress. This category (or classification) depends on the location of the SCL in the structure, and the origin of the load. Stresses near discontinuities have higher allowables to reflect their ability to redistribute small amounts of plasticity into surrounding elastic material. Stresses produced solely by strain-controlled loads (e.g., thermal contractions and blade tuner extension) are given higher allowables regardless of their location in the structure.

Allowable stresses are expressed in terms of multiples of S , which is the allowable general primary membrane stress. The values of S used in this analysis are given in Table 6.

Division 1 Calculations by Rule

Ti Cylindrical Shells

Thickness for Internal Pressure

The minimum thickness required for the Ti cylindrical shells under internal pressure can be calculated from UG-27(c)(1):

$$t = \frac{PR}{SE - 0.6P}$$

where: t = required thickness

P = pressure = 30 psi (warm), 60 psi (cold)

R = inside radius of shell = 4.53 in

E = efficiency of seam weld (TIG, one-sided butt weld, no radiography) = 0.6

S = maximum allowable membrane stress = 9680 psi (warm), 24500 psi (cold)

Substituting, the minimum required thickness when warm and pressurized to 30 psi is 0.023 in. The minimum required thickness when cold and pressurized to 60 psi is 0.018 in. The actual minimum thickness of the shells is 0.098 in (2.5 mm). Therefore, the Ti cylindrical shells meet the minimum thickness requirements of UG-27 for internal pressure.

Thickness for External Pressure (Buckling)

The minimum thickness required for the Ti cylindrical shells under external pressure can be calculated from UG-28(c). This procedure uses charts found in the Code, Section II, Part D. These charts are based on the geometric and material characteristics of the vessel.

Using: L = 20 in

D_o = 9.25 in

t = 0.055 in

Then: L/D = 2.2

D_o/t = 168

From the Code, Section II, Part D, Subpart 3, Figure G, the factor A is 0.00027. From Figure NPT-2 (the material chart for Grade 2 Ti), the factor B is 2100.

The allowable pressure is then

$$P = \frac{4B}{3(D_o/t)}$$

Substituting give P = 16.6 psi. This is approximately equal to the 15 psi maximum external vessel for which the vessel must be qualified.

The actual minimum thickness of the Ti shell is 0.1 inches. This occurs near the ends, and it is unlikely that the collapse is well predicted by this thickness, due to its short length, and proximity to the conical head, which will tend to stiffen the region. If we assume, however, that the entire shell is this thickness, and repeat the calculations above, the allowable external pressure is 72 psi.

If we assume the collapse is better predicted by the predominate thickness of 0.2 inches, then the factor $A = 0.0019$, the factor $B = 21000$, and the allowable external pressure is 345 psi.

In any case, the required minimum thickness of 0.055 inches is less than the actual minimum thickness anywhere on the Ti cylindrical shell. Therefore, the Ti shell satisfies the Code requirement for external pressure.

Penetrations

The Ti cylindrical shell contains two penetrations. These are shown in Figure 18. The largest of these penetrations is 2.16 inches (54.8 mm) in diameter.

From UG-36(c)(3):

“Openings in vessels not subject to rapid fluctuations in pressure do not require reinforcement other than inherent in the construction under the following conditions: welded, brazed, and flued connections meeting applicable rules and with a finished opening not larger than 3.5 in diameter – in vessel shells or heads with a required minimum thickness of 3/8 inch or less.”

The minimum required thickness of the shell is largest for the case of 30 psi pressurization, warm. This thickness (calculated in 7.1.1) is 0.023 in. This is less than 3/8 in. Therefore, since the penetrations are smaller than 3.5 in. in diameter, no additional reinforcement is required for either penetration in the Ti shells.

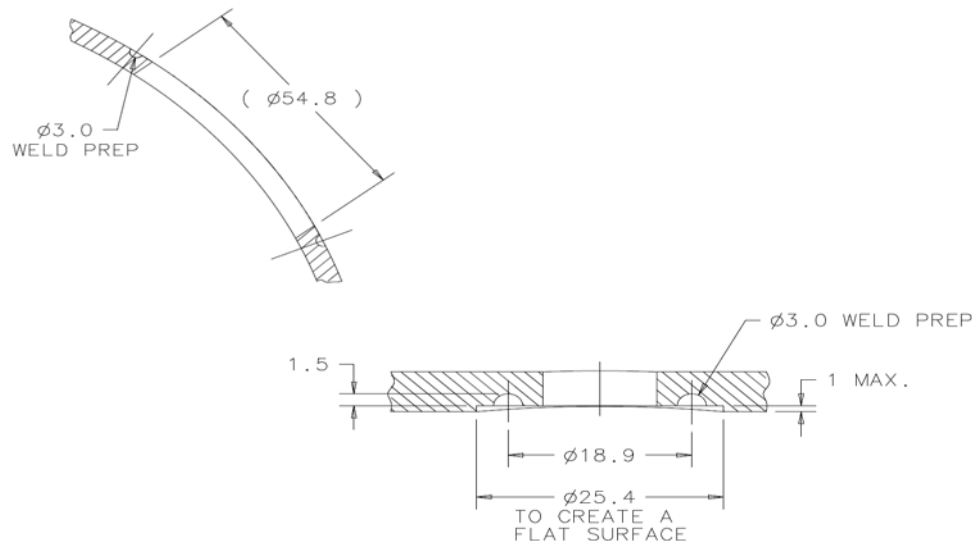


Figure 18. Penetrations in the Ti Shell

Ti Bellows

The design of metallic expansion joints (e.g., bellows) is addressed by Appendix 26 of the Code. The formulas permit calculation of internal and external pressure limits. In a bellows, the pressure may be limited not only by stress, but by squirm (internal pressure), and collapse (external pressure.)

The bellows with an internal MAWP of 4.0-bar (58-psia) at 1.88 K follows the rules of Appendix 26. Since the analysis is independent of temperature and the room temperature allowable stress (which is more conservative) is used, the bellows analysis for the 4.0-bar is considered. The external MAWP at all temperatures is 408 psi. The required external MAWP is 1.0-bar (14.5-psia).

Table 10 defines the stresses that are examined in the bellows analysis. Table 11 summarizes how the calculated or actual stresses comply with the allowed stresses.

The details of the Appendix 26 calculations are presented in Appendix C.

Table 10 – Definition of Stresses, Coefficients in the Bellows Analysis, following the Code, Division 1, Appendix 26.

		Units
S1	Circumferential membrane stress in bellows tangent, due to pressure P	psi
S2e	Circumferential membrane stress due to pressure P for end convolutions	psi
S2i	Circumferential membrane stress due to pressure P for end convolutions	psi
S11	Circumferential membrane stress due to pressure P for the collar	psi
S3	Meridional membrane stress due to pressure P	psi
S4	Meridional bending stress due to pressure P	psi
P	Design pressure	psi
S	Allowable stress of bellows material	psi
Cwc	Weld joint efficiency of collar to bellows (no radiography, single butt weld)	--
Sc	Allowable stress of collar material	psi
Kf	Coefficient for formed bellows	--
Psc	Allowable internal pressure to avoid column instability	psi
Psi	Allowable internal pressure based on in-plane instability	psi
Pa	Allowable external pressure based on instability	psi

Table 11 – Complying with Appendix 26 Rules for Internal Pressure of 4.0-bar (58-psia)

Calculated or Actual Value	Allowed Value	Requirement	Applicable Paragraph
S1 = 2738 psi	S = 9680 psi	$S1 < S$	26-6.3.1
S11 = 2859 psi	$Cwc \cdot Sc = 5808$	$S11 < Cwc \cdot Sc$	26-6.3.2
S2e = 4276 psi	S = 9680 psi	$S2e < S$	26-6.3.3(a)(1)
S2i = 9379 psi	S = 9680 psi	$S2i < S$	26-6.3.3(a)(2)
$S3 + S4 = 14590$ psi	$Kf \cdot S = 29040$ psi	$(S3 + S4) < (Kf \cdot S)$	26-6.3.3(d)
P = 58 psi	Psc = 13300 psi	$P \leq Psc$	26-6.4.1
P = 58 psi	Psi = 212 psi	$P \leq Psi$	26-6.4.2
External pressure = 14.5 psia	Pa = 408 psi	Ext. pressure < Pa	26-6.5

Fatigue Analysis for Titanium Bellows

The equations in the Code for fatigue analysis of a bellows are not valid for titanium. The manufacturer of the titanium bellows for the helium vessel provided design calculations following the Standards of the Expansion Joint Manufacturers Association ⁽⁷⁾. The allowable fatigue life is calculated with the equation

$$N_c = \left(\frac{c}{S_T - b} \right)^a$$

where a, b, and c are material and manufacturing constants. The manufacturer uses the same material and manufacturing constants as what EJMA uses for austenitic stainless steel. In addition, the manufacturer includes a safety factor of two in their calculation of the allowable number of cycles since the titanium bellows is a custom-made project. The manufacturer calculated an allowable number of cycles to be $N_c = 764,058$.

The slow tuner system has the capability of increasing the vessel length less than 2.0-mm after each cooldown. The bellows extension will occur 200 times over the lifetime of the vessel. This is far less than the allowable number of cycles, so the bellows is designed well within the limits of fatigue failure.

Copies of the Mathcad analysis and the manufacturer's calculations are available online at

<http://ilc-dms.fnal.gov/Workgroups/CryomoduleDocumentation/AES004/ti-bellows-calcs/>

Finite Element Model

A 3-d finite element half model was created in ANSYS. Elements were 10-node tetrahedra, and 20-node hexahedra. Material behavior was linear elastic.

The blade tuner, which mounts between the two Ti flanges, is very rigid. Axial constraint of the helium vessel was therefore simulated by constraining the outer surface of each flange in the Z (axial) direction. This constraint places the line of action at a maximum distance from the shell, producing the maximum possible moment on the welds between the Ti blade tuner flanges and the shell.

For the cool down loading, the distance between the Ti flanges was assumed to close by an amount equivalent to the shrinkage of a rigid stainless steel mass spanning the flanges.

The constraint against gravity is simulated by fixing the flange outer surface nodes at 180 degrees in the Y (vertical) direction.

The finite element model is shown in Figure 19. Figure 20 shows mesh detail at various locations within the model.

The complete model was used to demonstrate satisfaction of the plastic collapse, ratcheting, and local failure criteria. Subsets of the model were also used to address the linear buckling of the Nb cavity and conical head.

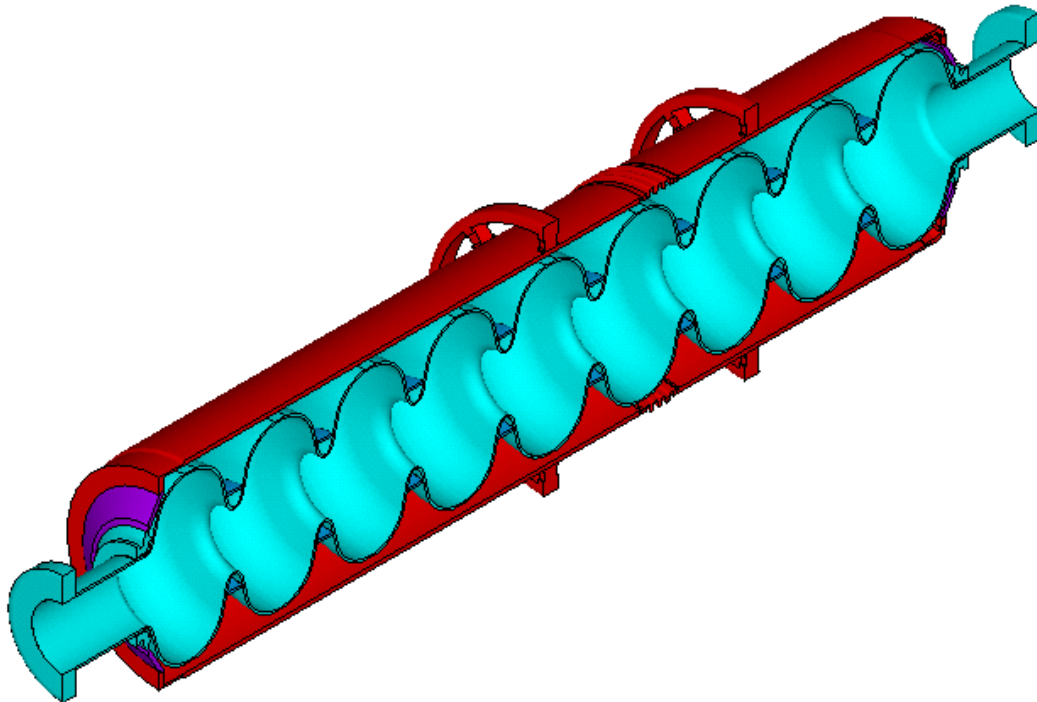


Figure 19. The Finite Element Model

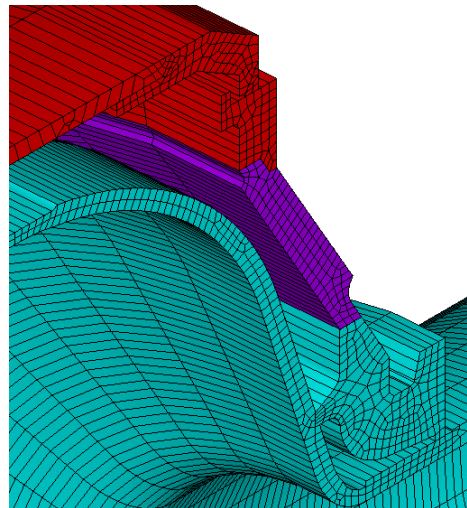
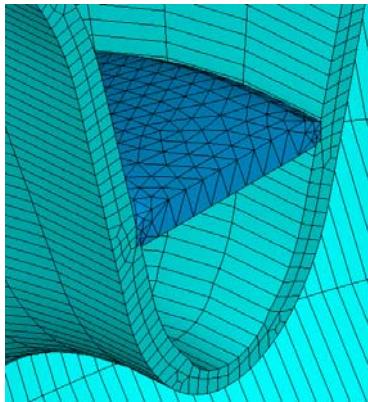
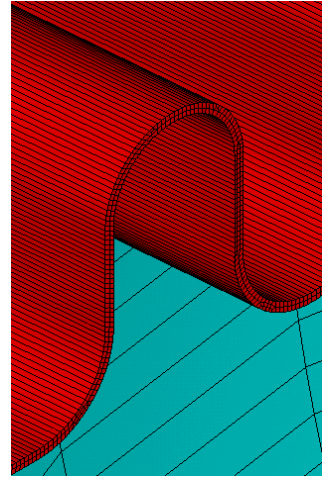
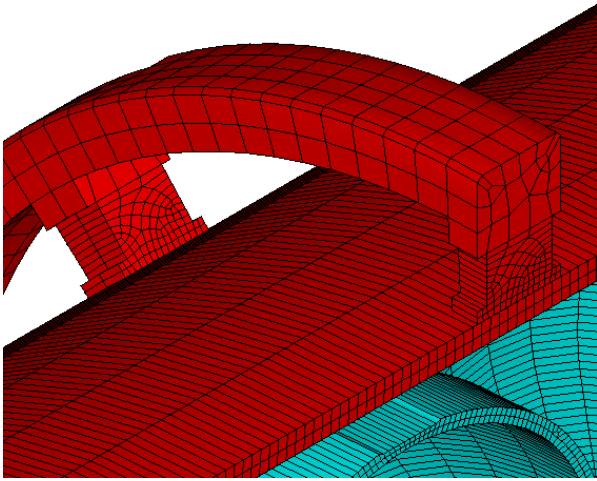


Figure 20. Mesh Details

Stress Analysis Results

General

The complete finite element model was run for the five load cases. Stress classification lines, shown in Figure 21, were established through the critical sections of the structure. The stresses along these lines were linearized with ANSYS, and separated into membrane and bending components. The linearized stresses (expressed in terms of von Mises equivalent stress, as required by 5.2.2.1(b)) are categorized according to the Code, Div. 2, Part 5, 5.2.2.2 into primary and secondary stresses.

The primary and secondary stresses along each SCL for each of the five load cases are given in Tables 12-16. Where more than one weld of a given number is present (as indicated in Figs 13 and 15) the weld with the highest stresses was assessed.

The stresses from Tables 12-16 are used to demonstrate satisfaction of two of the criteria listed in 5.2 of this report: Protection against plastic collapse, and protection against ratcheting. Demonstrating protection against local failure employs the complete model, but requires the extraction of different quantities.

Note: The required minimum thicknesses of the Ti shells for internal and external pressure are calculated by Div. 1 rules in section 7.0 of this report. Therefore, no SCLs addressing the Ti shell thickness far from welds or other discontinuities are established here. See the Appendix B for verification that the FEA produces the correct hoop stress in the Ti shell.

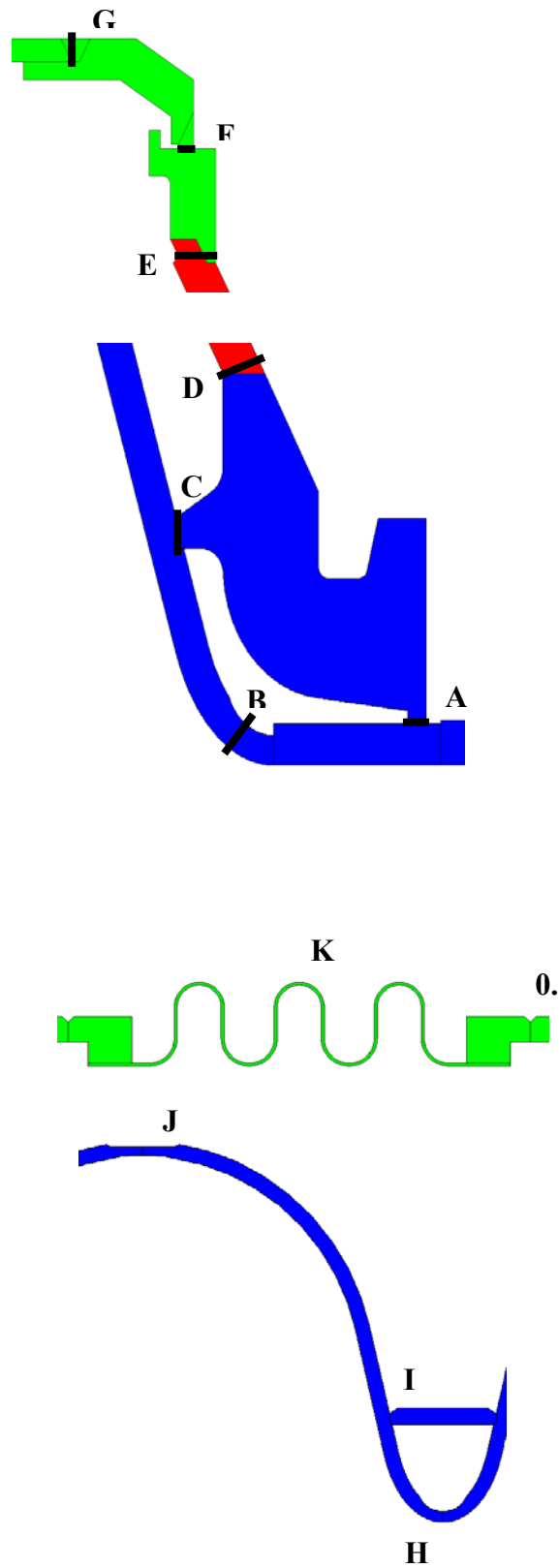


Figure 21. Stress classification lines

Table 12. Load Case 1 – Stress Results

Material	SCL	Weld #	Membrane Stress (psi)	Classification	Allowable Stress (psi)	Ratio S_{fe}/S_a
Nb weld	A	1	165	P_m	1740	0.09
Nb weld	B	2	198	P_l	3045	0.06
Nb weld	C	3	1655	P_m	1740	0.95
Nb weld to NbTi	D	4	426	P_m	1740	0.24
Ti weld to NbTi	E	5	255	P_m	6775	0.04
Ti weld	F	6	711	P_m	5808	0.12
Ti weld	G	7	1130	P_m	9680	0.12
Nb weld	H	11	643	P_m	1740	0.37
Nb weld	I	9	932	P_m	1740	0.53
Nb weld	J	10	519	P_m	1740	0.30
Ti	K	-	4079	P_m	9680	0.42
Ti weld	L	12	2112	P_l	8712	0.24
Ti weld	M	8	914	P_m	5808	0.15
Material	SCL	Weld #	Membrane + Bending	Classification	Allowable Stress	Ratio S_{fe}/S_a
Nb weld	A	1	569	P_m+P_b	2610	0.22
Nb weld	B	2	724	P_l+Q	6090	0.12
Nb weld	C	3	2817	Q	5220	0.54
Nb weld to NbTi	D	4	1507	P_m+P_b	2610	0.58
Ti weld to NbTi	E	5	1122	P_m+P_b	10160	0.11
Ti weld	F	6	1552	P_m+P_b	8712	0.18
Ti weld	G	7	3985	P_m+P_b	14520	0.27
Nb weld	H	11	661	P_m+P_b	2610	0.25
Nb weld	I	9	2090	Q	5220	0.40
Nb weld	J	10	715	P_m+P_b	2610	0.27
Ti	K	-	9876	P_m+P_b	14520	0.68
Ti weld	L	12	9909	P_l+Q	21780	0.45
Ti weld	M	8	962	P_m+P_b	8712	0.11

Table 13. Load Case 2 – Stress Results

Material	SCL	Weld #	Membrane Stress (psi)	Classification	Allowable Stress (psi)	Ratio S_{fe}/S_a
Nb weld	A	1	287	P_m	11880	0.02
Nb weld	B	2	434	P_l	20800	0.02
Nb weld	C	3	2970	P_m	11880	0.25
Nb weld to NbTi	D	4	882	P_m	9170	0.1
Ti weld to NbTi	E	5	545	P_m	10700	0.05
Ti weld	F	6	1490	P_m	14700	0.10
Ti weld	G	7	2341	P_m	24500	0.09
Nb weld	H	11	1283	P_m	11880	0.11
Nb weld	I	9	1707	P_m	11880	0.14
Nb weld	J	10	1036	P_m	11880	0.09
Ti	K	-	8204	P_m	24500	0.33
Ti weld	L	12	5246	P_l	22050	0.24
Ti weld	M	8	1831	P_m	14700	0.12

Material	SCL	Weld #	Membrane + Bending (psi)	Classification	Allowable Stress (psi)	Ratio S_{fe}/S_a
Nb weld	A	1	1148	P_m+P_b	17820	0.06
Nb weld	B	2	1432	P_l+Q	41580	0.03
Nb weld	C	3	5222	Q	35640	0.15
Nb weld to NbTi	D	4	3006	P_m+P_b	1375	0.22
Ti weld to NbTi	E	5	2300	P_m+P_b	16060	0.14
Ti weld	F	6	3241	P_m+P_b	22050	0.15
Ti weld	G	7	8166	P_m+P_b	36750	0.22
Nb weld	H	11	1319	P_m+P_b	17820	0.07
Nb weld	I	9	3719	Q	35640	0.10
Nb weld	J	10	1396	P_m+P_b	17820	0.08
Ti	K	-	19655	P_m+P_b	36750	0.53
Ti weld	L	12	16403	P_l+Q	44100	0.37
Ti weld	M	8	1923	P_m+P_b	22050	0.09

Table 14. Load Case 3 – Stress Results

Material	SCL	Weld #	Membrane Stress (psi)	Classification	Allowable Stress (psi)	Ratio S_{fe}/S_a
Nb weld	A	1	821	N/A	N/A	N/A
Nb weld	B	2	109	N/A	N/A	N/A
Nb weld	C	3	3386	N/A	N/A	N/A
Nb weld to NbTi	D	4	3560	N/A	N/A	N/A
Ti weld to NbTi	E	5	1252	N/A	N/A	N/A
Ti weld	F	6	961	N/A	N/A	N/A
Ti weld	G	7	1072	N/A	N/A	N/A
Nb weld	H	11	1974	N/A	N/A	N/A
Nb weld	I	9	5055	N/A	N/A	N/A
Nb weld	J	10	1287	N/A	N/A	N/A
Ti	K	-	5068	N/A	N/A	N/A
Ti weld	L	12	1054	N/A	N/A	N/A
Ti weld	M	8	292	N/A	N/A	N/A

Material	SCL	Weld #	Membrane + Bending (psi)	Classification	Allowable Stress (psi)	Ratio S_{fe}/S_a
Nb weld	A	1	1554	Q	35640	0.04
Nb weld	B	2	639	Q	41580	0.02
Nb weld	C	3	6395	Q	35640	0.18
Nb weld to NbTi	D	4	5682	Q	27535	0.20
Ti weld to NbTi	E	5	4132	Q	32130	0.13
Ti weld	F	6	2276	Q	44100	0.05
Ti weld	G	7	4217	Q	73500	0.06
Nb weld	H	11	2796	Q	35640	0.08
Nb weld	I	9	12846	Q	35640	0.36
Nb weld	J	10	1634	Q	35640	0.05
Ti	K	-	31128	Q	73500	0.42
Ti weld	L	12	1324	Q	44100	0.03
Ti weld	M	8	1073	Q	44100	0.02

Table 15. Load Case 4 – Stress Results

Material	SCL	Weld #	Membrane Stress (psi)	Classification	Allowable Stress (psi)	Ratio S_{fe}/S_a
Nb weld	A	1	789	N/A	N/A	N/A
Nb weld	B	2	385	N/A	N/A	N/A
Nb weld	C	3	5465	N/A	N/A	N/A
Nb weld to NbTi	D	4	3573	N/A	N/A	N/A
Ti weld to NbTi	E	5	938	N/A	N/A	N/A
Ti weld	F	6	729	N/A	N/A	N/A
Ti weld	G	7	1337	N/A	N/A	N/A
Nb weld	H	11	728	N/A	N/A	N/A
Nb weld	I	9	6049	N/A	N/A	N/A
Nb weld	J	10	1646	N/A	N/A	N/A
Ti	K	-	3139	N/A	N/A	N/A
Ti weld	L	12	5926	N/A	N/A	N/A
Ti weld	M	8	2078	N/A	N/A	N/A

Material	SCL	Weld #	Membrane + Bending (psi)	Classification	Allowable Stress (psi)	Ratio S_{fe}/S_a
Nb weld	A	1	1160	Q	35640	0.03
Nb weld	B	2	850	Q	41580	0.02
Nb weld	C	3	6649	Q	35640	0.19
Nb weld to NbTi	D	4	4129	Q	27535	0.15
Ti weld to NbTi	E	5	3868	Q	32130	0.12
Ti weld	F	6	1194	Q	44100	0.03
Ti weld	G	7	4001	Q	73500	0.05
Nb weld	H	11	2125	Q	35640	0.06
Nb weld	I	9	14362	Q	35640	0.40
Nb weld	J	10	1696	Q	35640	0.05
Ti	K	-	47590	Q	73500	0.65
Ti weld	L	12	16744	Q	44100	0.38
Ti weld	M	8	2563	Q	44100	0.06

Table 16. Load Case 5 – Stress Results

Material	SCL	Weld #	Membrane (psi)	Classification	Allowable Stress (psi)	Ratio S_{fe}/S_a
Nb weld	A	1	83	P_m	11880	0.01
Nb	B	2	167	P_l	29700	0.01
Nb weld	C	3	457	P_m	11880	0.04
Nb weld to NbTi	D	4	272	P_m	7867	0.035
Ti weld to NbTi	E	5	171	P_m	9180	0.02
Ti weld	F	6	402	P_m	14700	0.03
Ti weld	G	7	660	P_m	24500	0.03
Nb weld	H	11	326	P_m	11880	0.03
Nb weld	I	9	410	P_m	11880	0.03
Nb weld	J	10	263	P_m	11880	0.02
Ti	K	-	2111	P_m	24500	0.09
Ti weld	L	12	980	P_l	22050	0.04
Ti weld	M	8	461	P_m	14700	0.03

Material	SCL	Weld #	Membrane + Bending (psi)	Classification	Allowable Stress (psi)	Ratio S_{fe}/S_a
Nb weld	A	1	256	P_m+P_b	17820	0.01
Nb	B	2	351	P_l+Q	59400	0.01
Nb weld	C	3	820	Q	35640	0.02
Nb weld to NbTi	D	4	728	P_m+P_b	11800	0.06
Ti weld to NbTi	E	5	630	P_m+P_b	13770	0.05
Ti weld	F	6	852	P_m+P_b	22050	0.04
Ti weld	G	7	2226	P_m+P_b	36750	0.06
Nb weld	H	11	335	P_m+P_b	17820	0.02
Nb weld	I	9	700	Q	35640	0.02
Nb weld	J	10	316	P_m+P_b	17820	0.02
Ti	K	-	4782	P_m+P_b	36750	0.13
Ti weld	L	12	4753	P_l+Q	44100	0.11
Ti weld	M	8	481	P_m+P_b	22050	0.02

Collapse Pressure

The criterion for protection against plastic collapse is given in Div. 2, 5.2.2. The criterion is applied to load cases in which primary (load-controlled) stresses are produced. For this analysis, this is Load Case 1, Load Case 2, and Load Case 5.

The following stress limits must be met (per 5.2.2.4(e)):

1. P_m = primary membrane stress $\leq S$
2. P_l = primary local membrane stress $\leq 1.5 S$
3. $P_l + P_b$ = primary local membrane + primary bending $\leq 1.5 S$

where S = maximum allowable primary membrane stress.

In this work, the P_l classification is limited to SCL B (weld 2), and SCL L (weld 12). All other membrane stresses extracted on the SCLs are classified as the more conservative P_m , which is then used in place of P_l in 3) above.

Examining Tables 12, 13, and 16, it is found that the closest approach to the limiting stress for any load case occurs at SCL C (weld #3, the weld between the end disk flange and the end cell of the Nb cavity) in Load Case 1, where the primary membrane stress of 1655 psi compares to an allowable of 1740 psi. This weld is unusual in that it is intermittent azimuthally (an effect modeled in the analysis), which tends to concentrate the stresses near the middle of a line of weld. Also, the end disk flange is intended to stiffen the iris against axial motion only through the membrane stress in the weld, which means that any bending stresses are self-limiting and small rotations will satisfy the conditions that produce them. For this reason, the membrane stresses in this weld are classified as primary, while the bending stresses are secondary.

Ratcheting

Protection against ratcheting, the progressive distortion of a component under repeated loadings, is provided by meeting the requirements of Div. 2, 5.5.6. Specifically, the following limit must be satisfied:

$$\Delta S_{n,k} \leq S_{PS}$$

where: $\Delta S_{n,k}$ = primary plus secondary equivalent stress range

S_{PS} = allowable limit on primary plus secondary stress range

The stress range $\Delta S_{n,k}$ must take into account stress reversals; however, there are no stress reversals in normal operation of the cavity, so for this analysis $\Delta S_{n,k}$ is equal to the primary plus secondary stresses given in Tables 12-16.

Examination of the tables shows that the cavity satisfies the ratcheting criterion; the closest approach to the allowable primary plus secondary stress range limit occurs for Load Case 4 (gravity + liquid head + 60 psi + blade tuner extension + cool down) in the Ti bellows. For this load case, the calculated primary plus secondary stress range reaches 65% of the allowable.

Local Failure

The criterion for protection against local failure is given in Div. 2, 5.3.2:

$$\sigma_1 + \sigma_2 + \sigma_3 \leq 4S$$

where σ_1 , σ_2 , σ_3 are the principal stresses at any point in the structure, and S is the maximum allowable primary membrane stress (see Table 5), multiplied by a joint efficiency factor if applicable.

This criterion is assumed to be satisfied if the sum of the principal stresses calculated at every element centroid in the model meet the stress limit for the material.

Table 17 lists the maximum allowable sum of principal stresses for each material at each load case. These values are four times the full values given for maximum primary membrane stress times a joint efficiency for a Type 3 butt weld of 0.6. For those locations which are not near a joint, or are near one of the Type 2 butt weld joints, this is conservative.

The results for each material and each load case are given in Tables 18-20. The closest approach to the allowable limit occurs in the iris support ring welds for Load Case 1 (warm, 30 psi internal pressure), which reaches 0.93 of the allowable. For all other materials/load cases, the principal stress sum lies well below the allowable.

Table 17 – Maximum Allowable Sum of Principal Stresses

Maximum Allowable Sum of Principal Stresses (psi)			
Load Case (Temp)	Nb	TiNb	Ti
1 (293 K)	6960	36720	23232
2 (1.88 K)	47520	36720	58800
3 (1.88 K)	47520	36720	58800
4 (1.88 K)	47520	36720	58800
5 (293 K)	6960	36720	23232

Table 18 – Local Failure Criterion - Niobium

Load Case	Maximum Principal Stress Sum (psi)	Allowable Stress (psi)	Location	Ratio S_{fe}/S_a
1	6462	6960	weld #3	0.93
2	11182	47520	weld #3	0.24
3	27031	47520	weld #3	0.57
4	34170	47520	weld #3	0.72
5	1676	6960	weld #3	0.24

Table 19 – Local Failure Criterion – Ti-45Nb

	Maximum Principal Stress Sum (psi)	Allowable Stress (psi)	Location	Ratio S_{fe}/S_a
Load Case				
1	3265	23232	weld #5	0.14
2	6361	36720	weld #5	0.17
3	7675	36720	weld #5	0.21
4	7651	36720	weld #5	0.21
5	1055	23232	weld #5	0.05

Table 20 – Local Failure Criterion – TiGr2

	Maximum Principal Stress Sum (psi)	Allowable Stress (psi)	Location	Ratio S_{fe}/S_a
Load Case				
1	12189	23232	bellows – SCL K	0.52
2	24329	58800	bellows – SCL K	0.41
3	38503	58800	bellows – SCL K	0.65
4	44584	58800	bellows– SCL K	0.76
			Ti blade tuner	
5	4962	23232	flange	0.21

Buckling

Ti Shells and Bellows

The buckling of the Ti shells and bellows is addressed by Div. 1 rules in an earlier section of this report.

The Nb Cavity

The Code, Div. 1, does not contain the necessary geometric and material information to perform a Div. 1 calculation of Nb cavity collapse. Therefore, the procedures of Div. 2, Part 5, 5.4 “Protection Against Collapse from Buckling” are applied.

A linear elastic buckling analysis was performed with ANSYS. A design factor was applied to the predicted collapse pressure to give the maximum allowable external working pressure. This design factor, taken from 5.4.1.3(c) for spherical shells, is 16.

Only the cavity was modeled. The ends are constrained in all degrees of freedom to simulate the effect of attachment to the conical heads and Ti shells of the helium vessel.

The predicted buckled shape is shown in Figure 22. The critical pressure is 12450 psi. Applying the design factor gives this component a maximum allowable external working pressure of 778 psi, which is far greater than the required MAWP of 60 psi external.

The ANSYS buckling pressure seems large; as a check, a calculation of the collapse of a sphere of similar dimensions to those of a cell was done using a formula from Ref. 4. This calculation, given in Appendix B of this report, produces a similar result.

Conical Heads

The buckling pressure of the conical heads was calculated by the linear buckling approach used for the Nb cavity.

A model of the head only was made. It was constrained against axial motion where it connects to the Ti shell, but allowed to rotate freely, and translate radially.

The predicted buckling shape is shown in Figure 23. The critical buckling pressure is 3880 psi. Applying the design factor of 2.5 (from 5.4.1.3(b) for conical shells under external pressure) gives an MAWP for external pressure of 1550 psi, which is well below the actual maximum pressure of 15 psi.

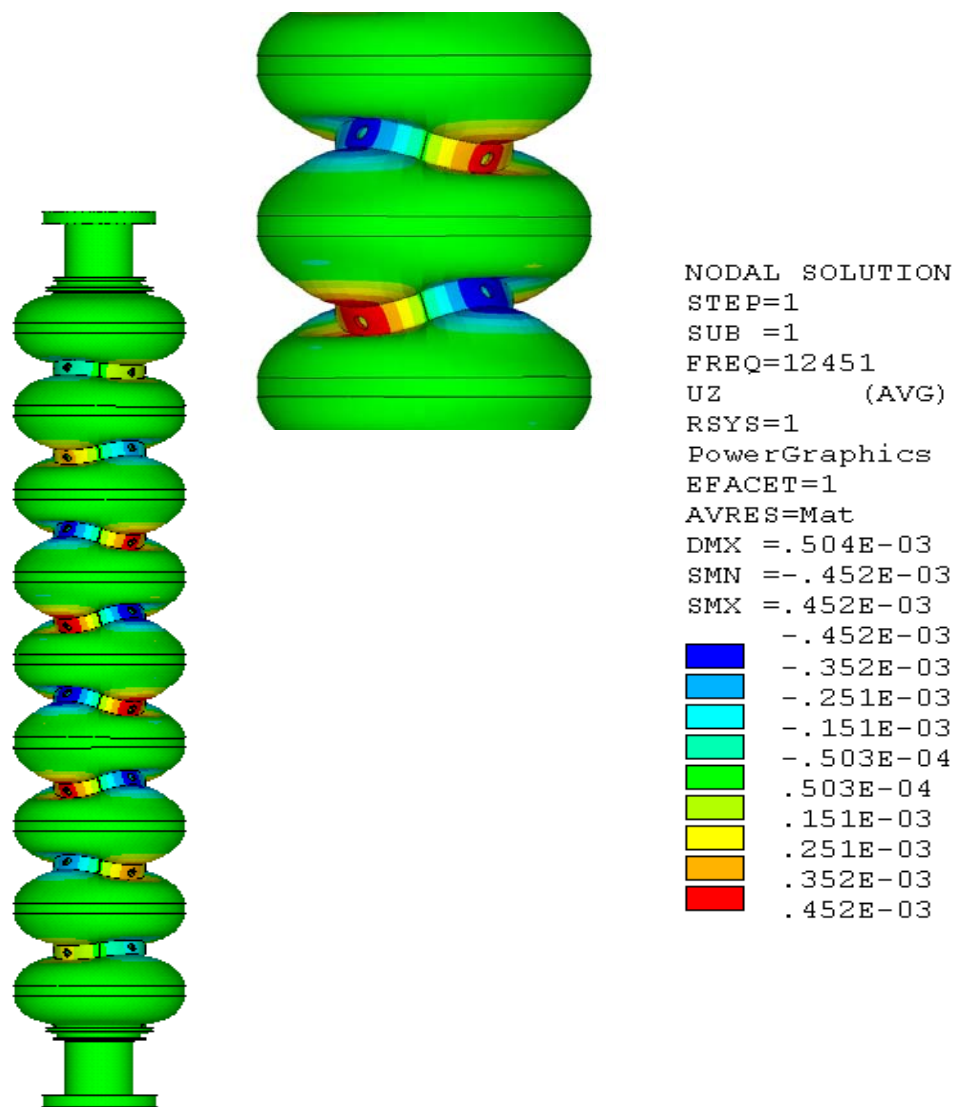


Figure 22. Lowest buckling mode of Nb Cavity (Pcr = 12450-psi)

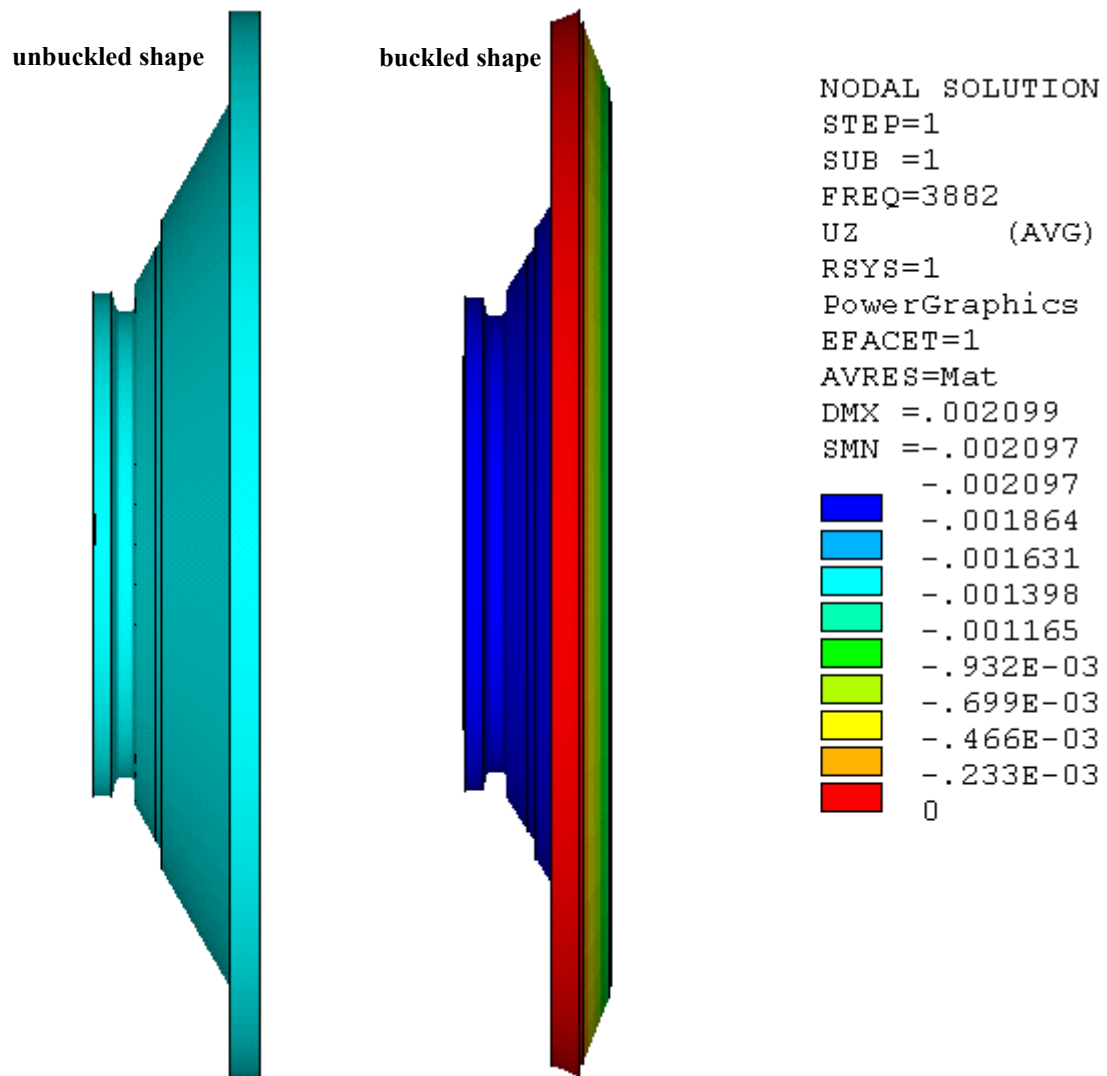


Figure 23. Buckling of conical head

Fatigue Assessment

The need for a fatigue analysis can be determined by applying the fatigue assessment procedures of Div. 2, Part 5, 5.5.2.3, “Fatigue Analysis Screening, Method A.”

In this procedure, a load history is established which determines the number of cycles of each loading experienced by the dressed cavity. These numbers are compared against criteria which determine whether a detailed fatigue analysis is necessary.

The load history consists of multiple cool down, pressurization, and tuning cycles. Estimates for the number of cycles of each load a cavity might experience are given in Table 21.

Table 21 – Estimated Load History of Dressed Cavity

Loading	Designation	Number of Cycles
Cool down	$N_{\Delta TE}$	100
Pressurization	$N_{\Delta FP}$	200
Tuning	$N_{\Delta tuner}$	200

The information of Table 21 is used with the criterion of Table 22 (a reproduction of Table 5.9 of Part 5) to determine whether a fatigue analysis is necessary.

The tuning load has no direct analog to the cycle definitions of Table 22. Therefore, it will be assigned its own definition as a cyclic load, $N_{\Delta tuner}$, and treated additively.

For the Nb cavity, construction is integral, and there are no attachments or nozzles in the knuckle regions of the heads. Therefore, the applicable criterion is

$$N_{\Delta TE} + N_{\Delta FP} + N_{\Delta tuner} \leq 1000$$

$$100 + 200 + 200 = 500 \leq 1000$$

The criterion is satisfied, and no fatigue assessment is necessary for the Nb cavity.

Table 22 – Reproduction of Table 5.9 of Part 5, “Fatigue Screening Criteria for Method A”

Description	
Attachments and nozzles in the knuckle region of formed heads	$N_{\Delta FP} + N_{\Delta PO} + N_{\Delta TE} + N_{\Delta T\alpha} \leq 350$
All other components that do not contain a flaw	$N_{\Delta FP} + N_{\Delta PO} + N_{\Delta TE} + N_{\Delta T\alpha} \leq 1000$
Attachments and nozzles in the knuckle region of formed head	$N_{\Delta FP} + N_{\Delta PO} + N_{\Delta TE} + N_{\Delta T\alpha} \leq 60$
All other components that do not contain a flaw	$N_{\Delta FP} + N_{\Delta PO} + N_{\Delta TE} + N_{\Delta T\alpha} \leq 400$
$N_{\Delta FP}$ = expected number of full-range pressure cycles, including startup and shutdown $N_{\Delta PO}$ = expected number of operating pressure cycles in which the range of pressure variation exceeds 20% of the design pressure for integral construction or 15% of the design pressure for non-integral construction $N_{\Delta TE}$ = effective number of changes in metal temperature difference between any two adjacent points $N_{\Delta T\alpha}$ = number of temperature cycles for components involving welds between materials having different coefficients of thermal expansion that cause the value of $(\alpha_1 - \alpha_2)\Delta T$ to exceed 0.00034	

Welds Between Ti Flanges and Ti Cylindrical Shells

The welds between the Ti blade tuner flange and the Ti cylindrical are structural support welds. The Code, Div. 1, Nonmandatory Appendix G, “Suggested Good Practice Regarding Piping Reactions and Design of Supports and Attachments” was applied to their analysis. This appendix states that supports should conform to good structural practice. As a guide to this practice, the Manual of Steel Construction is suggested⁽⁸⁾. Additional conservatism was applied by using the Code fillet weld joint efficiency of 0.55.

Figure 24 shows the location of the most highly stressed weld on the flange. Also shown is the coordinate system used to calculate weld stress.

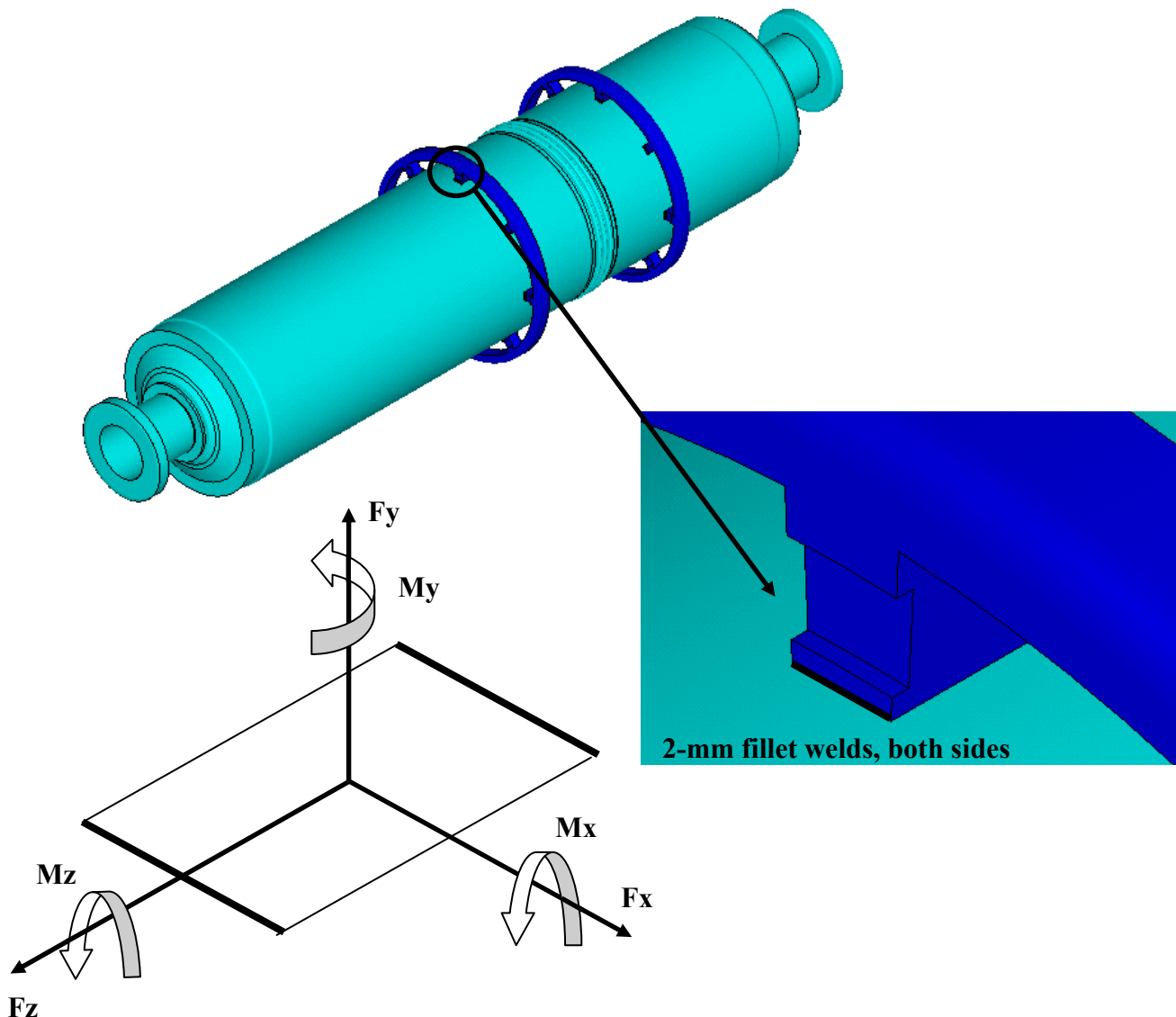


Figure 24. Location of most highly stressed weld on Ti flange and coordinate system for evaluation

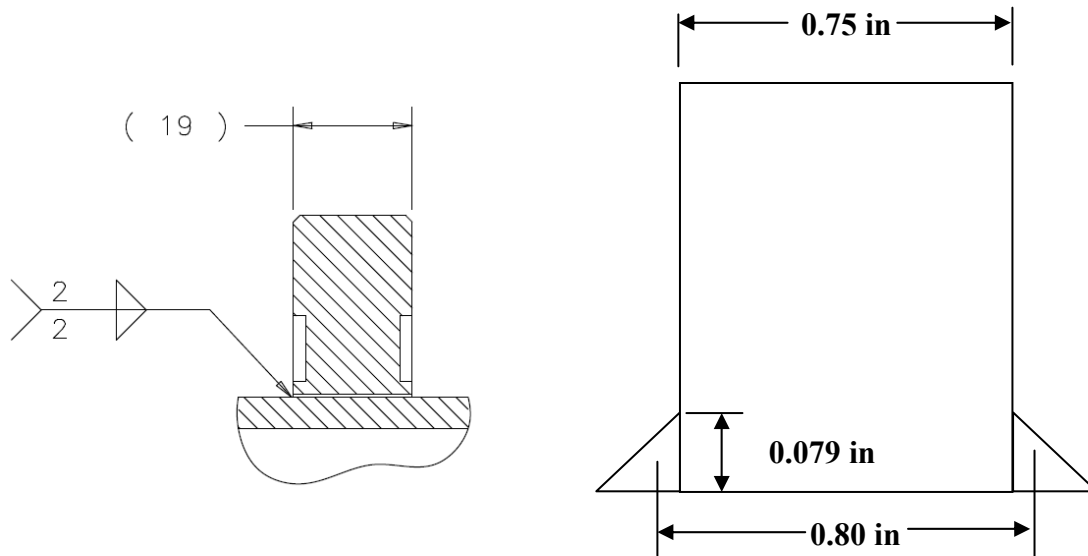


Figure 25. Weld detail and determination of distance between weld centroid (moment arm for M_x)

Due to the location (at the symmetry plane), there are no net M_y or M_z moments acting on the weld, and no net F_x force. Therefore, the only relevant loads on the welds are F_y , F_z , and M_x .

Figure 25 shows the weld detail, and the distance between weld centroids used to calculate the force components due to M_x .

The stress area of a 2 mm fillet weld, 0.5 inches long, is 0.028 in^2 . The shear on a single weld was calculated by extracting F_y , F_z , and M_x from the nodal forces of the finite element model, calculating the maximum force acting on the weld (without regard to direction) and applying that force to the stress area.

Allowable shear stresses are calculated according to Ref. 5 as 0.4 times the yield stress of the base metal (in this case, Grade 2 Ti), with an additional 0.55 factor applied for joint efficiency.

Table 23 summarizes the results for the four load cases. The closest approach to the allowable stress limit occurs for Load Case 1, which is 30 psi warm pressurization.

Table 23 – Maximum Shear Stress in Ti flange Weld to Ti Cylindrical Shell

Load Case	F_y (lbs)	F_z (lbs)	M_x (in-lbs)	Shear Force (lbs)	Shear Stress (psi)	Allowable Stress (psi)
1	25	199	162	237	8522	8800
2	56	373	306	451	16163	26620
3	104	153	111	206	7389	26620
4	160	220	194	341	12244	26620

System Venting Verification

Summary

The 1.3-GHz dressed cavity will be performance tested in the Horizontal Test Stand (HTS). For the helium system, there are two relief devices. The larger burst disk has a set pressure of 12-psig. A small check valve acts as an operational relief. For the RF cavity (beam) vacuum, there is a burst disk that ruptures at positive pressure. Table 24 lists information about each relief device.

Table 24 – Relief Devices in HTS

Type	System	Manufacturer	Model	Set Pressure	Flow Rate Capacity	Size
Burst disk	Helium	BS&B	LPS	12-psig	2188-SCFM air	3.0-in.
Check valve	Helium	Hylok	700 CV-5-F12N-25	5-psig	C _v =5.2	0.75-in.
Burst disk	Vacuum	MDC	BDA-M	1-psig		0.75-in.

The helium vessel is protected against various sources of pressure. Table 25 lists the pressure sources of the helium to the vessel, including sources that are addressed in the CGA S-1.3-2008 guideline (9). The larger burst disk on the helium system (SV-H1) is sized to relieve any of these pressure sources.

Table 25 – Helium Vessel Pressure Sources

Helium Pressure Source	Maximum Flow Rate (g/sec)	Helium Temperature in Vent Line (K)	Required Capacity (SCFM-air)
Primary relief (CGA 6.2.2)		10	236
Fire relief (CGA 6.3.2)		10	1274
Warm helium supply from cryoplant	25	300	93
Cold helium supply from cryoplant	64	10	43
Loss of RF cavity (beam) vacuum	2317	10	1568
Loss of insulating vacuum	1992	10	1348

The helium supply maximum flow rates are provided by the engineering team for MDB ^(5, 10).

For the mass flow rates that are listed, the following equation is used for conversion to volumetric flow rate (SCFM-air): ⁽¹¹⁾

$$Q_a = \frac{13.1 * W * C_a}{60 * C} \sqrt{\frac{Z * T * M_a}{M * Z_a * T_a}}$$

Where:

W	Corrected mass flow rate of helium (divide the mass flow rate by 0.9 to size an ASME relief device)	lbm/hr
C _a	gas constant of air	
Z _a	compressibility factor of air	
T _a	air temperature at standard conditions	R
M _a	air molecular weight	
C	helium gas constant	
M	molecular weight of helium	kg/kmol
Z	compressibility factor of helium	
Q _a	volumetric flow rate	SCFM air

Venting System Description

Figure 26 shows the Piping and Instrumentation Diagram (P&ID) of the HTS system (drawing 4906.320-ME-440302) which contains the placement of the larger helium burst disk (SV-H1) and the vacuum (beam line) burst disk (SV-RF01). Table 26 is the complete component list for the HTS P&ID. Figure 27 shows drawing 5520.000-ME-440517 which shows the operational relief (SVH1) as well as the larger helium burst disk (SVHTC).

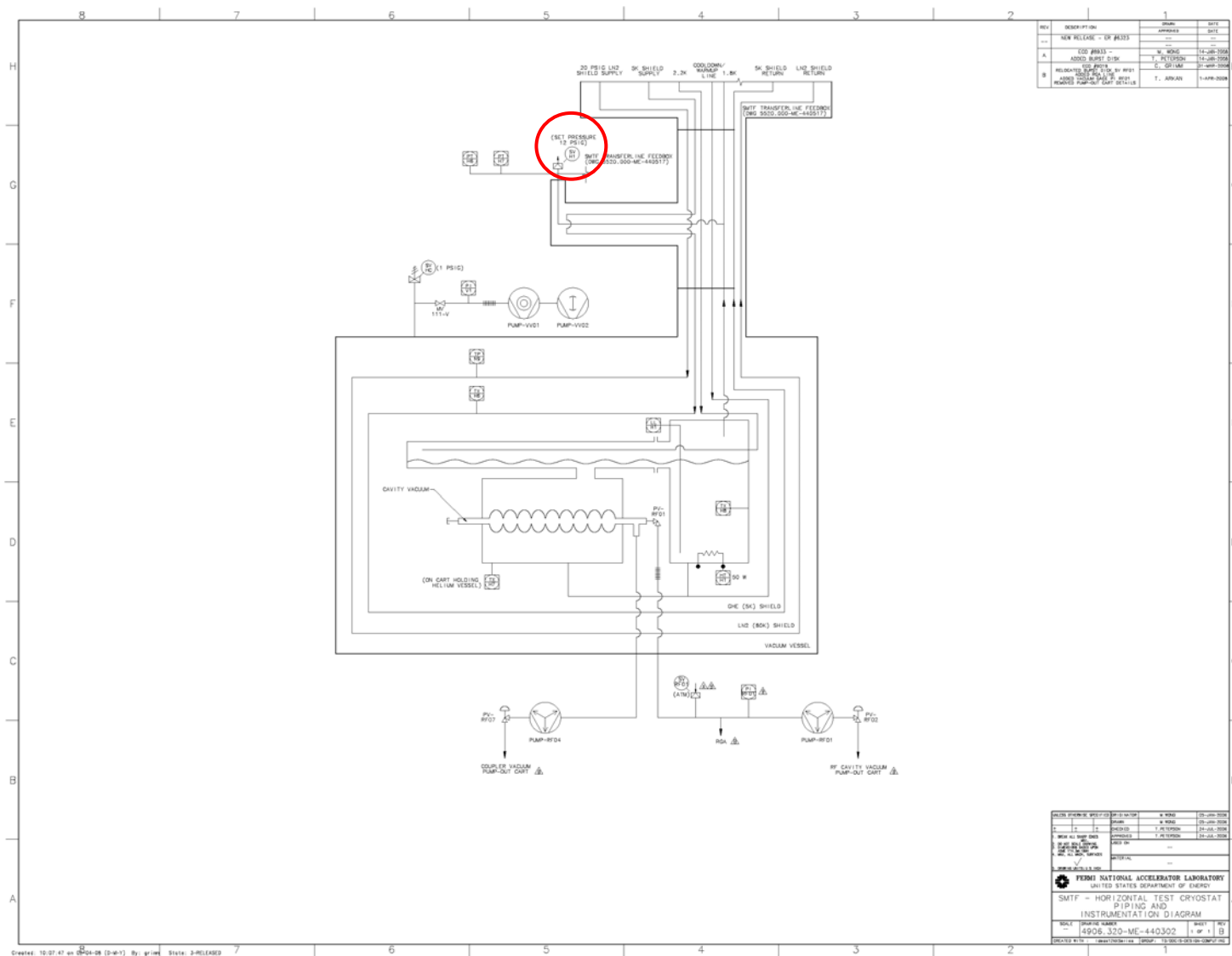


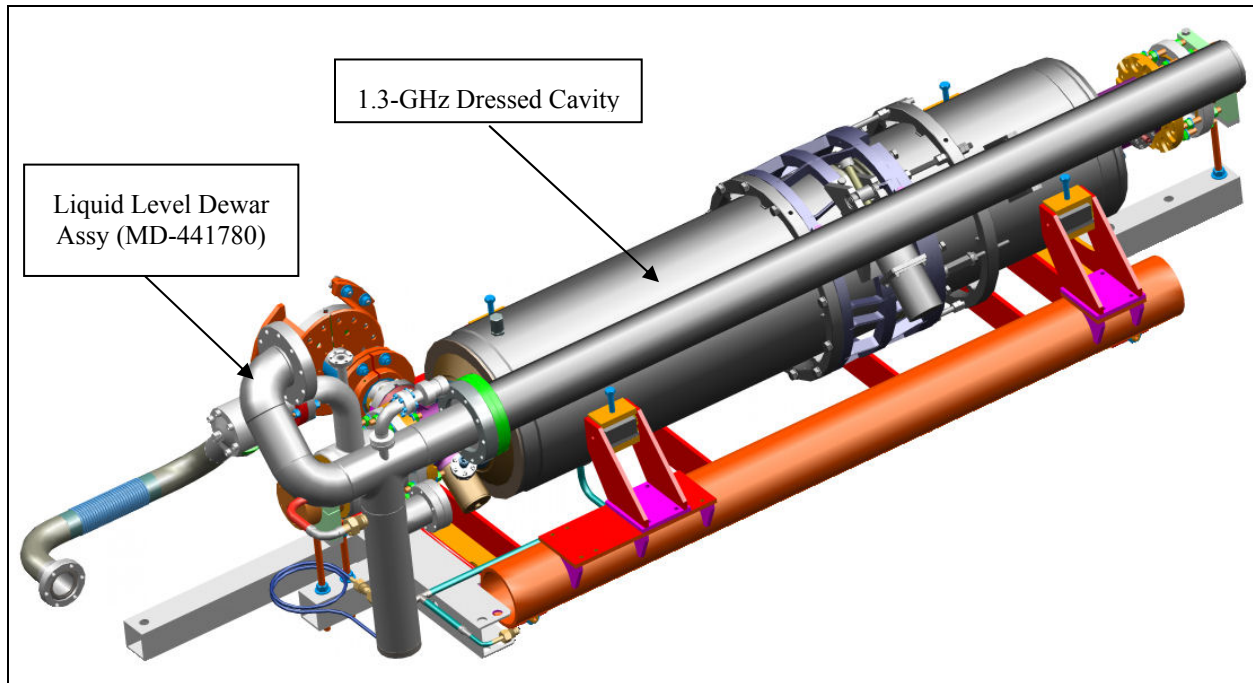
Table 26 – Component List for Horizontal Test Stand (for P&ID drawing 4906.320-ME-440302)

Tag	ACCNET	APACS	Location	Type	Model	Company	Range	Readback
Instrumentation								
CALLH1	Z:CALLH1	SMTA_CALLH1	LHe level dewar	Liquid level sensor	12-inch active	AMI	0 -100 %	4-20 mA
CAPTV1	Z:CAPTV1	SMTA_CAPTV1	Cryostat insulating vacuum	Pressure transducer	ITR90 Ionivac	Leybold	3.75E-10 - 750 torr	0-10 V
CAPTH6	Z:CAPTH6	SMTA_CAPTH6	Helium pumping line	Pressure transducer (high range)	FPA	Sensotec	0-50 psia	4-20 mA
CAPTH7	Z:CAPTH7	SMTA_CAPTH7	Helium pumping line	Pressure transducer (low range)	230EA-00100BC	MKS	0-100 torr	4-20 mA
CAHTH1	Z:CAHTH1	SMTA_CAHTH1	LHe level dewar	Cartridge heater	E1J39	Watlow	120V-50W	I/O
CATPN9	Z:CATPN9	SMTA_CATPN9	80K Thermal shield	Platinum temperature sensor	PT102	Lake Shore	40 K-300 K	4-20 mA
CATXH6	Z:CATXH6	SMTA_CATXH6	5K Thermal shield	Cernox resistor temperature sensor	CX-1050-SD	Lake Shore	0.1K-300K	4-20 mA
CATXH7	Z:CATXH7	SMTA_CATXH7	Dressed RF cavity cart	Cernox resistor temperature sensor	CX-1050-SD	Lake Shore	0.1K-300K	4-20 mA
CATXH8	Z:CATXH8	SMTA_CATXH8	LHe level dewar	Cernox resistor temperature sensor	CX-1050-SD	Lake Shore	0.1K-300K	4-20 mA

Tag	ACCNET	APACS	Description / Location	Type	Model	Company	Range	Size
Valves								
CASVH1	--	--	Helium pumping line	Rupture disk	LPS	BS&B	Set point 12 psig @ 72 deg F	3-inch
CASVHC	--	--	Cryostat insulating vacuum	Fermi vacuum safety relief valve	1620-MB-106391	Fermilab	Set point 1 psig @ room temp	2.625-inch ID

Tag	ACCNET	APACS	Description / Location	Type	Model	Company	Pump Speed	Operating pressure
Vacuum Pumps								
PUMP-VV01	--	--	Cryostat insulating vacuum	Turbomolecular pump	ATP 80	Alcatel	80 L/sec	3.75E-9 torr
PUMP-VV01	--	--	Cryostat insulating vacuum	Roots pump	ACP 15	Alcatel	14 m^3/hr	3.7E-2 torr

Figures 28 and 29 show the helium pumping line that also serves as the helium venting line. The two-phase helium line of the 1.3-GHz dressed cavity attaches directly to the piping in the HTS at the liquid level dewar assembly (part and drawing number 441780).



**Figure 28. 1.3-GHz Dressed Cavity and Liquid Level Dewar Assembly (MD-441780)
Ready for Installation into HTS**

The liquid level dewar assembly is connected to the flexhose assembly and hard piping that lead to the burst disk.

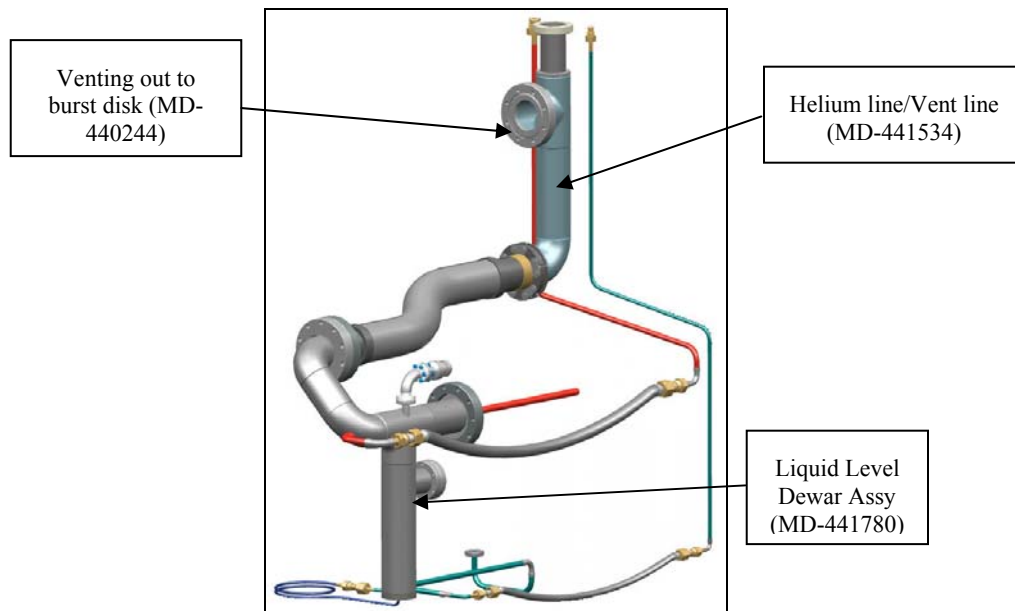
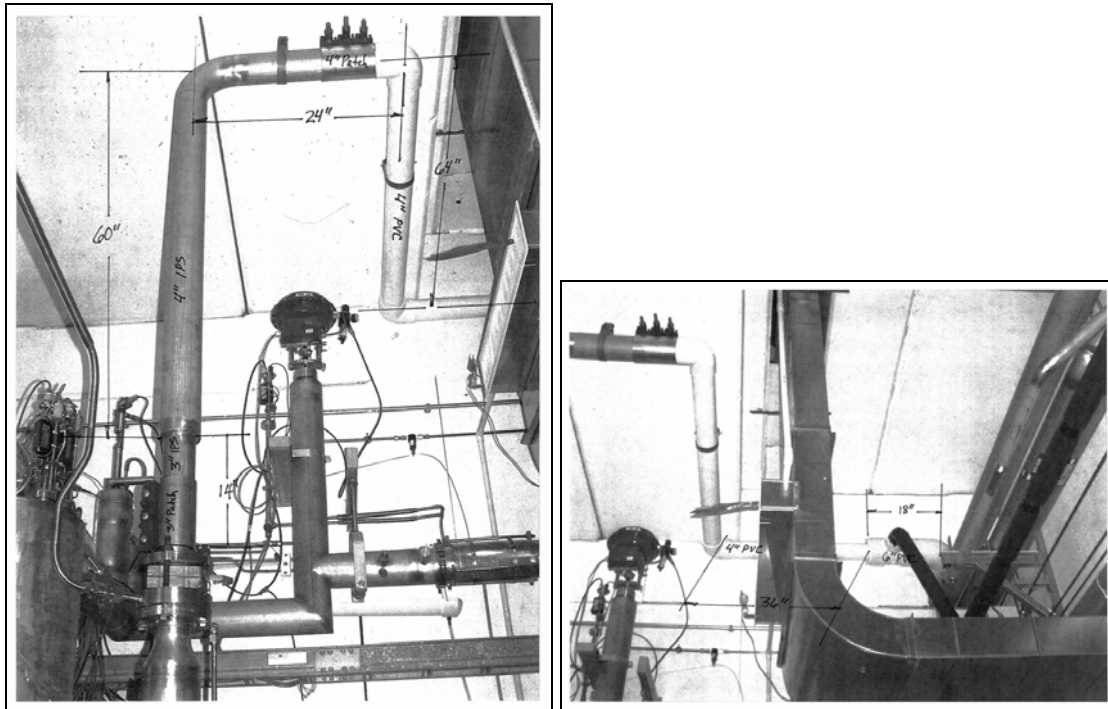


Figure 29. Helium pumping line which serves also as the large relief venting line

Figures 30-32 are photos of the helium vent header, which is depicted in the SMTF P&ID

440517 (Figure 27). The photos show the dimensions of the line.



Figures 30-31. Photos of the vent piping for the horizontal test cryostat downstream of the rupture disk.

Figures 30 and 31 - The 4-inch pipe has a straight section of 184-inches long and four 90° elbows. The 4-inch section is a combination of steel and PVC components.

Figure 31 – The visible part of the 6-inch PVC pipe is 18-inches long



Figure 32. Vent piping exit outside the cave. The 6-inch PVC pipe is 86-inches long through the cave wall to discharge.

Detailed Calculations for the System Venting

Temperature of relief flow (CGA S-1.3—2008 paragraph 6.1.3)

The CGA specifies a temperature to calculate the flow capacities of pressure relief devices for both critical and supercritical fluids. The temperature to be used is determined by calculating the square root of fluid's specific volume and dividing it by the specific heat input at the flow rating pressure. The sizing temperature would be when this calculation is at a maximum. For the relief pressure of 12-psig, the temperature is 6.0°K. The temperature of 10.0°K is used as a conservative way to calculate the flow capacities and size the relief device.

Primary relief sizing (CGA S-1.3—2008 paragraph 6.2.2)

The required flow capacity for primary relief is calculated:

$$Q_a = \frac{(590 - T)}{4 * (1660 - T)} F * G_i * U * A$$

Where:

Q _a	primary relief flow capacity	236	SCFM air
T	helium temperature	18	°R
F	correction factor for cryogenic systems	1	
U	overall heat transfer coefficient of insulating material	0.779	Btu/(hr-ft ² -°F)
G _i	gas factor for insulated containers of liquid helium	52.5	
A	arithmetic mean of the inner and outer surface areas of insulation	66.3	ft ²

Fire relief sizing (CGA S-1.3—2008 paragraph 6.3.3)

The required flow capacity for fire relief is calculated

$$Q_{a_fire} = F * G_i * U * A^{0.82}$$

Where:

Q_{a_fire}	primary relief flow capacity	1274.2	SCFM air
F	correction factor for cryogenic systems	1	
U	overall heat transfer coefficient of insulating material	0.779	Btu/(hr-ft ² -°F)
G_i	gas factor for insulated containers of liquid helium	52.5	
A	arithmetic mean of the inner and outer surface areas of insulation	66.3	ft ²

Secondary relief sizing – Loss of RF Cavity (Beam) Vacuum and Loss of Insulating Vacuum

The secondary relief requirement considers two independent scenarios in calculating the helium boil-off: helium vaporization due to the loss of RF cavity (beam) vacuum and helium vaporization due to the loss of insulating vacuum. The helium boil-off during the loss of RF cavity vacuum is calculated based on the total surface area of the RF cavity, which is 1302-in² (0.84-m²). For a loss of cavity vacuum due to an air leak, the heat flux of 4.0-W/cm² is used ⁽¹²⁾. For helium at the relief pressure of 12.0-psig, the heat absorbed per unit mass of efflux, equivalent to a latent heat but including the effect of significant vapor density is 14.5-J/g. The maximum mass flow rate can be calculated:

$$\dot{m}_{RF_cavity} = \frac{A_{cavity} * Q}{LH}$$

Where

$\dot{m}_{RF_cavity}$	Mass flow rate	2317	g/sec
A_{cavity}	Total surface area of RF cavity	0.84	m ²
		8400	cm ²
LH	Effective latent heat @ 5K (maximum specific heat input for 12-psig)	14.5	J/g
Q	Heat efflux due to air leak into cavity	4	W/cm ²

The helium boil-off during the loss of insulating vacuum is calculated based on the total surface area of the cold mass. The cold mass includes the total surface area of the helium vessel and the associated piping leading to the burst disk. The total surface area is 14,439-cm². (The detailed list of components in the cold mass with their surface areas is shown in Table 27) The heat efflux for a superinsulated vacuum vessel with an uninsulated helium vessel is 2.0-W/cm².^(13, 14) So the mass flow rate is 1348-SCFM air.

Table 27 – Surface area for the cold mass, including the helium vessel and the piping leading to the burst disk

Helium Vessel - Assembly Number and Name	Part Name	Drawing Number	SA of flow path (in ²)
872825: G3 Helium Vessel RF Cavity Assy	(Helium vessel boundary)	87285	1550.0
	Helium line		370.0
MD-441523: 3.9GHz Liquid Level Dewar Assy	Helicoflex Flange	MA-441524	7.2
	Pipe, 2 Sch 10 x 3.5"LG	MD-441523, Item 2	23.7
	Modified Tee	MB-441525	33.9
	Modified Elbow	MB-441526	21.5
	90° Elbow, 2" Sch 10, SR	MD-441523, Item 8	21.3
	Pipe, 2" Sch 10 x 0.5"LG	MD-441523, Item 9	3.4
	Helicoflex Flange	MA-441524	7.2
	Bottom pipe	MB-441527	67.2
	Bottom cap	MB-441529	4.4
MB-441533: Flexhose Subassy	Helicoflex Flange	MA-441524	7.2
	Flexhose	MB-441025	113.9
	Helicoflex Flange	MA-441524	7.2
MC-441534: Pumping Line Weldment	Helicoflex Flange	MA-441524	7.2
	Elbow, 2" Sch 10, SR	MC-441534, Item 2	21.3
	Pipe, 2" Sch 10 x 6.3"LG	MC-441534, Item 3	42.6
	Tee, 2" Sch 10	MC-441534, Item 4	20.0
MD-440244: Helium Relief Subassy	Modified Conflat Flange	ME-440245	2.0
	Pipe, 2 Sch 10 x 12.4"LG	ME-426450, Item 2	84.0
	90° Elbow, 2" Sch 10, SR	ME-426450, Item 3	21.3
	Pipe, 2 Sch 10 x 5"LG	ME-426450, Item 2	33.9
	Flexhose Assy	MB-440246	86.0
	Pipe, 2 Sch 10 x 4.25"LG	ME-426450, Item 2	28.8

Total Surface Area of Cryostat Helium Return Line (in ²)	2238.1
(cm ²)	14439.1

Pressure drop through the vent line

To ensure that the burst disk has been adequately sized, the pressure drop through the vent line is calculated. Assume that the burst disk has been ruptured. The total pressure drop is calculated by dividing the entire vent line into shorter sections and calculating the pressure drop in each section, adjusting the helium properties along the vent line. The inlet pressure of the vent line is the dressed cavity's cold MAWP of 4-bar. The pressure at the exit of the vent line must be larger than atmospheric pressure, confirming in a conservative way that there is enough helium flow to push through the vent line.

For the pressure drop calculations described in this amendment, all equations come from Crane's Flow of Fluids Handbook.⁽¹⁵⁾ For the entire vent line, the equation that is used is:

$$\Delta P = 2.8E^{-7} * \frac{K * W}{\rho * d^4}$$

Where ΔP = pressure drop (psi)

K = the resistance coefficient of the section

W = maximum mass flow rate = $2317/0.9 = 2575\text{-g/sec} = 20438\text{-lbm/hr}$

V = helium specific volume (ft^3/lbm)

d = flow diameter = 2.16-inch

The pressure drop through the vent line is calculated for helium at 10°K. The flow resistance value for each section is ultimately calculated in terms of one diameter, which is the 2.16-inch diameter. For straight sections of pipe, the friction factor was determined using the chart titled “Friction Factors for Clean Commercial Steel Pipe” in Crane. It is noted that PVC pipe, which is used downstream of the burst disk, is nominally smoother than steep pipe.

The following tables show the pressure drop calculations for each section. Table 28a lists the helium properties and the friction factor calculations for each section. Table 28b shows the resistance factor and pressure drop calculations. If the inlet helium pressure at the vessel (the entrance to the vent line) is 4-bar at 10.0°K, then the final pressure at discharge is calculated to be 1.08-bar. Since the pressure at discharge is actually 1.0-bar, the maximum helium vessel pressure will not reach 4.0-bar.

Table 28a – Helium Properties and Friction Factors for Each Section

Mass flow rate helium	2317.241 g/sec
Adjusted mass flow rate (divide by 0.9)	2574.713 20438.1 lbm/hr
At vessel	
Helium temperature	10 K (assume constant through entire vent line)
Helium pressure	4.00 bar
Helium absolute viscosity	2.50E-03 cP
Helium specific volume	4.63E-02 m ³ /kg 0.74 ft ³ /lbm
Pressure drop at entrance into pipe	0.28 bar
Through 2.16-inch pipe	
Pressure at pipe inlet	3.72 bar
Helium absolute viscosity	2.48E-03 cP
Helium specific volume	5.03E-02 m ³ /kg 0.81 ft ³ /lbm
d_2-16	2.16 inch
Re_2-16	2.41E+07 (for 2.16-inch diameter pipe)
f_2-16	0.019 (for 2.16-inch diameter pipe)
Through 2.00-inch flexhose	
Pressure at pipe inlet	3.36 bar
Helium absolute viscosity	0.0024487 cP
Helium specific volume	0.056306 m ³ /kg 0.90 ft ³ /lbm
d_2	2.00 inch
Re_2	2.58E+07 (for 2-inch diameter pipe)
f_2	0.019 (for 2-inch diameter pipe)
Through 2.16-inch pipe	
Pressure at pipe inlet	2.96 bar
Helium absolute viscosity	2.42E-03 cP
Helium specific volume	6.44E-02 m ³ /kg 1.03 ft ³ /lbm
d_2-16	2.16 inch
Re_2-16	2.47E+07 (for 2.16-inch diameter pipe)
f_2-16	0.019 (for 2.16-inch diameter pipe)
Through 2.16-inch pipe	
Pressure at pipe inlet	2.34 bar
Helium absolute viscosity	2.37E-03 cP
Helium specific volume	8.33E-02 m ³ /kg 1.33 ft ³ /lbm
d_2-16	2.16 inch
Re_2-16	2.52E+07 (for 2.16-inch diameter pipe)
f_2-16	0.019 (for 2.16-inch diameter pipe)
Through 3.00-inch pipe	
Pressure at pipe inlet	1.64 bar
Helium absolute viscosity	0.0023088 cP
Helium specific volume	0.12063 m ³ /kg 1.93 ft ³ /lbm
d_3-26	3.26 inch
Re_3-26	1.71E+07 (for 3-inch diameter pipe)
f_3-26	0.017 (for 3-inch diameter pipe)
Through 4.00-inch pipe	
Pressure at pipe inlet	1.34 bar
Helium absolute viscosity	0.0022851 cP
Helium specific volume	0.14879 m ³ /kg 2.38 ft ³ /lbm
d_4-26	4.26 inch
Re_4-26	1.32E+07 (for 4-inch diameter pipe)
f_4-26	0.016 (for 4-inch diameter pipe)
Through 6.00-inch pipe	
Pressure at pipe inlet	1.10 bar
Helium absolute viscosity	2.27E-03 cP
Helium specific volume	0.18234 m ³ /kg 2.92 ft ³ /lbm
d_6-357	6.357 inch
Re_6-357	8.95E+06 (for 6-inch diameter pipe)
f_6-357	0.015 (for 6-inch diameter pipe)

Table 28b – Resistance Factors and Pressure Drops in Each Section

Beta = smaller diameter / larger diameter
Ratio = reference diameter (2.16) / actual or downstream diameter

	K	K*Ratio^4	L (inch)	d (inch)	fT	r	r/d	K_R	Beta	Ratio	Assume T=10°K at each section				
											Total K for section	Helium pressure (bar)	Helium specific volume (ft^3/lbm)	Pressure drop (psi)	Pressure drop (bar)
<i>Piping within HTC</i>															
Entrance into vent pipe	1.00	1.00								1.00	Vent line on vessel - entrance 1.00	4.00	0.742	3.99	0.28
Vessel supply pipe	0.13	0.13	14.49	2.16						1.00	Vent line on vessel - run to dewar 0.19	3.72	0.806	0.84	0.06
Vent line to LL dewar	0.07	0.07	7.60	2.16						1.00	Vent line through LL dewar 1 0.40	3.67	0.817	1.77	0.12
Thru LL dewar											Vent line through LL dewar 2 0.59	3.54	0.852	2.71	0.19
straight run	0.03	0.03	3.80	2.16						1.00	Flexhose 1.18	3.36	0.902	5.74	0.40
tee thru	0.37	0.37		2.16	0.0185					1.00	Components of pumping line weldment 0.44	2.96	1.032	2.42	0.17
2-90 deg bends	0.57	0.57		2.16	0.0185	2.3	1.06			1.00	1.11	2.80	1.098	6.55	0.45
straight run	0.02	0.02	2.40	2.16						1.00	Components of helium vent line branch 0.88	2.34	1.335	6.30	0.43
Sudden contraction	0.18	0.18							0.93	1.00	0.45	1.91	1.647	3.96	0.27
Flexhose assy	0.98	1.33	102.80	2.00						1.08	Cmpts of 3-in diameter piping 0.21	1.64	1.932	2.20	0.15
Sudden expansion	0.03	0.03							0.93	1.00	0.08	1.48	2.158	0.94	0.06
Pumping line weldment											0.10	1.42	2.253	1.17	0.08
helicox flange	0.01	0.01	1.20	2.16						1.00	Cmpts of 4-in diameter piping 0.27	1.34	2.383	3.48	0.24
90 deg bend	0.37	0.37		2.16	0.0185	2	0.93			1.00	Discharge line to atmosphere 0.02	1.10	2.921	0.26	0.02
straight run	0.06	0.06	6.30	2.16						1.00	Exit	1.00			
tee branch	1.11	1.11		2.16	0.0185					1.00					
Helium vent line branch															
straight run	0.12	0.00	13.10	2.16											
90 deg bend	0.37	0.37		2.16	0.0185	2	0.93			1.00					
straight run / flexhose line	0.39	0.39	44.75	2.16						1.00					
Expansion 2 to 3-inch	0.45	0.45								0.72					
<i>3-inch diameter piping</i>															
BS&B LPS burst disk	0.79	0.21		3.00				0.79		0.72					
Expansion 3 to 3.26-inch	0.03	0.01								0.92					
Straight run	0.38	0.07	72.00	3.26						0.66					
Expansion 3 to 4-inch	0.50	0.10								0.77					
<i>4-inch diameter piping</i>															
Straight run	0.69	0.05	184.00	4.26						0.51					
90 deg elbow	0.48	0.03		4.26						0.51					
90 deg elbow	0.48	0.03		4.26						0.51					
90 deg elbow	0.48	0.03		4.26						0.51					
90 deg elbow	0.48	0.03		4.26						0.51					
Expansion 4 to 6-inch	1.51	0.10							0.67	0.51					
<i>6-inch diameter piping</i>															
Straight run	0.25	0.00	104.00	6.36						0.34					
Exit	1.00	0.01								0.34					

Final pressure at discharge as calc. 1.08 (bar)

Welding Information

The weld characteristics were introduced earlier in this document in the sub-section titled “Welds” in the “Design Verification” section. As stated earlier, welds are produced by either the electron-beam process or the tungsten inert gas (TIG) process. All welds on the dressed cavity are designed as full penetration butt welds. All welds are performed from one side, with the exception of the Ti-45Nb to Ti transition welds. Those welds are performed from two sides. No backing strips are used for any welds. Table 29 summarizes the welds, including the drawing, materials joined, weld type, and how the weld was qualified. Figure 33 shows the location of the welds on the vessel.

Table 29 – Weld Summary for AES-4

Weld	Weld Description	Drawing & Reference	Materials Joined	Weld Type	Weld Qualification
1	End Tube Spool Piece to End Cap Flange	MD-439178	Nb-Nb	EB	Welded at AES
2	End Tube Spool Piece to RF Half Cell	MD-439178	Nb-Nb	EB	Welded at AES
3	End Cap Flange to RF Half Cell	MD-439178	Nb-Nb	EB	Welded at AES
4	End Cap Flange to End Cap Disk	MD-439178	Nb-Ti45Nb	EB	Welded at AES
5	End Cap Disk to Transition Ring	MD-439180 MD-440003	Ti45Nb-Ti	EB	Welded at AES
6	1.3GHz 9 Cell RF Cavity (Transition Ring) to Cavity-Vessel Adapter Ring	872825	Ti-Ti	TIG	Welded at FNAL. WPS, PQR, WPQ for Procedure No. TI-1 and TI-6.
7 (FB End)	Cavity-Vessel Adapter Ring to G3 Helium Vessel Assembly	872825	Ti-Ti	TIG	Welded at FNAL. WPS, PQR, WPQ for Procedure No. TI-1 and TI-6.
7 (Coupler End)	G3 Helium Vessel Assembly to 1.3GHz 9 Cell RF Cavity	872825	Ti-Ti	TIG	Welded at FNAL. WPS, PQR, WPQ for Procedure No. TI-1 and TI-6.
8	Bellows Assembly to Tube	812815, X-Ray Report	Ti-Ti	TIG	Welded at Hi-Tech. WPS, PQR, WPQ. Final weld was radiographed (weld W3, W4 in x-ray report).
9	Support Ring to Half Cell	MC-439172	Nb-Nb	EB	Welded at AES
10	Dumbbell to Dumbbell	MD-439173	Nb-Nb	EB	Welded at AES
11	Half Cell to Half Cell	MC-439172	Nb-Nb	EB	Welded at AES
12	Bellows Convolutions to Weld Cuff	844575	Ti-Ti	TIG	Welded at Ameriflex. WPQ.
13	Seam Welds of Helium Tubes	812995, 813005, X-Ray Report	Ti-Ti	TIG	Welded at Hi-Tech. WPS, PQR, WPQ. Final weld was radiographed. (weld W2 in x-ray report)
14	2-phase pipe stub to helium vessel	812765, X-Ray Report	Ti-Ti	TIG	Welded at Hi-Tech. WPS, PQR, WPQ. Final weld was radiographed (weld W1 in x-ray report).

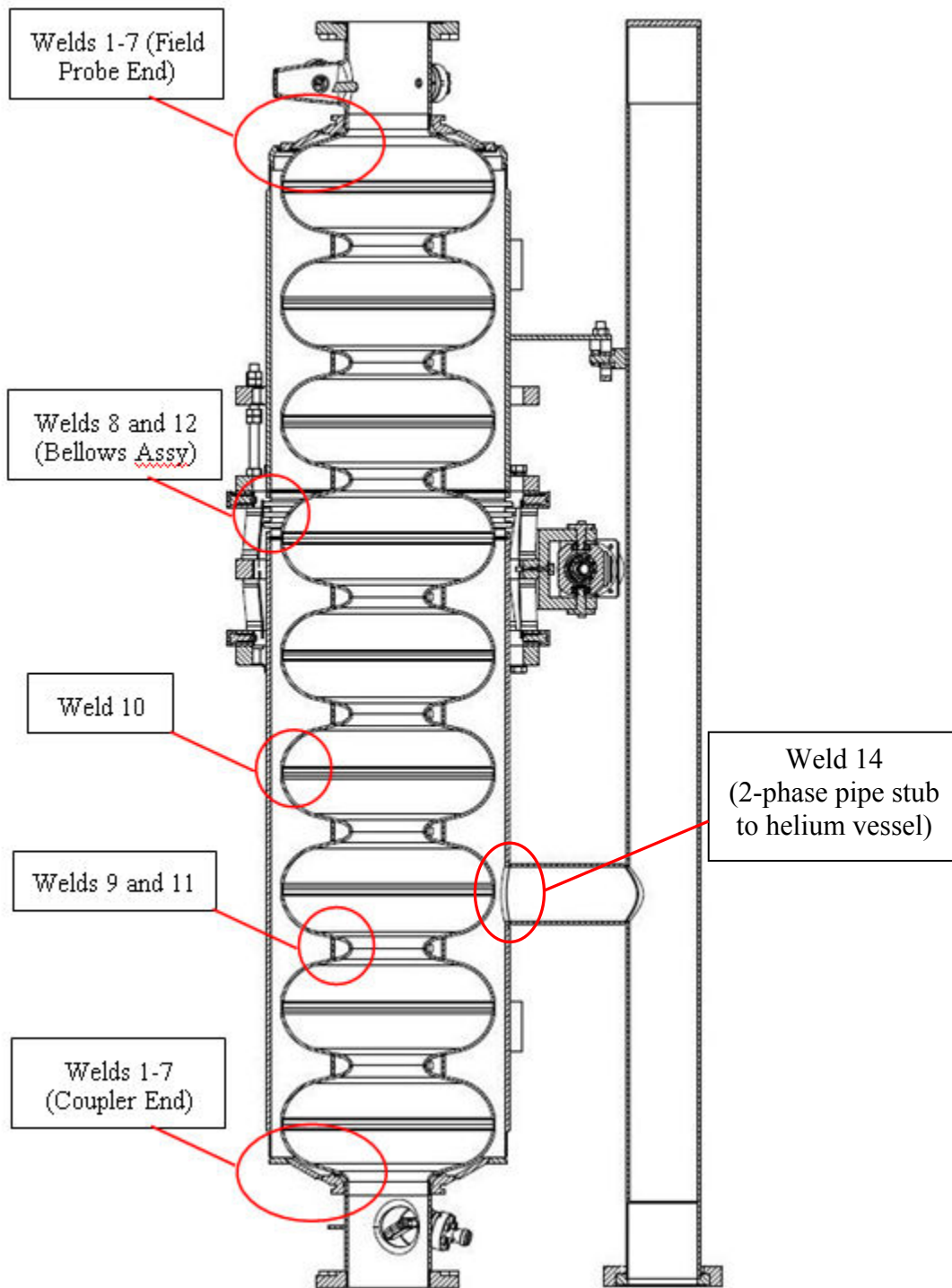


Figure 33. Weld Locations, as numbered in Table 28

According to the Code, the welds must follow certain guidelines. Table 30 summarizes the weld guideline, the paragraph in the Code which addresses the weld guideline, and how the weld does not follow the guideline. To accommodate for the exceptions, in the analysis of the design, the joint efficiency is at least 0.6, which is typical for a weld that is not radiographed (see Table 4).

Table 30 – Weld Exceptions to the Code

Weld Guideline	Code Paragraph	Exception to the Code	Explanation
Electron beam welds in any material must be ultrasonically examined along the entire length.	UW-11(e)	No ultrasonic examination was performed.	In the analysis, the joint efficiency is at least 0.6, as if the weld is not radiographed (see Table 3).
Category A and B Ti welds must be either Type 1 or Type 2 butt welds.	UNF-19(a)	Some Category B welds are Type 3.	In the analysis, the joint efficiency is at least 0.6, as if the weld is not radiographed (see Table 3).
Category A and B welds Ti welds must be fully radiographed.	UNF-57(b)	Bellows assembly (convolution to weld cuff) not radiographed.	In the analysis, the joint efficiency is 0.6 for a weld that is not radiographed (see Table 3).
All Ti welds must be examined by the liquid penetrant method.	UNF-58(b)	No liquid penetrant testing was performed.	In the analysis, the joint efficiency is at least 0.6, as if the weld is not radiographed (see Table 3).

Three welds are performed at Fermilab (welds 6-7 in Table 29). They are the final closure welds that bring the titanium helium vessel and the niobium RF cavity together to make the complete assembly. According to the Technical Appendix in the FESHM 5031 on Welding Information:

“Welding executed at Fermilab shall be done in a manner equivalent to a generic welding procedure specified and qualified under the rules of the A.S.M.E. Boiler and Pressure Vessel Code Section IX. The system designer of an in-house built vessel shall provide a statement from the welding supervisor or his designee certifying the welding was observed and accomplished in accordance to the specified generic welding procedure by a qualified welder and shall attach a copy of the welder's identification to the statement.”

The Code Section IX requires three documents that specify and qualify a weld procedure and certify a welder. These documents are the Welding Procedure Specification (WPS), the Procedure Qualification Record (PQR), and the Welder/Welding Operator Performance Qualifications (WPQ). For the titanium closure welds that are completed at Fermilab, namely welds 6-7 in Table 29, the relevant documents are titled “TI-1” and “TI-6”.

All other welds were performed at vendors outside Fermilab. Any available documentation and inspection results are explained in the following paragraphs.

For the niobium cavity electronic beam (EB) welding that took place at AES (welds 1-5, 9-11), no welding documents are available. The process is proprietary. How the welds and welders are qualified are not known other than what is specified in the engineering drawings. The quality

assurance for the niobium cavity is its RF performance. The RF performance is an indirect way of proving full penetration welds because if the weld is not full penetration, the RF performance is not acceptable.

For the bellows assembly, a single weld holds the bellows convolution to the weld cuff (weld 12 in Table 29). The bellows assembly was made at Ameriflex. A WPQ is available.

The titanium helium vessel assembly was manufactured at Hi-Tech. The available WPS, PQR, and WPQ located online. All of the final welds (including welds 8, 12-14) were radiographed (x-rayed). The weld documents and the radiography report are included online.

A detailed procedure, titled “1.3GHz Cavity Welding to Helium Vessel” lists all of the manufacturing steps that are taken for dressing a bare cavity after vertical testing in preparation for horizontal testing.

All documents that are discussed in the Welding Information section are available online at the following location:

<http://ilc-dms.fnal.gov/Workgroups/CryomoduleDocumentation/AES004/weld-docs/>

Anomalous Welds

Weld between Ti cylindrical shell and pipe at 2.16 in dia penetration (2-phase pipe stub)

The weld at the 2.16 in penetration in the Ti cylindrical shell has been shown to require no additional reinforcement “other than that inherent in the construction.” However, this assumes that the weld between the cylindrical shell and the pipe which attaches at the penetration is a Code weld; as we do not have a Code weld, the question of whether this affects the reinforcement “inherent” in the construction must be examined.

The actual attachment weld is a single fillet weld, as shown in Figure 34 below.

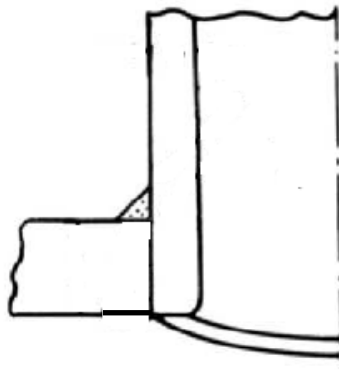


Figure 34. Single-sided fillet weld – non-Code

This type of unsupported single fillet weld is not allowed by the Code; however, a single fillet weld is permitted if the fillet weld occurs on the inner surface of the cylindrical shell (Figure 35).

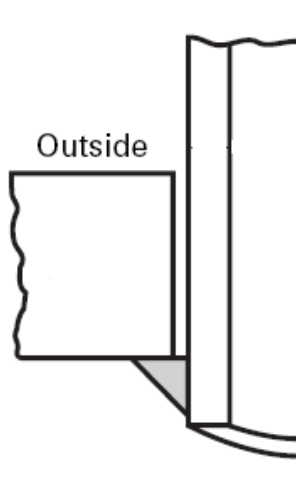


Figure 35. Single-sided fillet weld – Code

From the perspective of “inherent” strength of reinforcement, the location of the single fillet weld is unimportant; therefore, the argument that the penetration requires no additional reinforcement is still valid.

The attachment weld can be sized assuming that the only load it must resist is the pressure load, which tends to shear fillet weld. (No side loads or other incidental loads have been identified).

The force produced at the maximum pressure of 60 psi is

$$F = \frac{\pi D^2 P}{4} = 220 \text{ lbs}$$

The stress area of a fillet weld of leg t is

$$A = 0.707 \pi D t$$

Assuming a weld efficiency of 0.55, and an allowable stress in shear equal to one-half of the room temperature primary stress allowable for titanium gives a required minimum weld leg t to resist pressure of 0.017 in.

If the cold strength of the Ti is used (justifiable since the 60 psi pressure will only occur cold), then the minimum required weld thickness is only 0.006 in.

Radiographic examination of the weld shows that, while it is not uniform in thickness, the minimum thickness is not smaller than 0.017 in.

Fabrication Information

Fabrication documents for the titanium helium vessel assembly, the bellows assembly are available. These documents are not required by FESHM 5031 but are made available at a centralized location. These documents include material certifications, leak check results, and other quality assurance documents. The documents are available online at the following location:

<http://ilc-dms.fnal.gov/Workgroups/CryomoduleDocumentation/AES004/other-fab-docs/>

Appendix B

Verification of ANSYS Results

Hoop Stress in Ti Cylinder

The hoop stress in the Ti cylinder, far from the ends or the flanges (which function like stiffening rings) can be calculated from

$$S = Pr/t$$

where: S = hoop stress
P = pressure
r = mean radius of shell
t = thickness of shell.

Substituting P = 30 psi, r = 4.62 in, t = 0.2 in gives P = 693 psi.

To check this number against the ANSYS results for 30 psi, a path was created in the ANSYS model, and the hoop stress plotted along the path. Figure B-1 shows the path; Figure B-2 shows the comparison of the ANSYS results with those calculated from the expression above. Agreement is extremely good over the region away from the ends, averaging less than 1%.

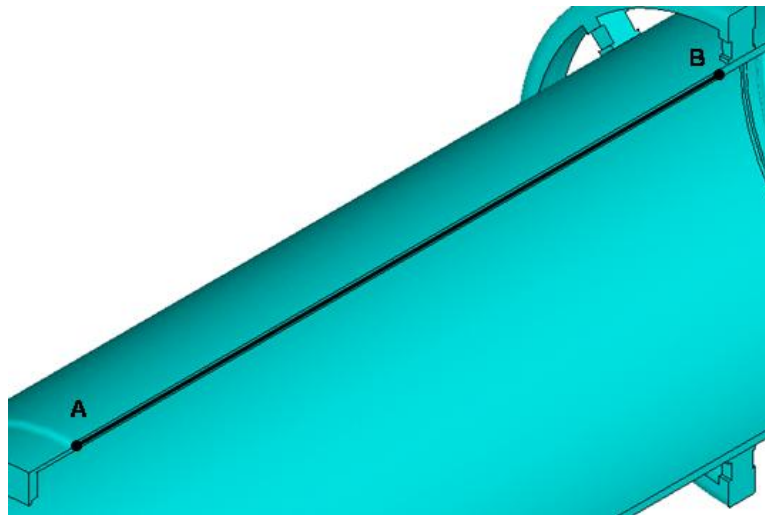
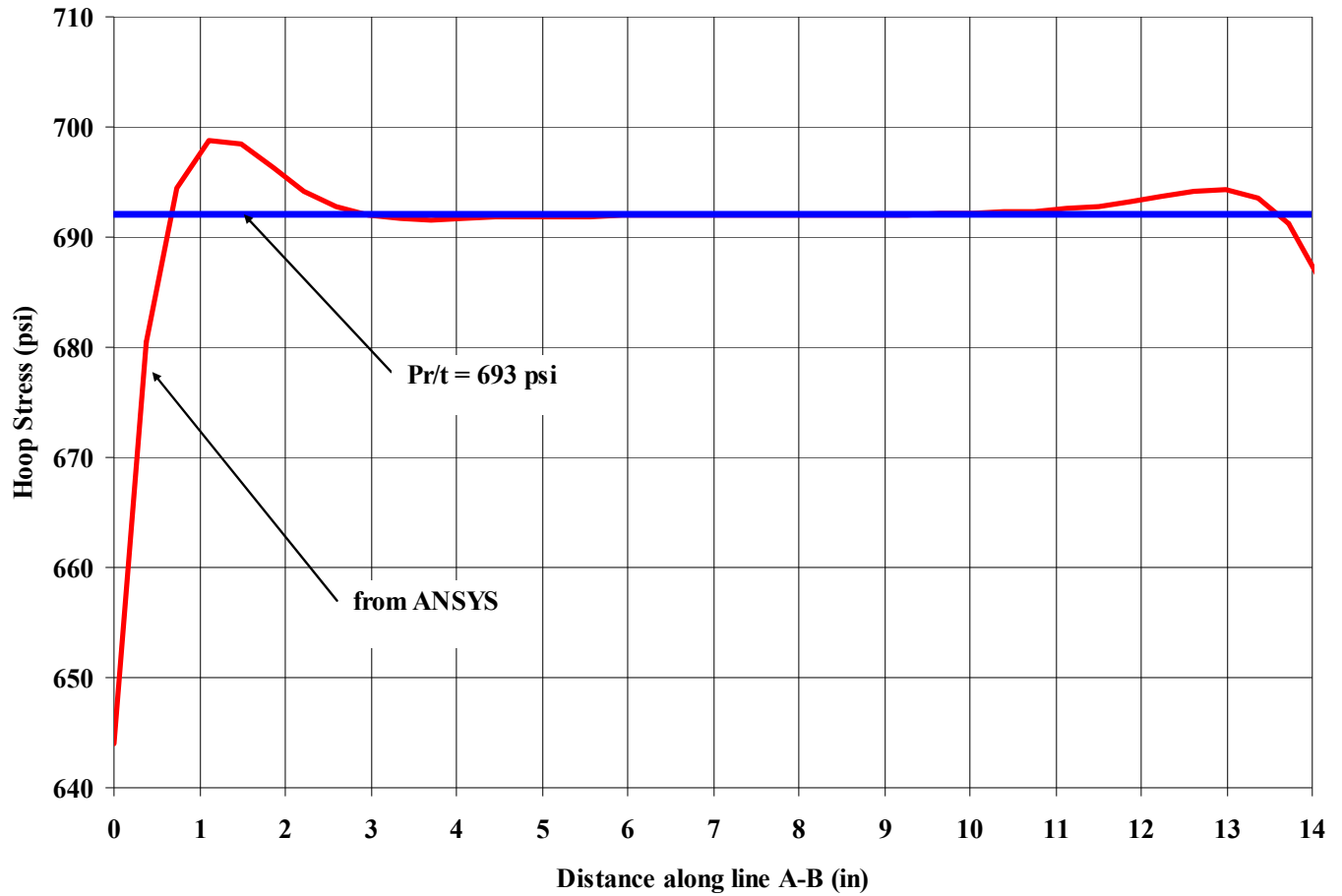


Figure B-1. Path for hoop stress plot

**Figure B-2 -
Hoop Stress in Ti Cylinder along line A-B for Pressure of 30 psi**



Buckling of Spherical Shell – Approximation to Cell Buckling

The ANSYS model predicted Nb cavity buckling would occur at a pressure of 12450 lbs. This number seems very large, so as a check a comparison was performed with the predicted collapse pressure for a thin sphere.⁽¹⁶⁾

From Ref. 4, Table 35, Case 22, the critical buckling pressure of a thin sphere is

$$q' = \frac{2Et^2}{r^2 \sqrt{3(1-\nu^2)}}$$

where: q' = critical pressure, psi

E = Young's modulus = 15.2e6 psi

r = radius of sphere = 4.14

ν = Poisson's ratio = 0.38

Substituting gives $q' = 13400$ psi. This compares well with the ANSYS linear buckling prediction.

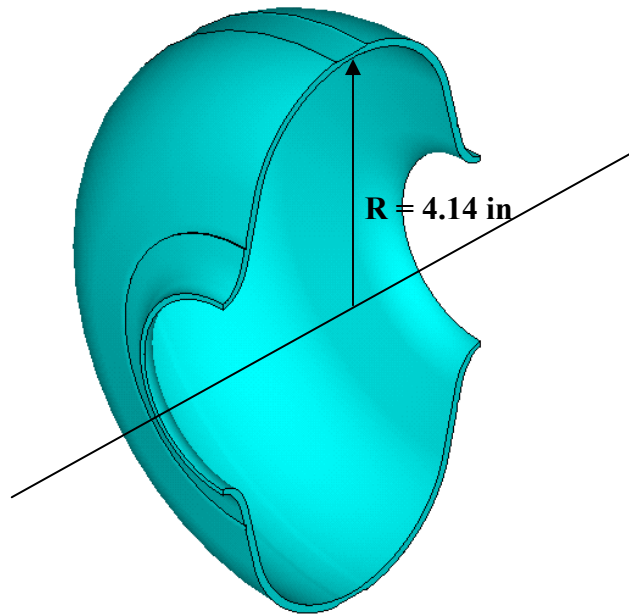


Figure B-3. Single cell – radius for spherical shell buckling calculation

Buckling of Ti Cylinder

The maximum allowable external pressure of the Ti cylinder was determined in section 7.0 of this report using the chart techniques of Div. 1. This calculation can be checked by doing an ANSYS linear buckling calculation on the length of shell used in the Div. 1 calculations, and applying the design factors for linear buckling given in Div. 2, Part 5, 5.4.1. This calculation is also useful for verifying that the buckling pressure of the conical head (calculated as 3880 psi in section 9.0 of this report) is higher than that of the cylinder.

The FE model, which includes the conical head, is shown in Figure B-4, along with the buckled shape. The analysis predicts collapse at 1380 psi. The Code calculation of section 7.0 gives an maximum allowable external pressure for this part of 345 psi. These numbers can be compared by noting that the factor $B = \sigma_{cr}/2$, where σ_{cr} is the hoop stress at which the cylinder buckles⁽¹⁷⁾. Substituting $\sigma_{cr} = P_{cr} r/t$, where P_{cr} is the critical buckling pressure, gives a theoretical buckling pressure for the cylinder of 1040 psi. This is reasonably close to the ANSYS value of 1380 psi.

This alternative calculation of Ti shell buckling pressure also verifies that it lies well below the calculated buckling pressure of the conical head, even when that head is unconstrained by the Nb cavity.

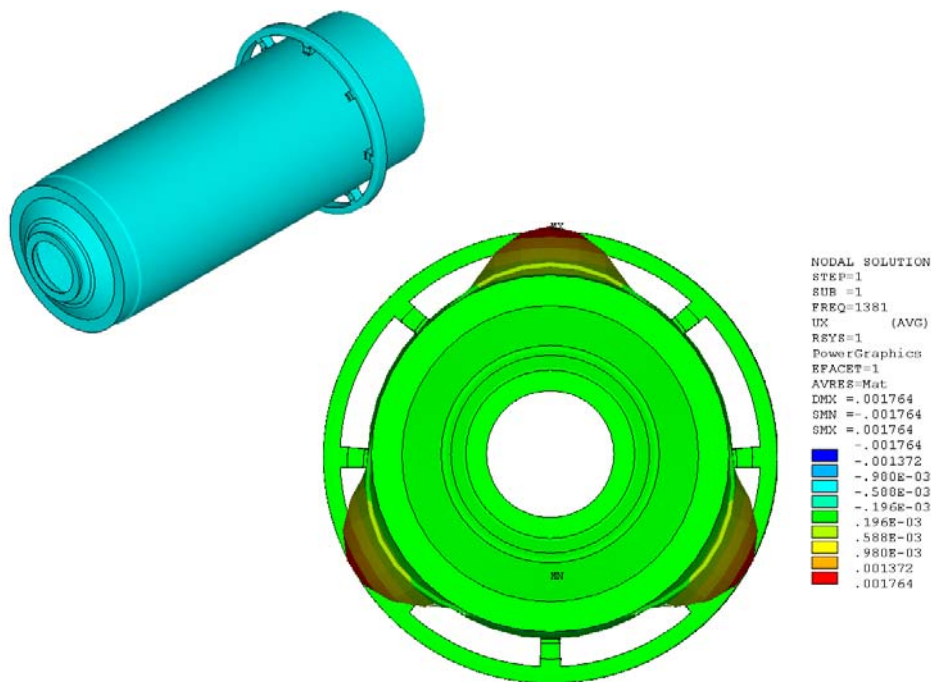


Figure B-4. ANSYS linear buckling of Ti cylindrical shell

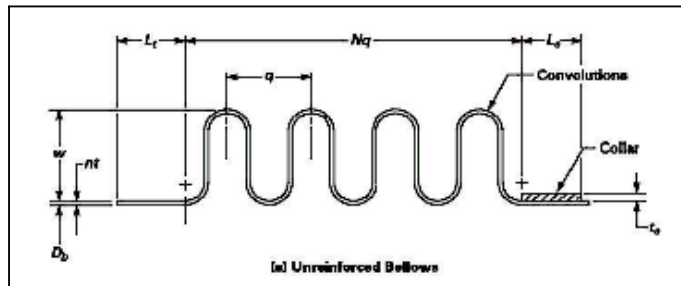
Appendix C

Fatigue Analysis of the Titanium Bellows

Here are the detailed calculations of the titanium bellows following the Code's Div. 1, Appendix 26 guidelines. Mathcad (version 14) was the software that was used.

Expansion Joint Analysis for the 1.3-GHz Helium Vessel's Titanium Bellows
29 June 2009

Following Appendix 26 of the ASME BPVC (2007), Section VIII, Division 1



Design Pressure (psi)	$P := 58$
Bellows Inside Diameter (in)	$D_b := 9.06$
Ply thickness (in)	$t := 0.012$
Number of Plies	$n := 1$
Bellows Tangent Length (in)	$L_t := 0.398$
Bellows Mean diameter (in)	$D_m := 9.390$
Modulus of elasticity (psi)	$E_b := 15200000$
Convolution height (in)	$w := 0.323$
Collar length (in)	$L_c := 0.170$
Collar thickness (in)	$t_c := 0.186$
Collar Modulus of elasticity (psi)	$E_c := 15200000$
Convolution Pitch (in)	$q := 0.341$
Kf coefficient 3.0 for as formed bellows 1.5 for annealed bellows	$K_f := 3.0$
Allowable stress of bellows (psi)	$S := 9680$
Allowable stress of collar (psi)	$S_c := 9680$
Weld joint efficiency of collar to bellows	$C_{wc} := 0.6$
Number of convolutions	$N := 3$

Bellows axial stiffness (N/micro-meter) $K_b := 0.228$

$$K_b := K_b \cdot \frac{2.2 \cdot 10^6 \cdot 2.54}{100}$$

$$K_b = 1.274 \times 10^4$$

Allowable yield stress (psi) $S_y := 40000$

Poisson's ratio of Ti G2 $\nu_b := 0.32$

Bellows live length (inch) $L := 1.024$

Maximum axial extension (mm) $x_{\text{positive}} := 2.1$

$$x_{\text{positive}} := \frac{x_{\text{positive}}}{25.4}$$

$$x_{\text{positive}} = 0.083$$

Maximum axial compression (mm) $x_{\text{negative}} := 0.33$

$$x_{\text{negative}} := \frac{x_{\text{negative}}}{25.4}$$

$$x_{\text{negative}} = 0.013$$

$$D_m := D_b + w + n \cdot t = 9.395$$

$$k := \min \left[\left(\frac{L t}{1.5 \sqrt{D_b \cdot t}} \right), 1.0 \right] = 0.805$$

$$t_p := \left(t \sqrt{\frac{D_b}{D_m}} \right) = 0.012$$

$$A := \left[\left(\frac{\pi - 2}{2} \right) q + 2w \right] n \cdot t_p = 9.906 \times 10^{-3}$$

$$D_c := D_b + 2n \cdot t + t_c = 9.27$$

$$c1 := \frac{q}{2 \cdot w} = 0.528$$

$$c2 := \frac{q}{2.2 \sqrt{D_m \cdot t_p}} = 0.466$$

$$I_{xx} := n \cdot t_p \cdot \left[\frac{(2 \cdot w - q)^3}{48} + 0.4 q \cdot (w - 0.2 q)^2 \right]$$

$$e_{eq} := \sqrt[3]{12 \cdot (1 - \nu_b^2) \cdot \frac{I_{xx}}{q}}$$

$$D_{eq} := D_b + w + 2 \cdot e_{eq}$$

Total axial movement per convolution (inch) $\Delta q := \frac{(x_{\text{positive}} + x_{\text{negative}})}{N}$

$$S1 := \frac{(Db + n \cdot t)^2 \cdot Lt \cdot Eb \cdot k \cdot P}{2[n \cdot t \cdot (Db + n \cdot t) \cdot Lt \cdot Eb + tc \cdot Dc \cdot Lc \cdot Ec \cdot k]} = 2.738 \times 10^3$$

$$S11 := \frac{Dc^2 \cdot P \cdot Lt \cdot Ec \cdot k}{2[n \cdot t \cdot (Db + n \cdot t) \cdot Lt \cdot Eb + tc \cdot Dc \cdot Lc \cdot Ec \cdot k]} = 2.859 \times 10^3$$

$$S2e := \frac{P \cdot [q \cdot Dm + Lt \cdot (Db + n \cdot t)]}{2(A + n \cdot tp \cdot Lt + tc \cdot Lc)} = 4.276 \times 10^3$$

$$S2i := \frac{P \cdot q \cdot Dm}{2 \cdot A} = 9.379 \times 10^3$$

$$S3 := \frac{P \cdot w}{2n \cdot tp} = 794.884$$

$$S4 := \left(\frac{w}{tp} \right)^2 \cdot \frac{P \cdot cp}{2n} = 1.38 \times 10^4$$

$$Psc := 0.34 \frac{\pi \cdot Kb}{N \cdot q}$$

$$\delta := \frac{S4}{3 \cdot S2i}$$

$$\alpha := 1 + 2 \cdot \delta^2 + \sqrt{1 - 2 \cdot \delta^2 + 4 \cdot \delta^4}$$

$$Sy_{eff} := 2.3 \cdot Sy$$

$$Psi := (\pi - 2) \cdot \frac{A \cdot Sy_{eff}}{Dm \cdot q \cdot \sqrt{\alpha}}$$

$$\beta0 := 1.005 \quad \beta1 := 1.9 \quad \beta2 := -3.4 \quad \beta3 := 7 \quad \beta4 := -8.4 \quad \beta5 := 3.37$$

$$Cf := \beta0 + \beta1 \cdot cl + \beta2 \cdot cl^2 + \beta3 \cdot cl^3 + \beta4 \cdot cl^4 + \beta5 \cdot cl^5$$

$$\gamma0 := 1.0 \quad \gamma1 := 1.7 \quad \gamma2 := -1.14 \quad \gamma3 := 1.75 \quad \gamma4 := 1.75 \quad \gamma5 := 2.1$$

$$Cd := \gamma0 + \gamma1 \cdot cl + \gamma2 \cdot cl^2 + \gamma3 \cdot cl^3 + \gamma4 \cdot cl^4 + \gamma5 \cdot cl^5$$

$$S5 := \frac{1}{2} \cdot \frac{Eb \cdot tp^2}{w^3 \cdot Cf} \cdot \Delta q$$

$$S6 := \frac{5}{3} \cdot \frac{Eb \cdot tp}{w^2 \cdot Cd} \cdot \Delta q$$

$$St := 0.7 \cdot (S3 + S4) + (S5 + S6)$$

Calculating the buckling pressure for the bellows as an equivalent cylinder

$$\frac{D_{eq}}{e_{eq}} = 63.704$$

$$\frac{L}{D_{eq}} = 0.106$$

$$A_{factor} := 0.055$$

$$B_{factor} := 19500$$

$$Pa := \frac{4 \cdot B_{factor}}{3 \cdot \left(\frac{D_{eq}}{e_{eq}} \right)}$$

circumferential membrane stress in bellows tangent (psi)	$S1 = 2.738 \times 10^3$
circumferential membrane stress in collar (psi)	$S11 = 2.859 \times 10^3$
circumferential membrane stress in bellows (psi) (for end convolution)	$S2e = 4.276 \times 10^3$
circumferential membrane stress in bellows (psi) (for intermediate convolution)	$S2i = 9.379 \times 10^3$
meridional membrane stress in bellow (psi)	$S3 = 794.884$
meridional bending stress in bellows (psi)	$S4 = 1.38 \times 10^4$
allowable internal pressure to avoid column instability (psi)	$Psc = 1.33 \times 10^4$
allowable internal pressure based on in-plane instability (psi)	$Psi = 211.979$
allowable external pressure based on instability (psi)	$Pa = 408.137$
meridional membrane stress (psi)	$S5 = 633.681$
meridional bending stress (psi)	$S6 = 4.432 \times 10^4$
total stress range due to cyclic displacement (psi)	$St = 5.516 \times 10^4$

ACCEPTANCE CRITERIA

$$S1 = 2.738 \times 10^3$$

$$S2e = 4.276 \times 10^3$$

$$S2i = 9.379 \times 10^3$$

$$S11 = 2.859 \times 10^3$$

$$S3 + S4 = 1.459 \times 10^4$$

$$P = 58$$

smaller than ?

$$S = 9.68 \times 10^3$$

$$Cwc \cdot Sc = 5.808 \times 10^3$$

$$Kf \cdot S = 2.904 \times 10^4$$

$$Psc = 1.33 \times 10^4$$

$$Psi = 211.979$$

$$Pa = 408.137$$

Appendix D – Pressure Test Results



Date: November 5, 2009

Pressure Testing Permit*

Type of Test: ☐ Hydrostatic ☒ Pneumatic

Test Pressure 32 psig Maximum Allowable Working Pressure 29 psid

Items to be Tested

AES-004 Cavity Helium Vessel, see figure 1.

Note1: Cavity beam-line is backfilled to atmospheric pressure with boiled off argon gas, outside of the helium vessel is at atmospheric pressure in air

Note 2: The mini Conflat flange at the bottom of the helium vessel will be used to backfill the helium vessel with boiled off nitrogen gas during the test. The Conflat flange on the 2-phase pipe of the helium vessel will be blanked off during the test.

Note 3: The blade tuner is installed to the cavity. It is imperative that the safety rods are engaged between the tuner and the cavity tuner support rings on the helium vessel before the pressure test. This will ensure that the load on the piezo stack will not exceed the allowable limit. The tuner assembly also ensures that the titanium bellows in the middle of the helium vessel is supported during the pressure test.

Note 4: The pressure test will also include an RF frequency measurement before, during, and after pressurization

Location of Test CAF-MP9 Date and Time 11/5/09

Hazards Involved

Contact with high velocity jet of test gas.

Safety Precautions Taken

System designed, fabricated, and inspected per ASME Boiler & Pressure Vessels code. Test will be conducted by trained personnel as described in ASME code. Access to test area will be limited only to those involved in the test during pressurization.

Special Conditions or Requirements

Operating pressure = 29 PSI, test pressure = 1.1*OP = 32 PSI, pneumatic per ASME code.

1. First pressurize to 2-5PSI and check for leaks.
2. Repeat at 16PSI.
3. Increase pressure gradually to the test pressure for 5minutes.
4. Reduce pressure to design pressure.
5. Close valve on regulator.
6. Maintain test for at least 10min. without loss of pressure.

Qualified Person and Test Coordinator Tug Arkan, Mayling Wong

Dept/Date TD/SRF Department

Division/Section Safety Officer

Dept/Date

Rich Ruthe

TD/ESH

Results

Pressure held @ 29 psig without dropping.

Witness

Richard Ruthe
Rich Ruthe or designee

Dept/Date

TD SUPESH / 11/9/09

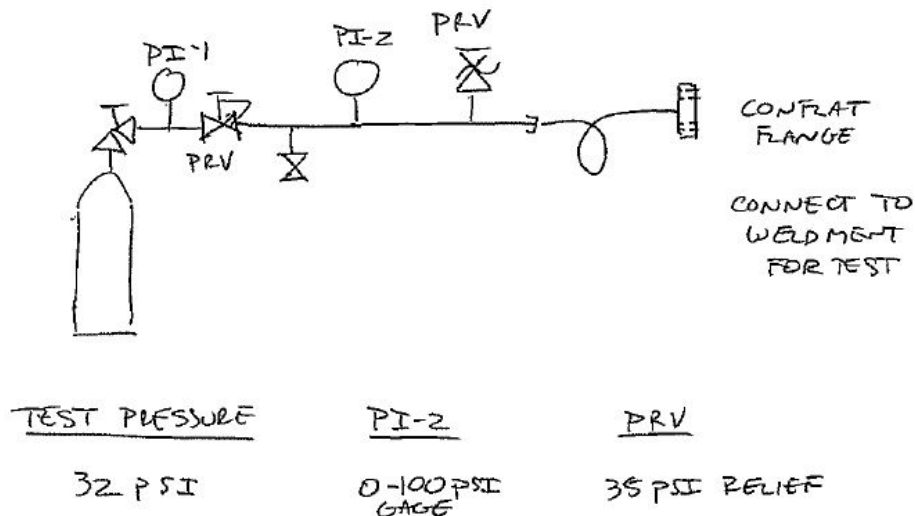
Detail for the pressure test steps.

The table below shows the pressure levels for each pause and what should be done at that pressure. Total time for the test, not including setup and tear-down time, will be about 20 minutes.

Pressure (psig) (psig equals differential pressure for this test)	Dwell time (minutes)	Activity at pressure
0	--	Baseline RF test
8.0	As needed	Snoop line fitting, RF check
16.0	As needed	Snoop line fitting, RF check
19.0	~1	
24.0	As needed	RF check
28.0	~1	
30.0	~1	
32	5	Peak test pressure of 1.1 x MAWP
29.0	10*	Test pressure hold point*, RF check
24.0	As needed	RF check
16.0	As needed	Visual inspection, RF check
8.0	As needed	RF check
0	--	RF check

*The pressure hold point of 29 psig is the MAWP. Dwell time is set long enough to assure us that pressure is not dropping.

Test Setup



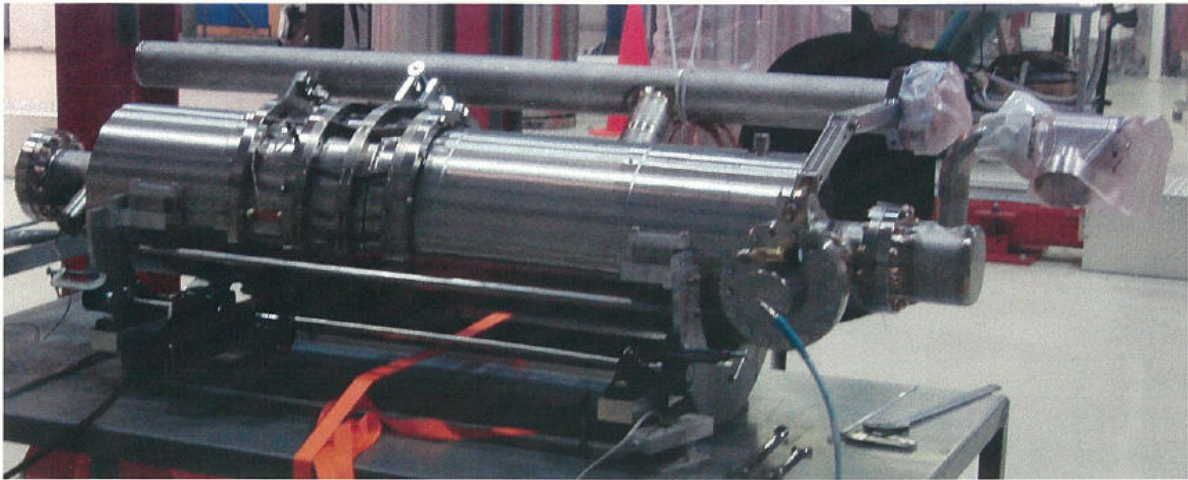


Figure 1: AES-004 assembled with the Blade tuner

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